

FIG. 1A

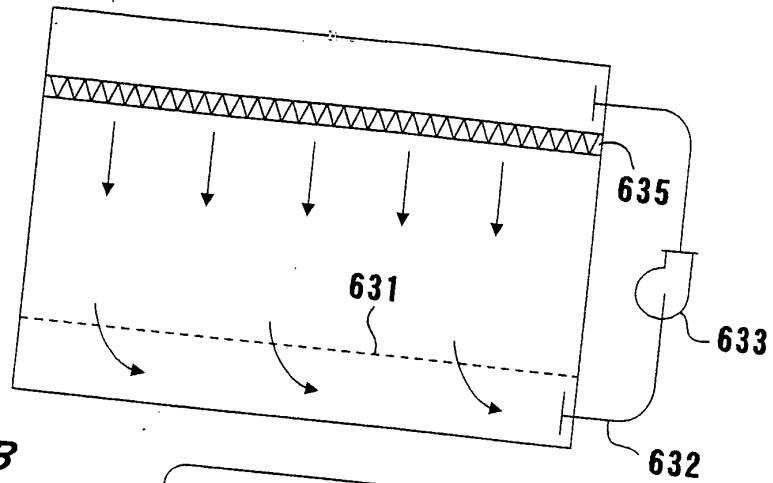


FIG. 1B

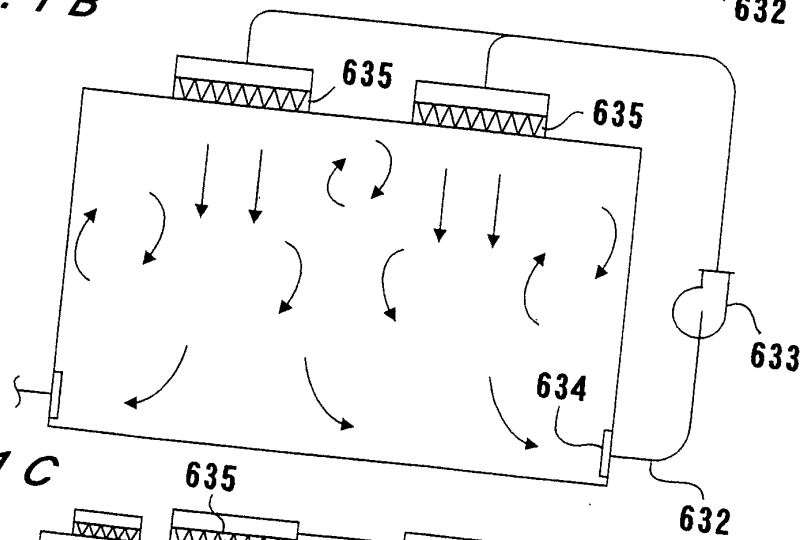
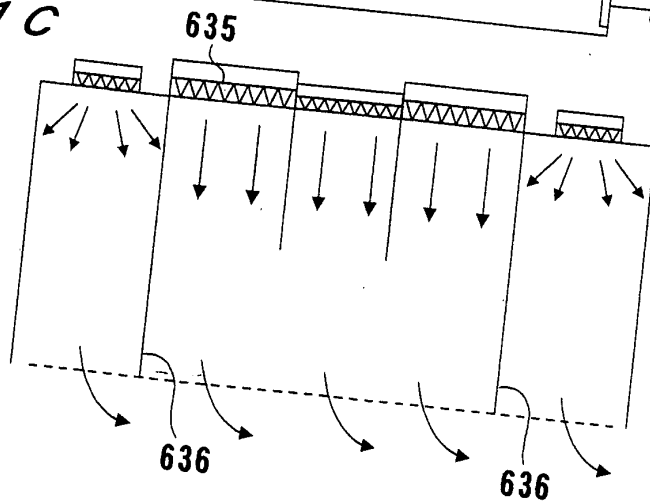


FIG. 1C



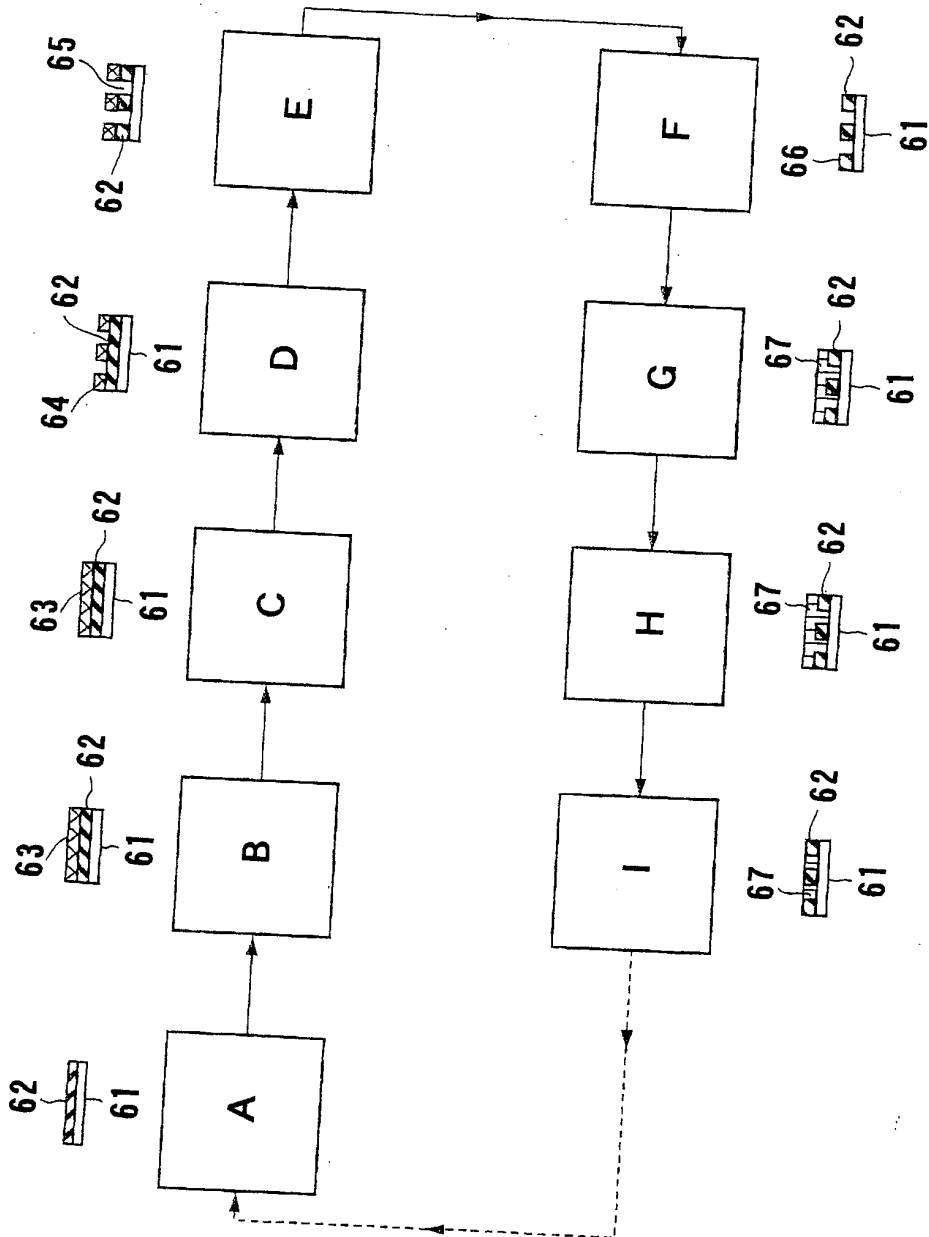
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FIG. 2

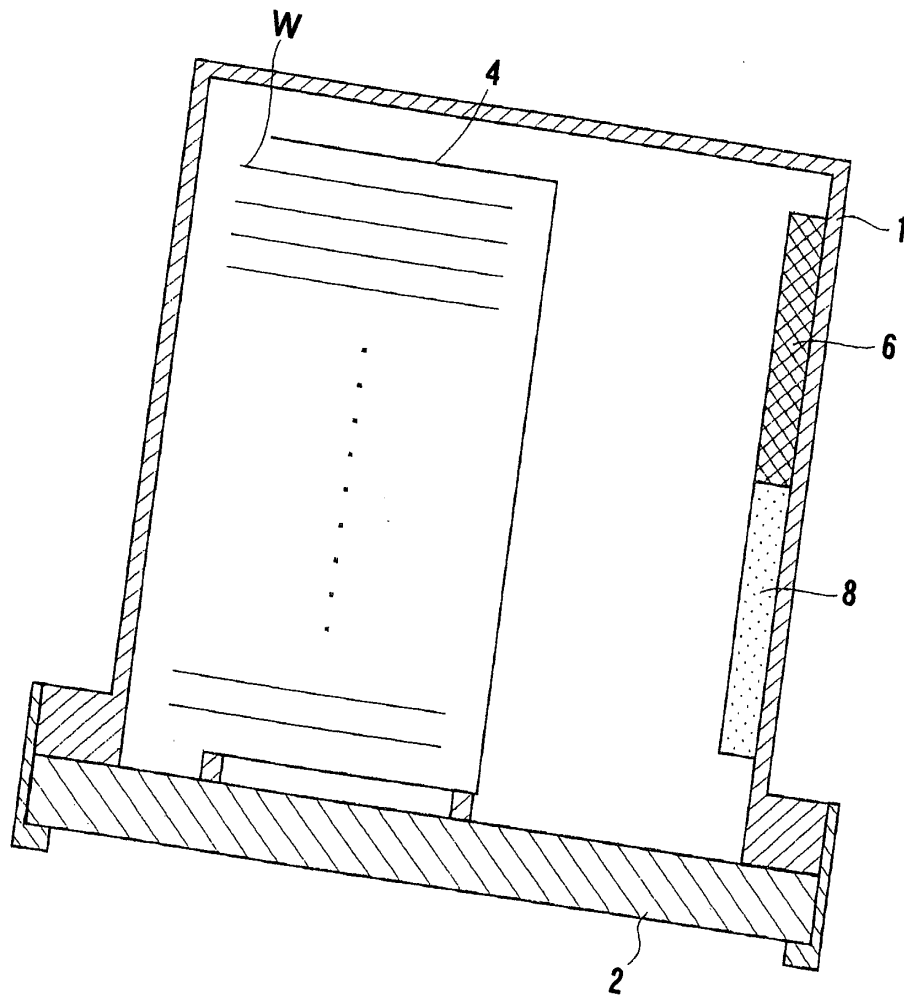
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FIG. 2



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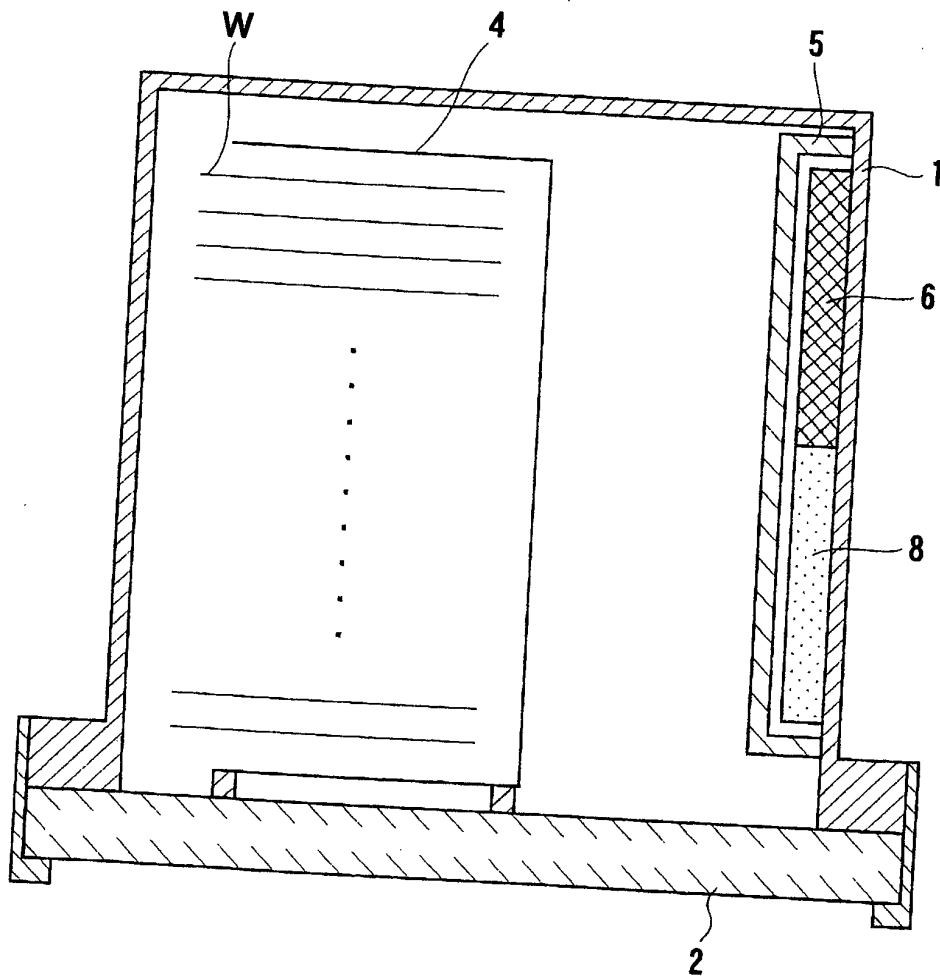
FIG. 3



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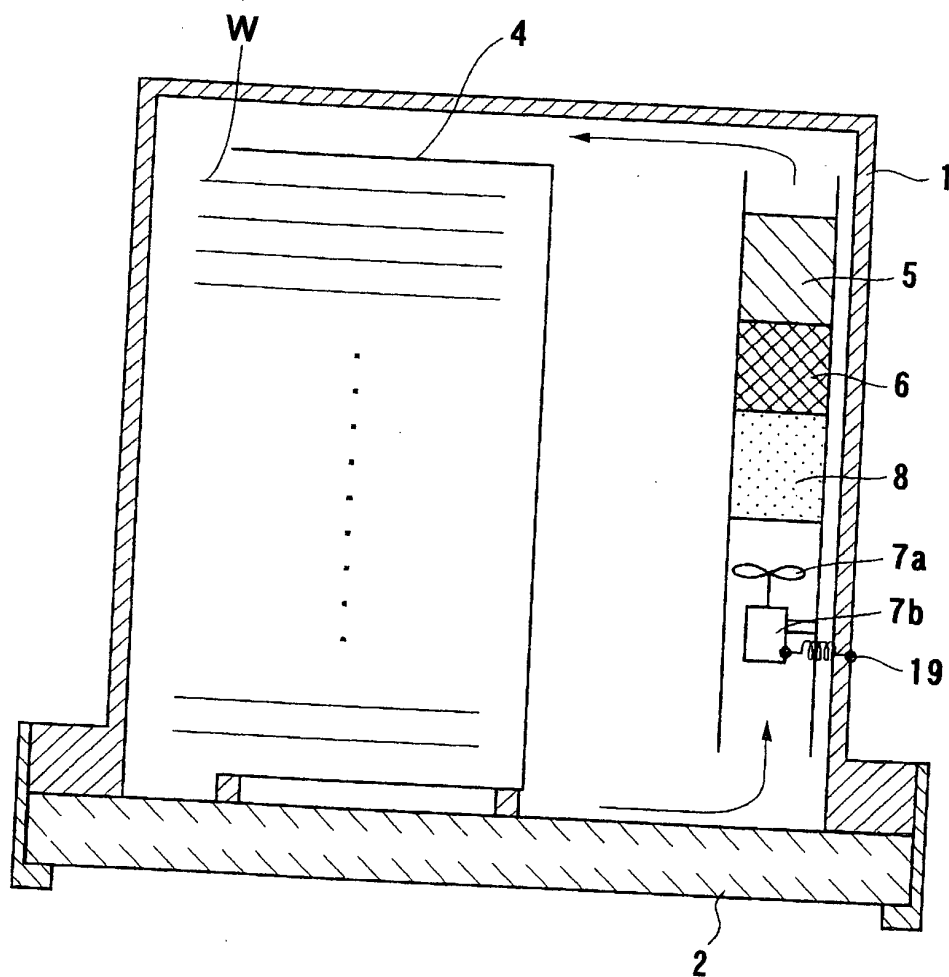
FIG. 4



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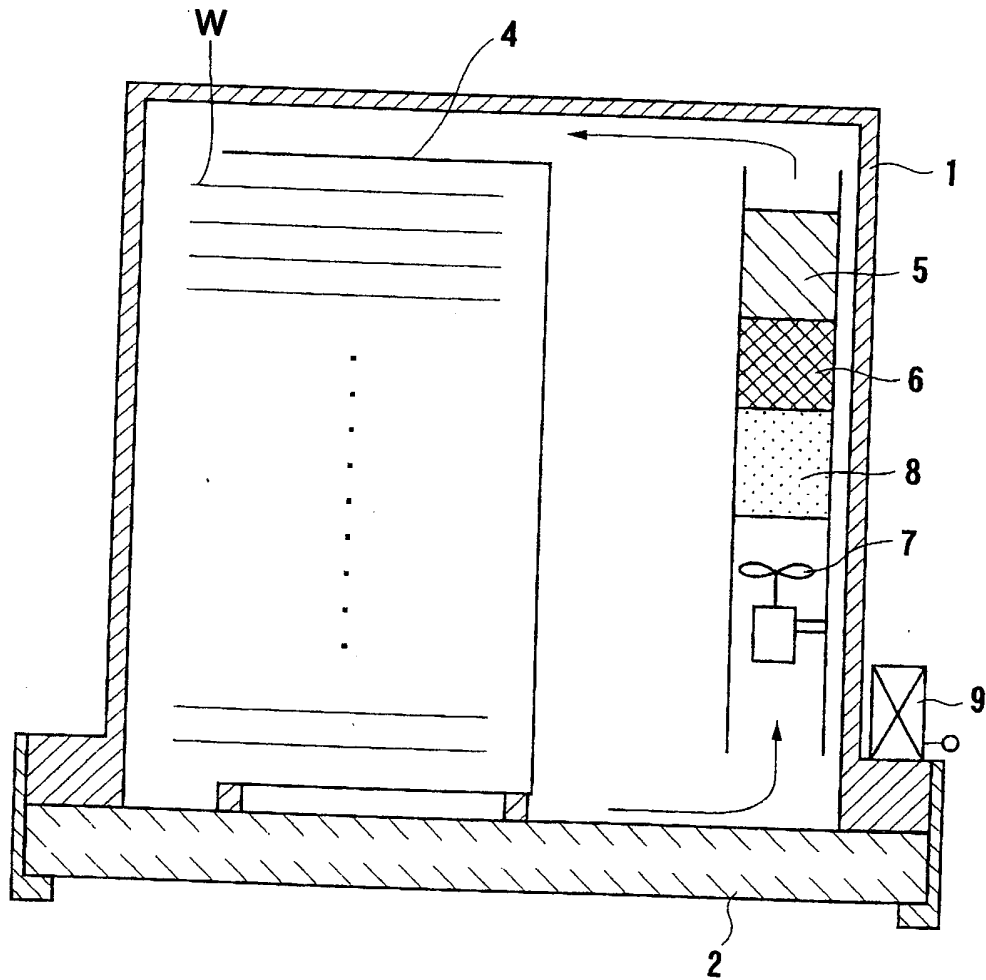
FIG. 5



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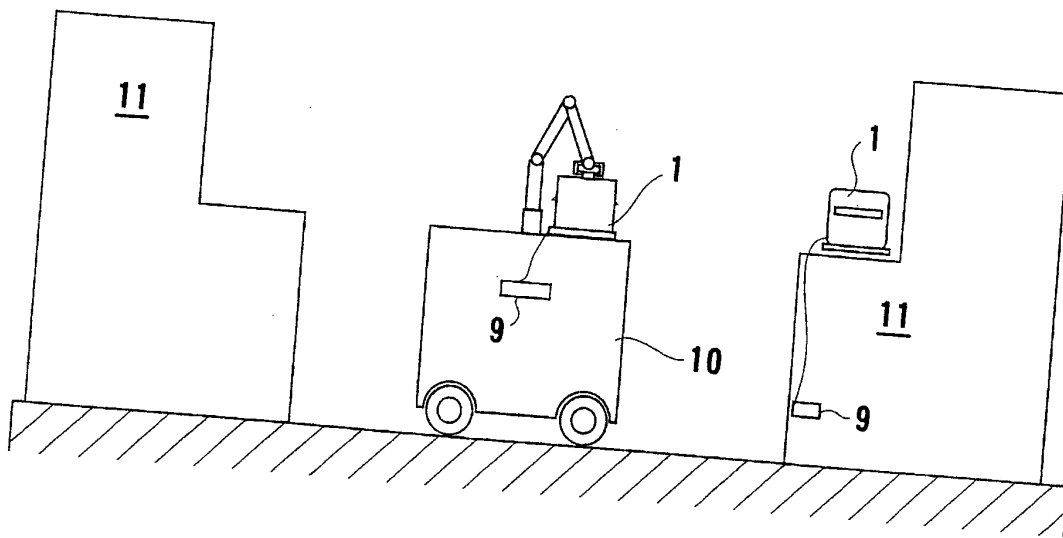
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FIG. 6



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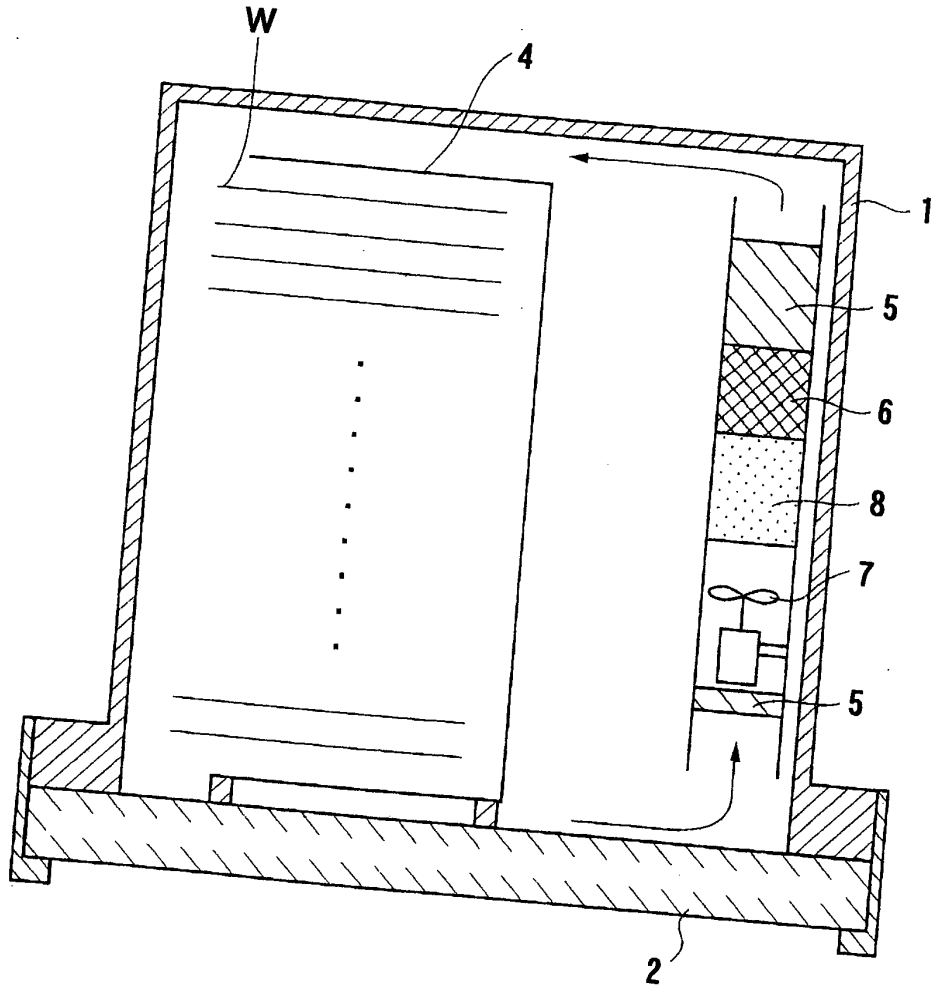
**FIG. 7**



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**FIG. 8**

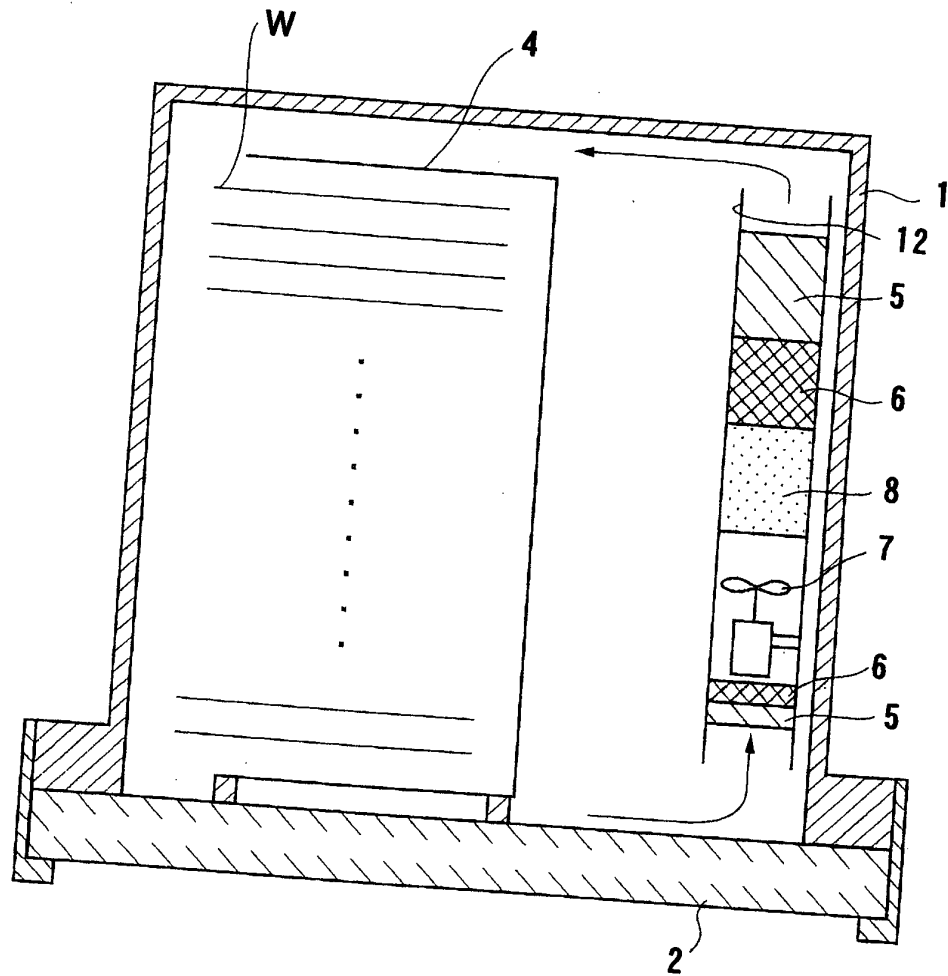


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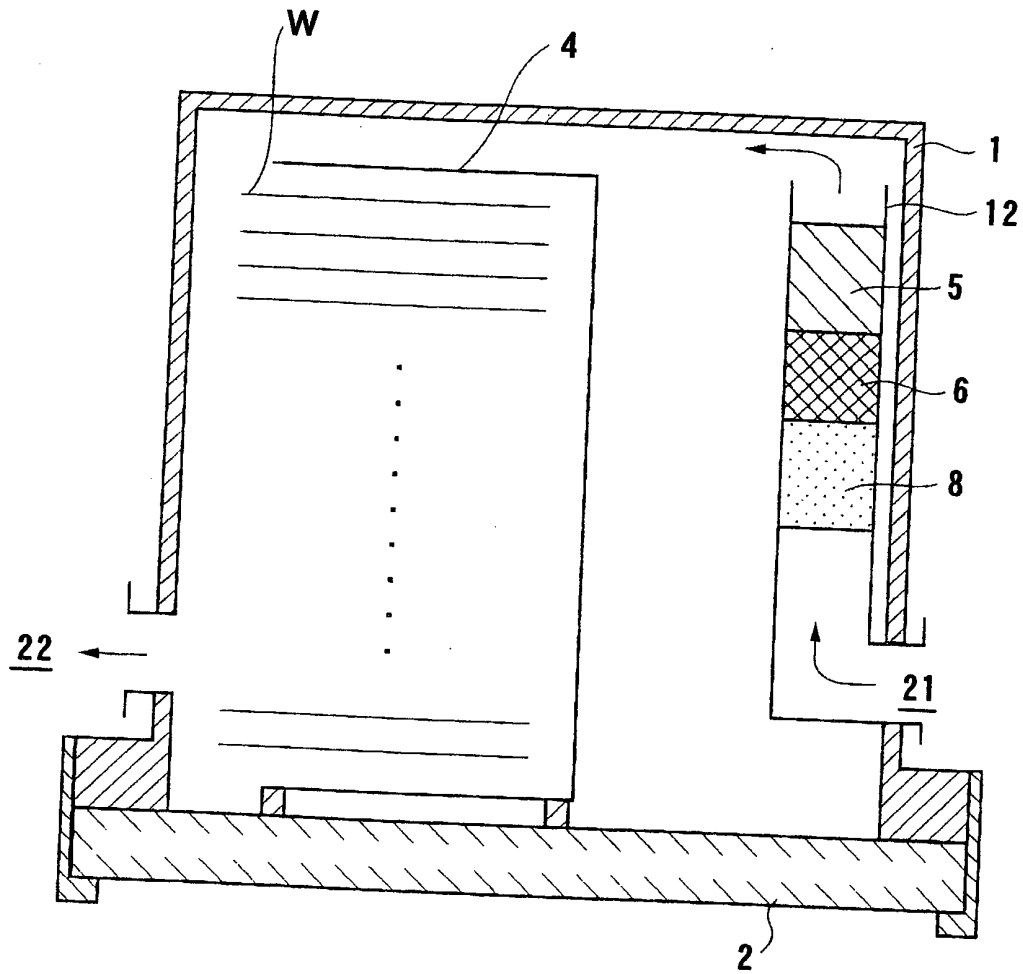
FIG. 9



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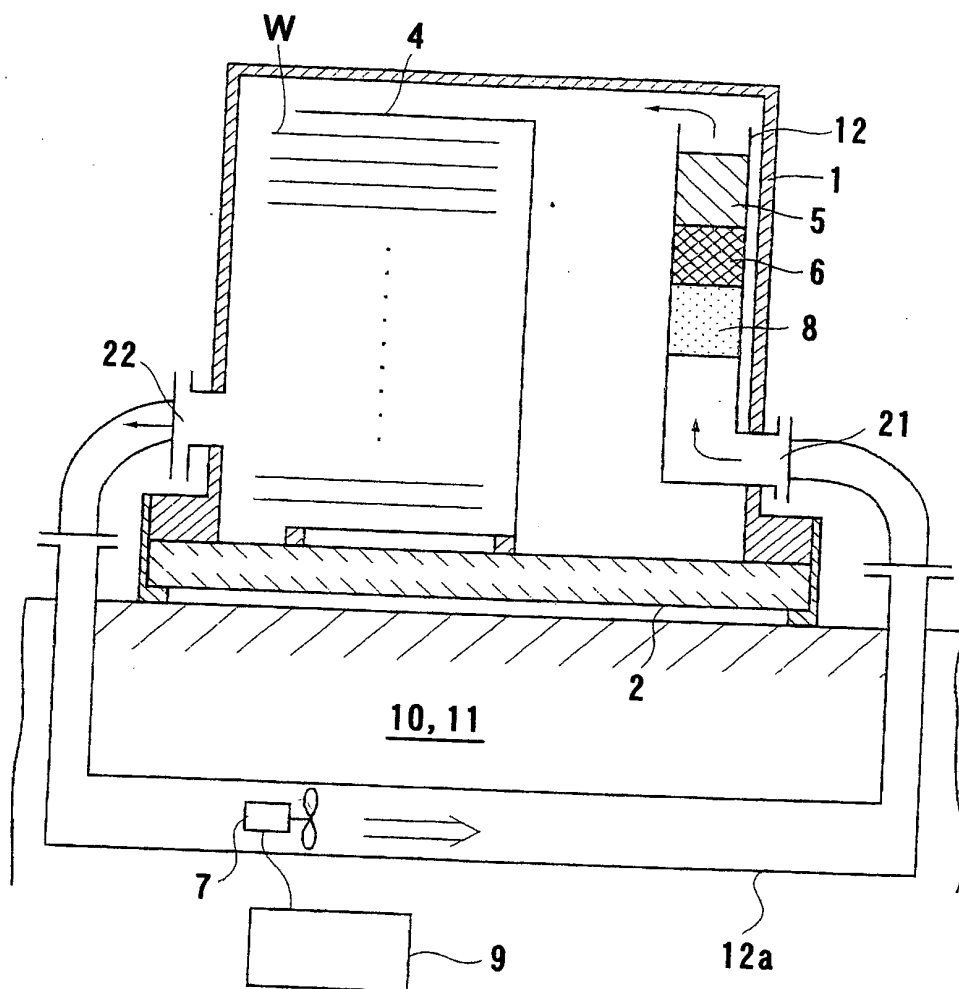
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FIG. 10



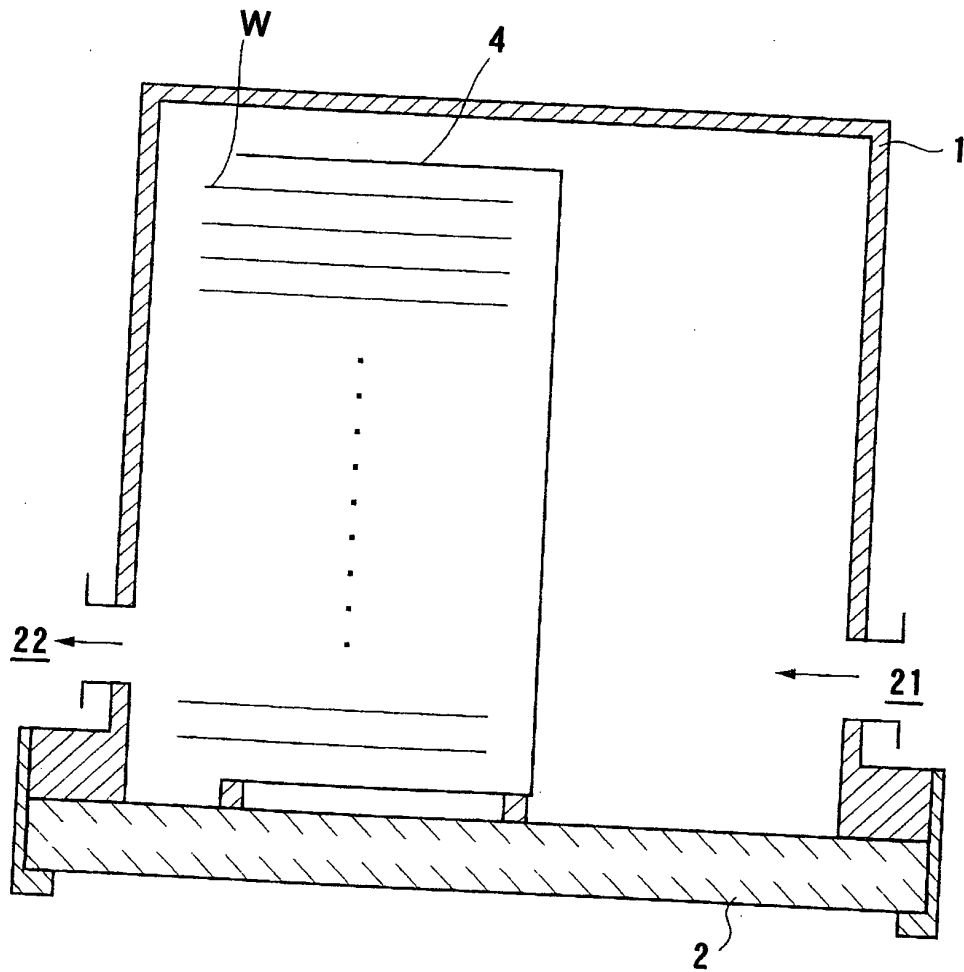
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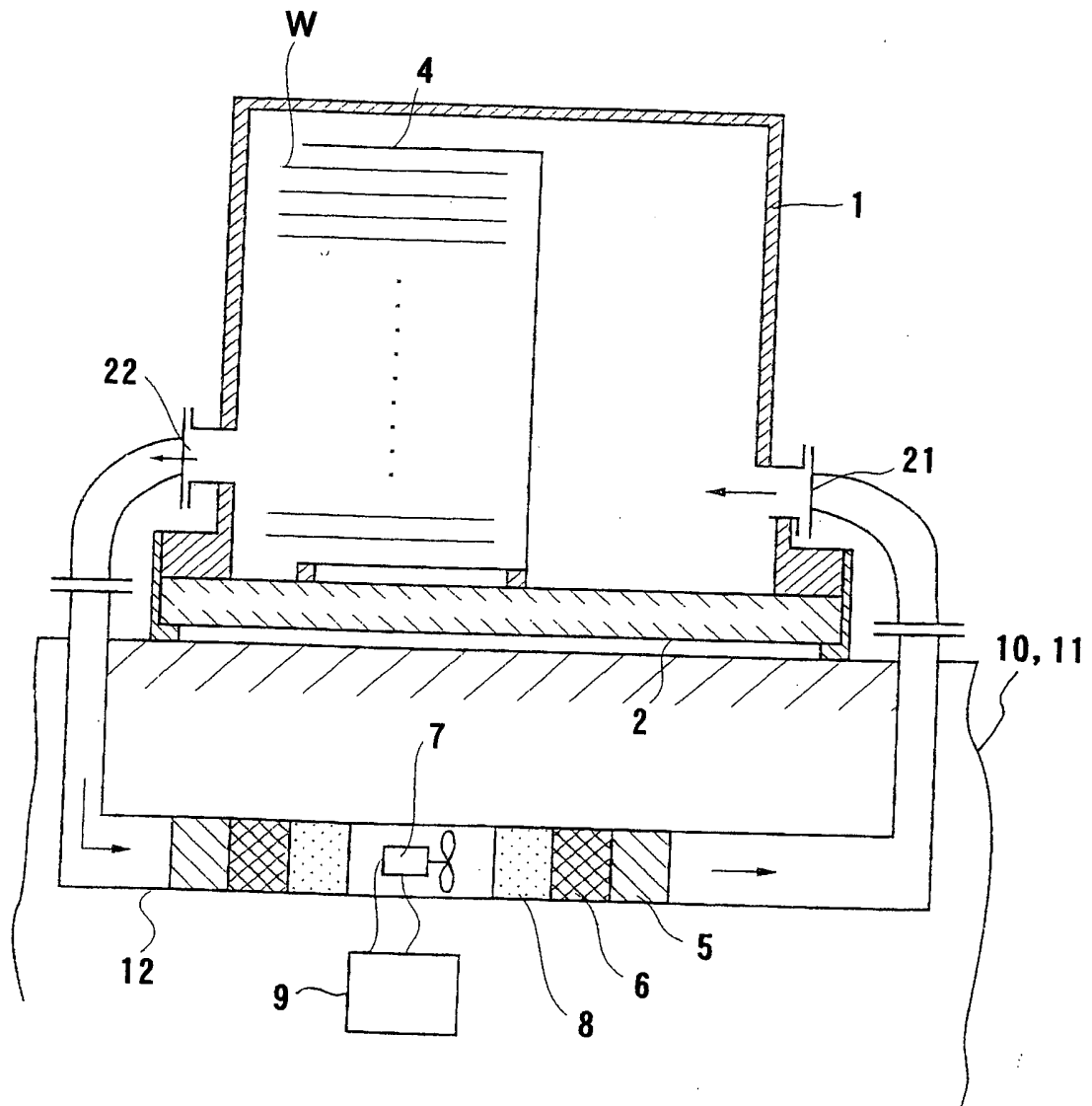
FIG. 12



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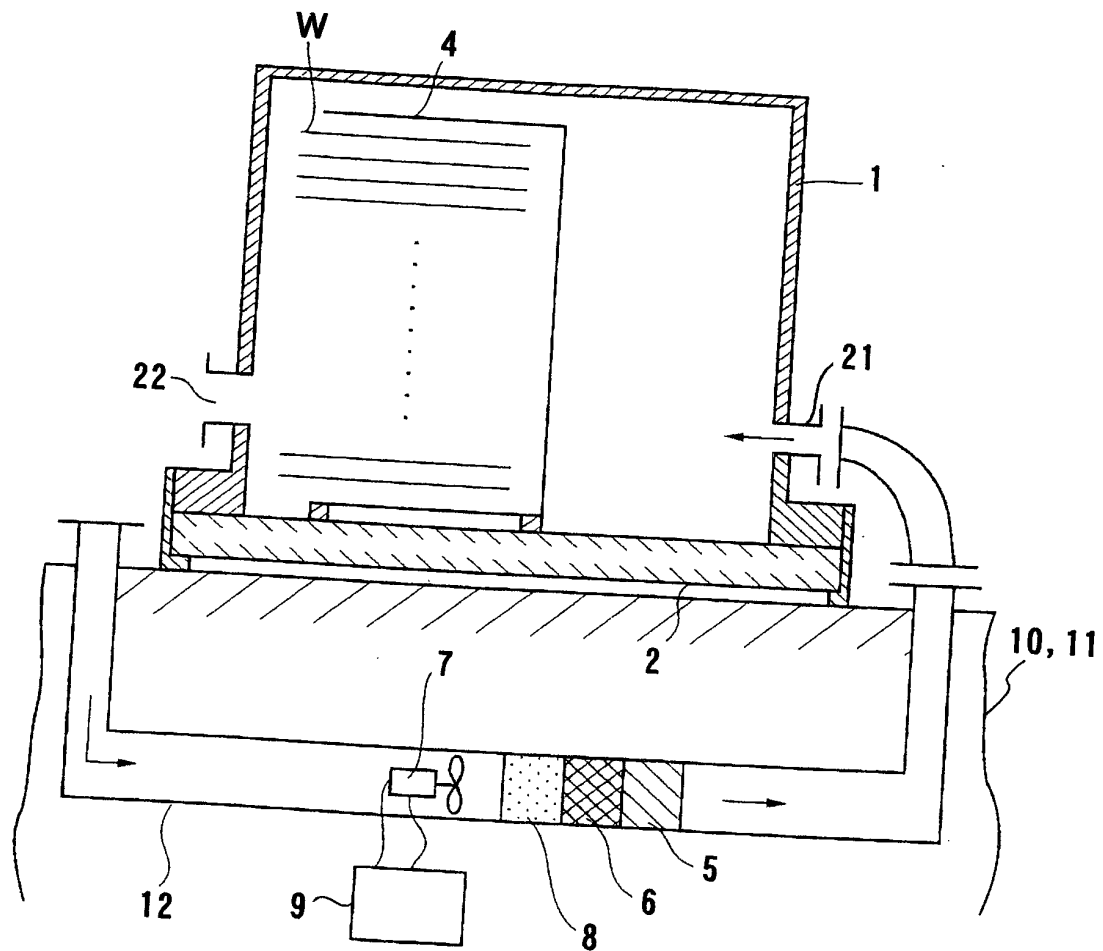
FIG. 13



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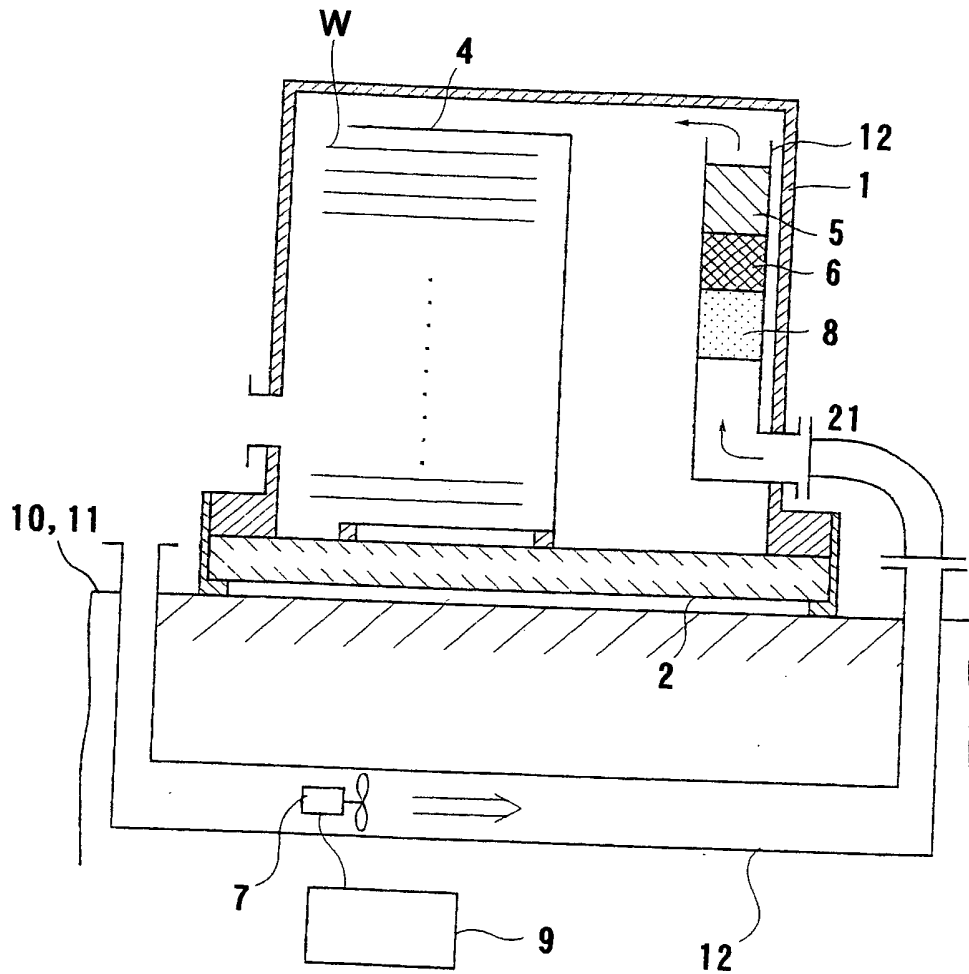
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FIG. 14



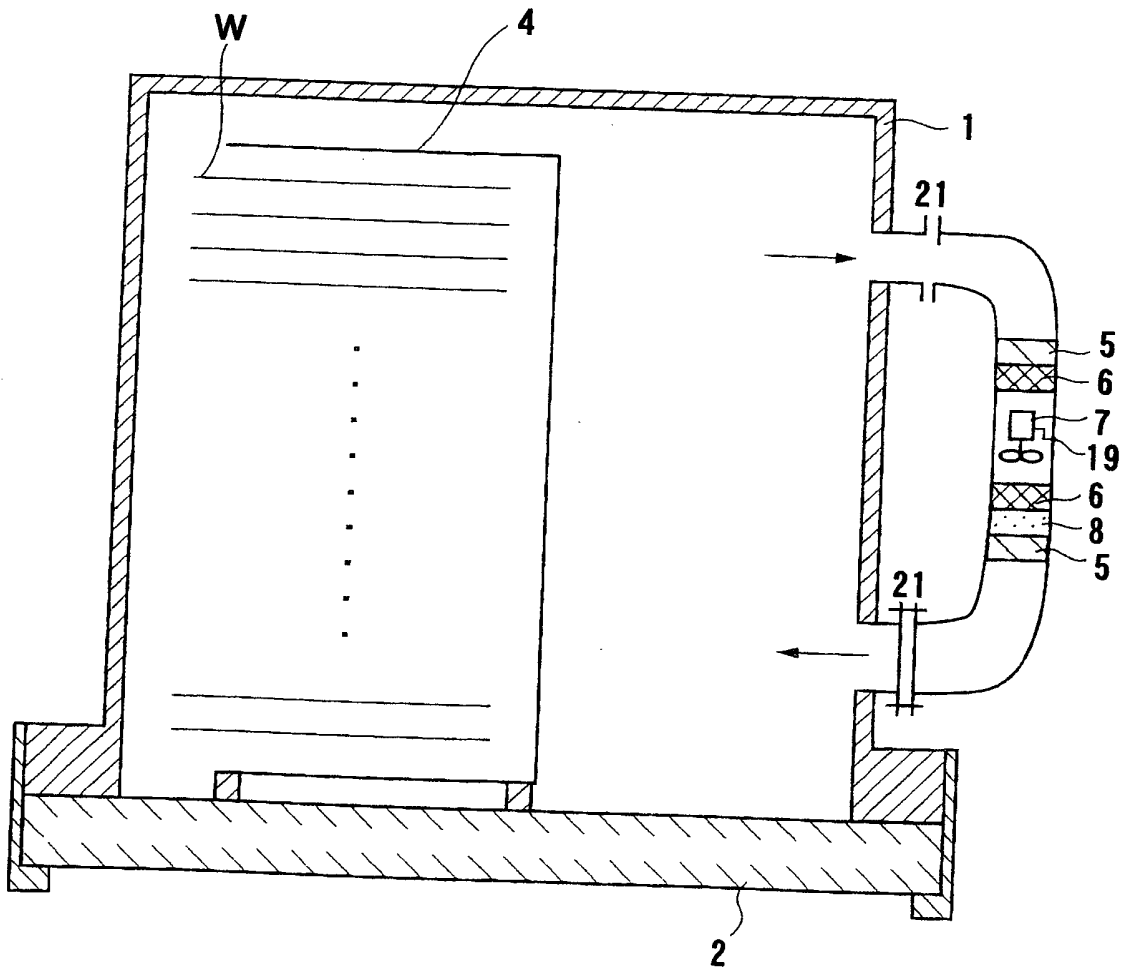
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FIG. 15



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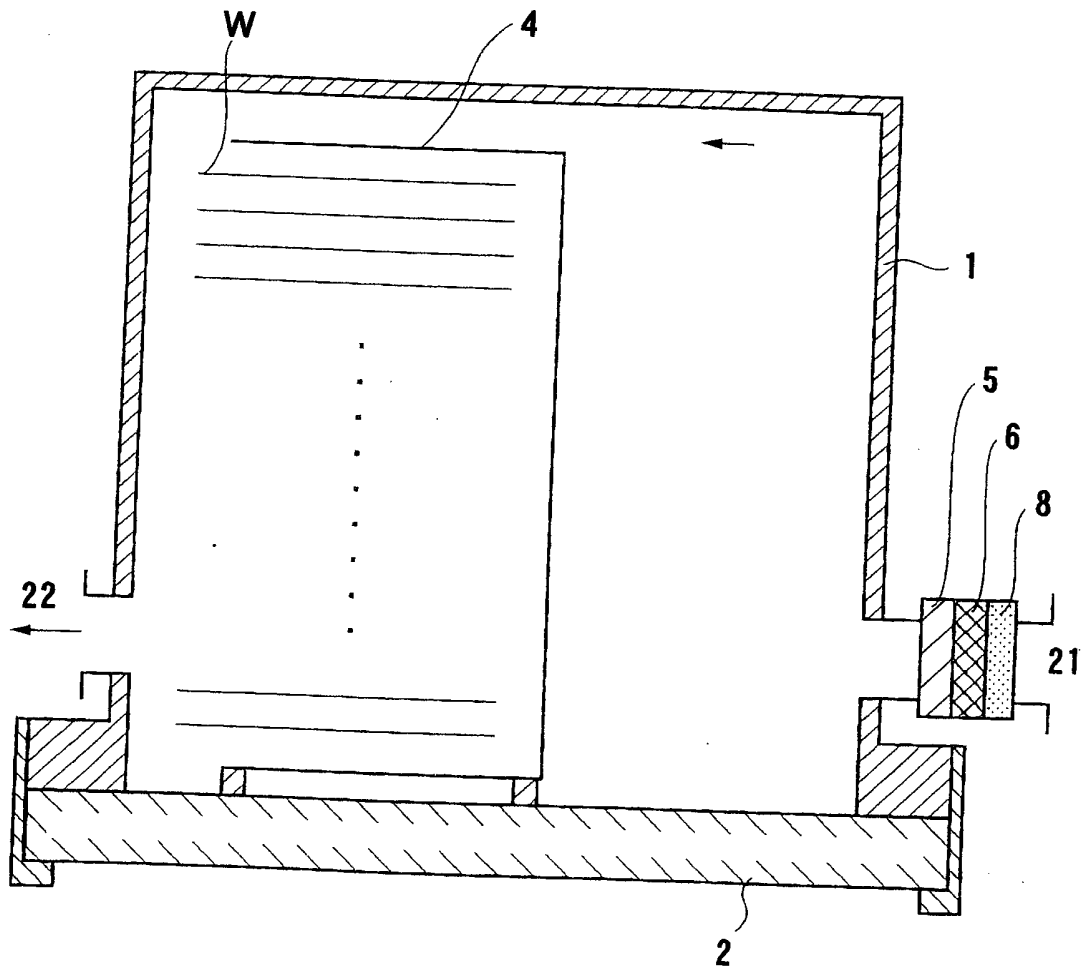
FIG. 16



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FIG. 17



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***FIG. 18***

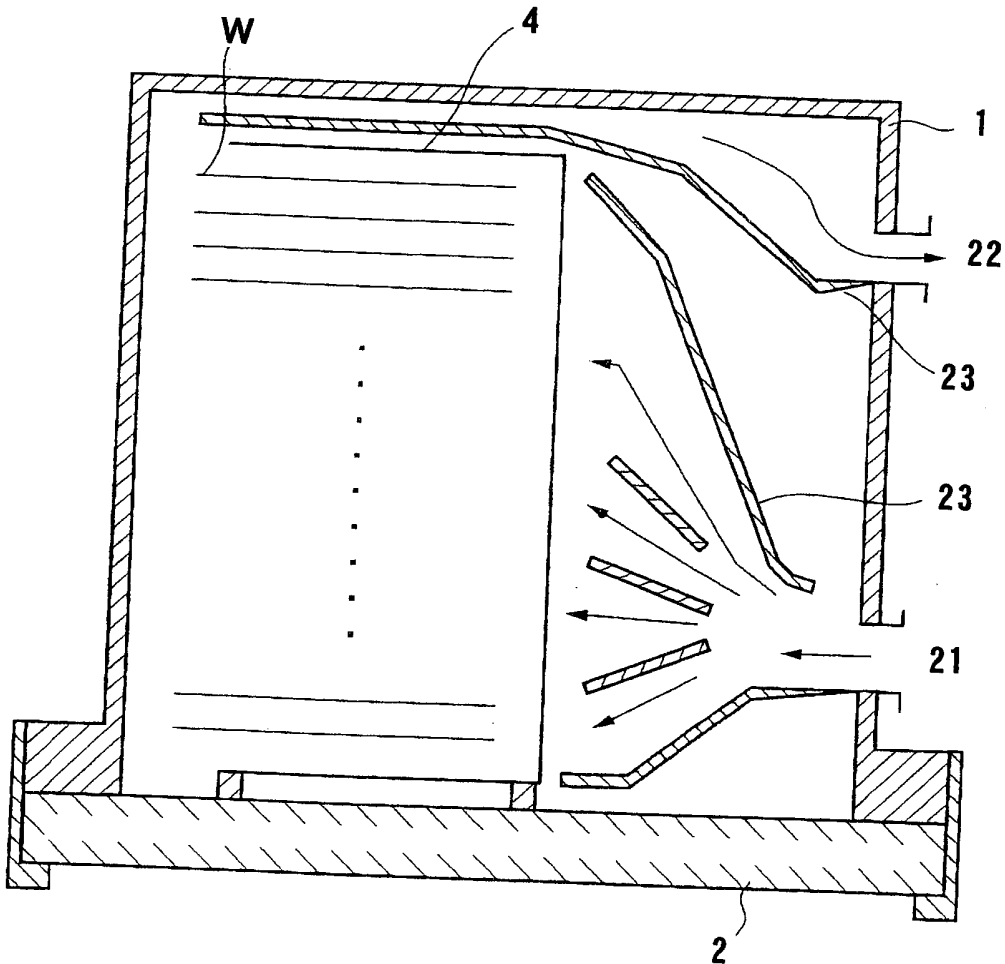
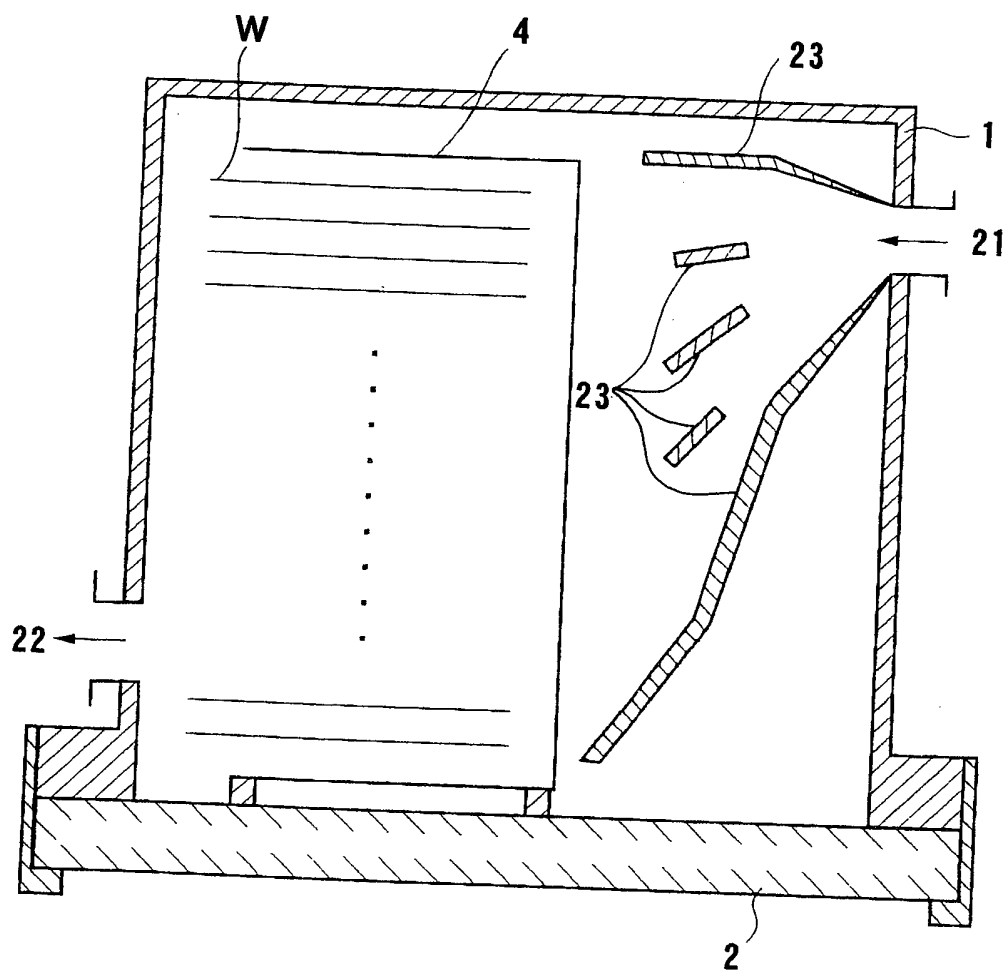


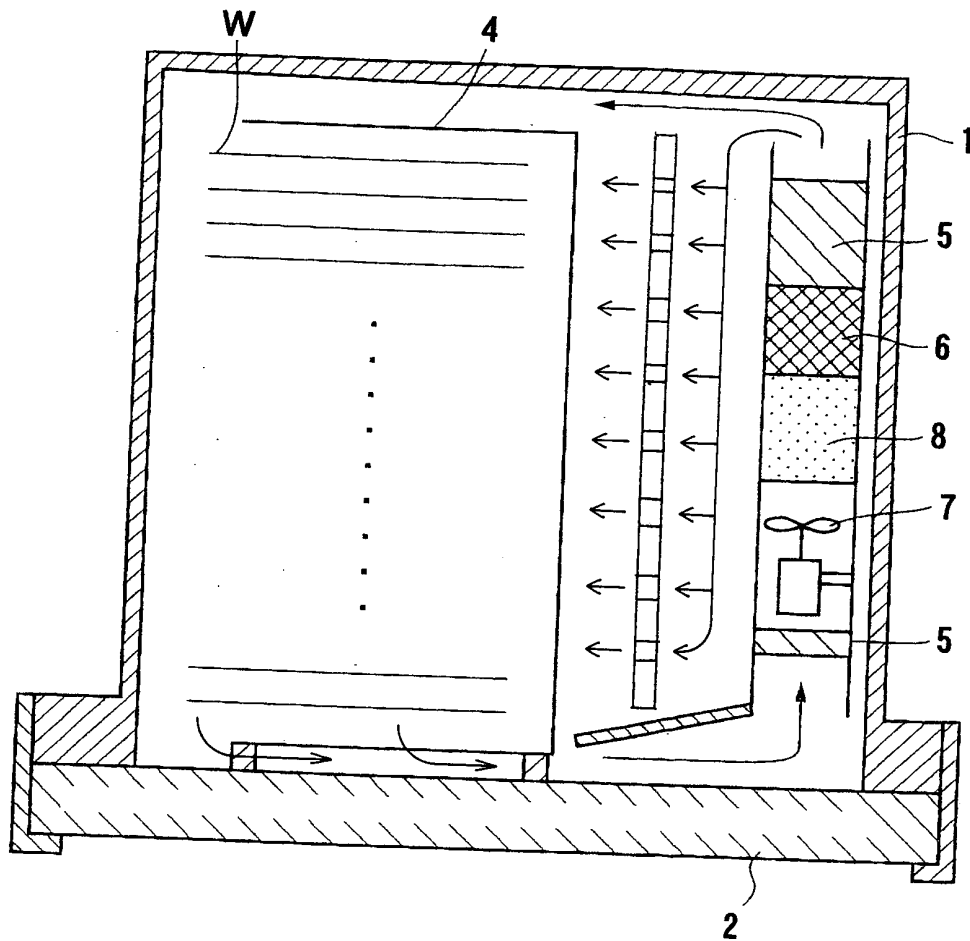
Figure 1. Schematic diagram of the experimental setup. The subject is seated in a chair, viewing the target through a video camera. The target is a vertical rod with a horizontal bar at the end. The subject's hand is positioned at the base of the rod. The distance between the subject's hand and the target is 100 cm. The target is 10 cm in diameter. The subject is instructed to move the hand to the target and hold it there for 10 seconds. The video camera records the hand position and the target position. The video is then analyzed to determine the hand position at the end of the movement. The video is also analyzed to determine the time taken for the hand to reach the target. The video is also analyzed to determine the time taken for the hand to hold the target for 10 seconds. The video is also analyzed to determine the time taken for the hand to move back to the starting position. The video is also analyzed to determine the time taken for the hand to move back to the starting position. The video is also analyzed to determine the time taken for the hand to move back to the starting position.

***FIG. 19***



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FIG. 20



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FIG. 21A

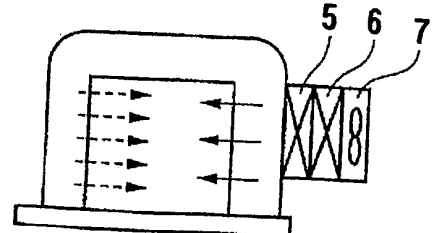
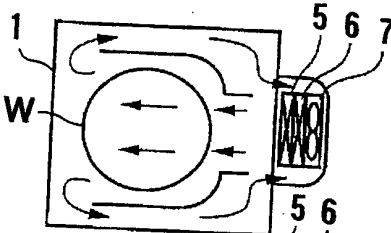


FIG. 21B

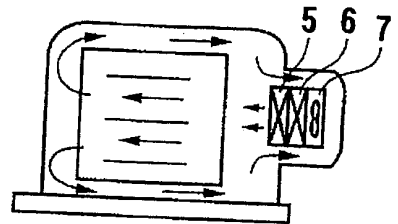
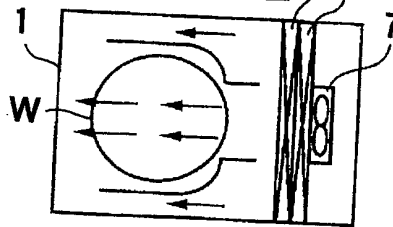


FIG. 21C

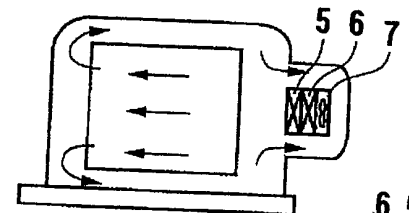
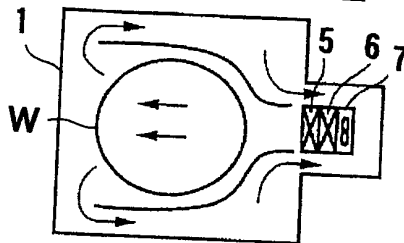


FIG. 21D

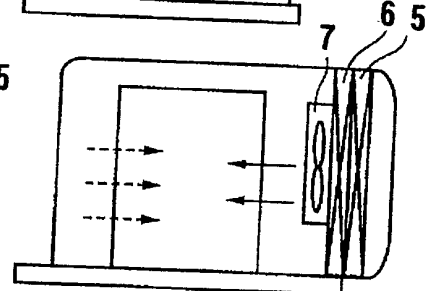
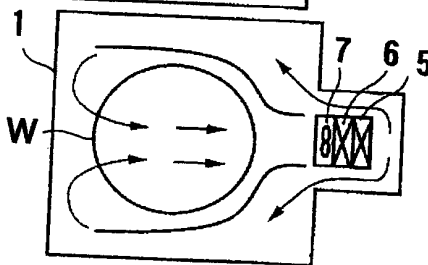


FIG. 21E

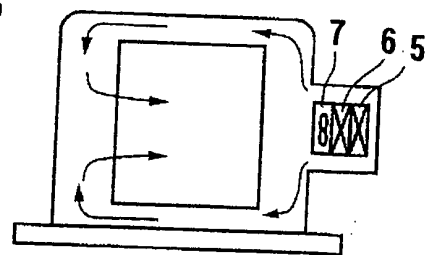
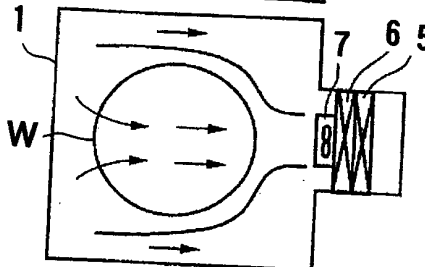
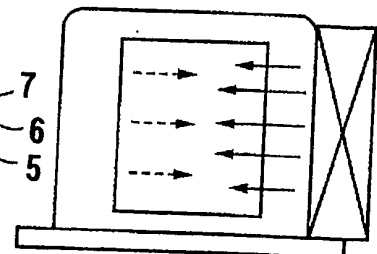
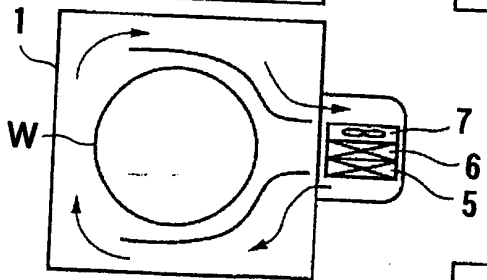


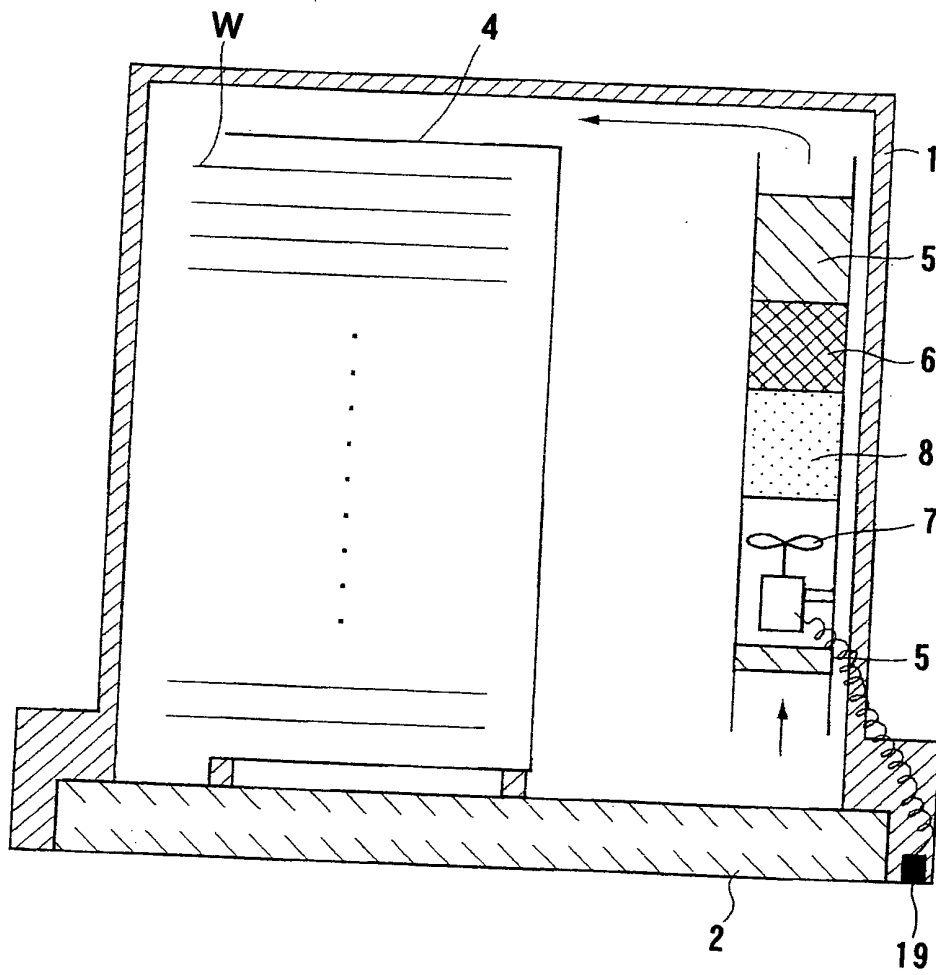
FIG. 21F



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FIG. 22



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FIG. 23A

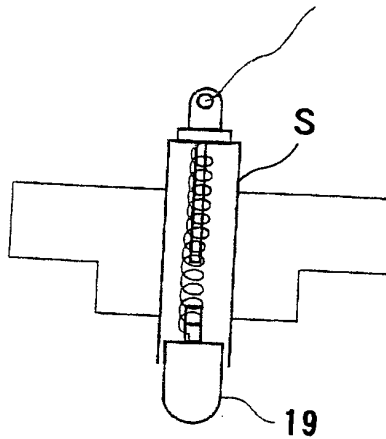
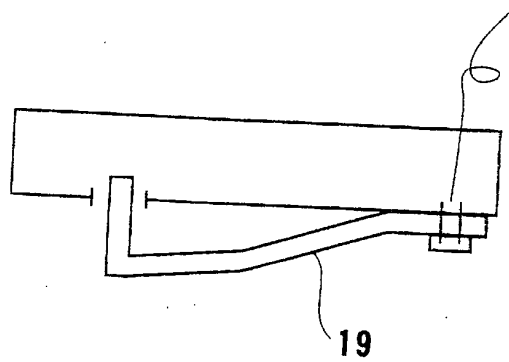
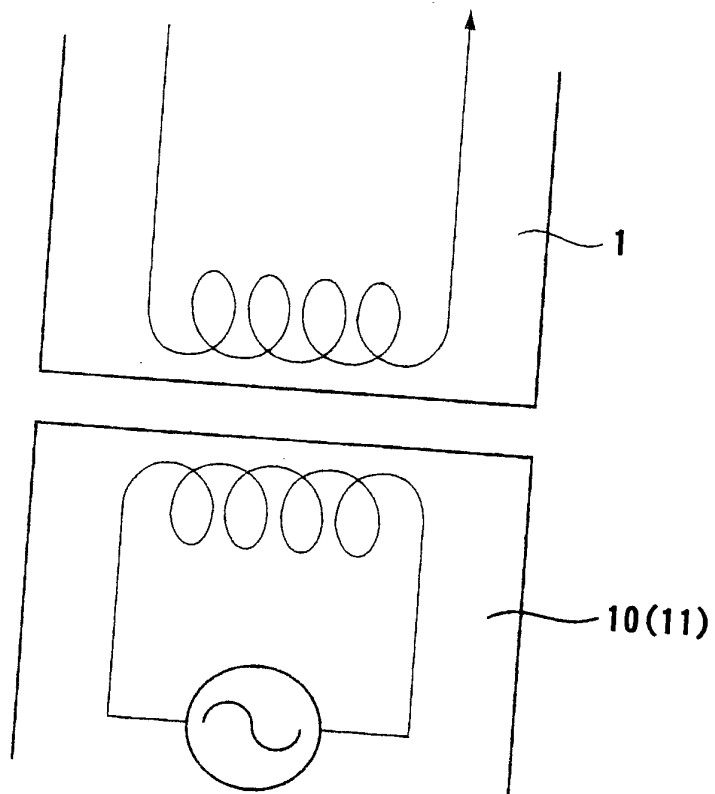


FIG. 23B



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FIG. 24

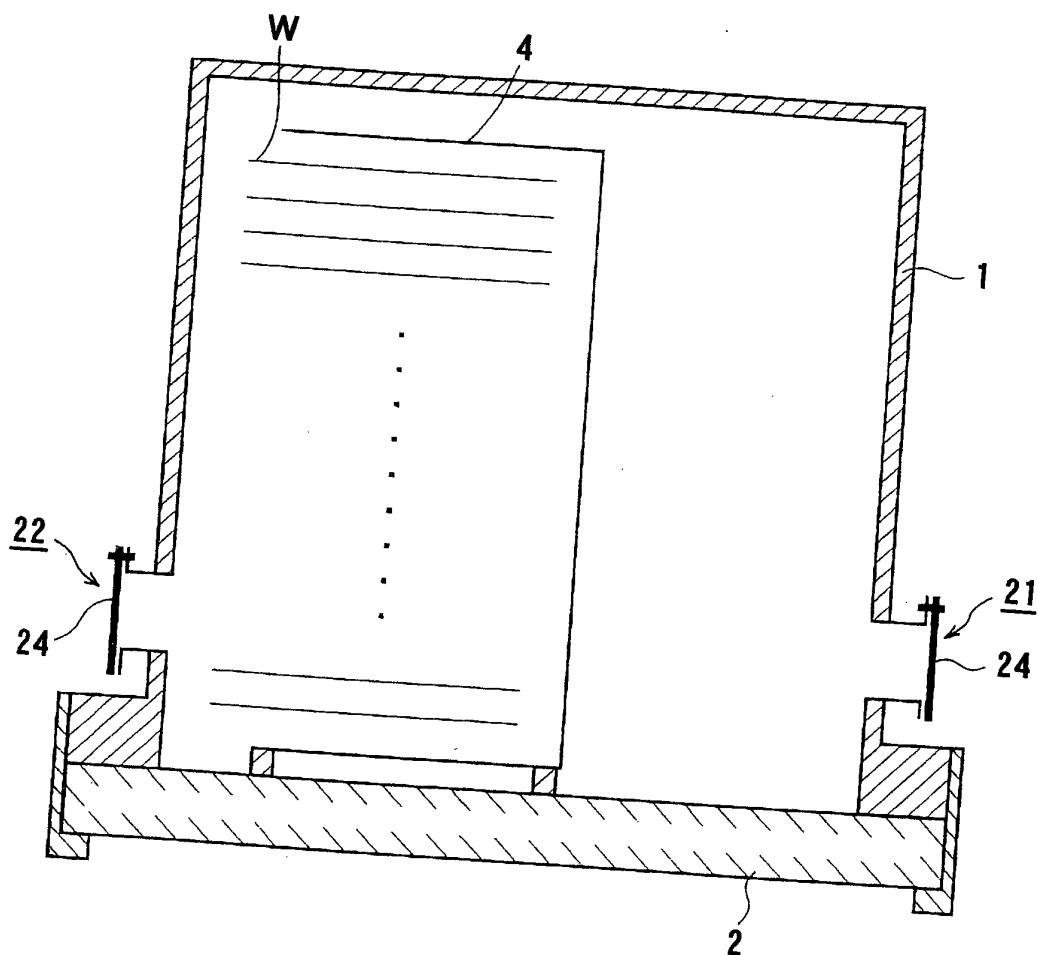


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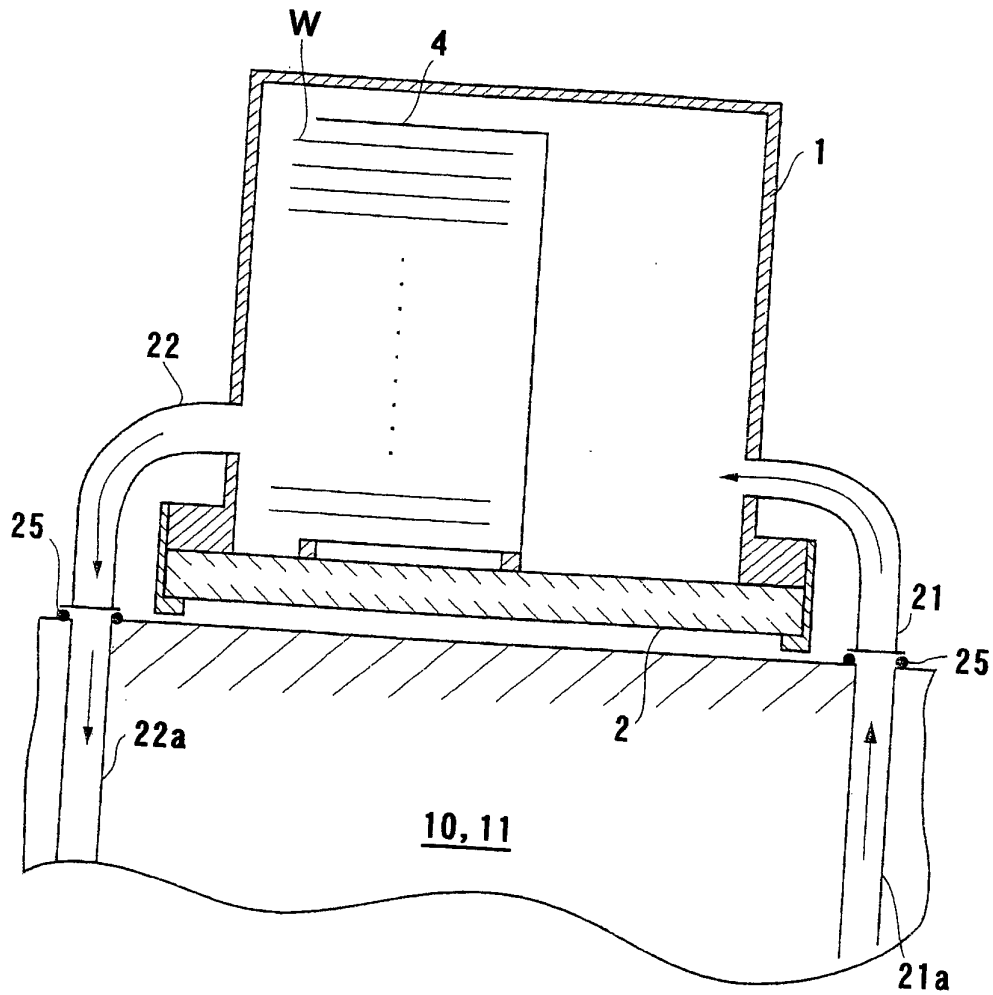
FIG. 25



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FIG. 26



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FIG. 27A

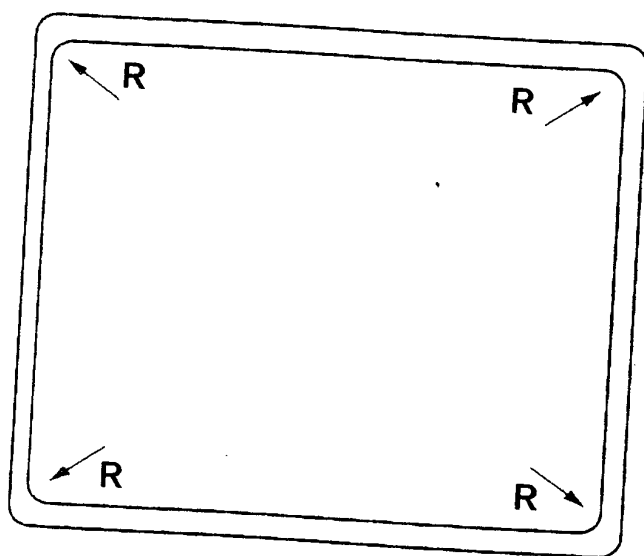
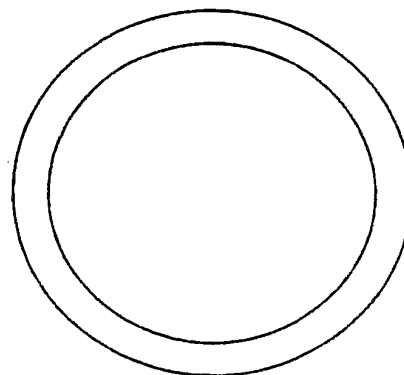


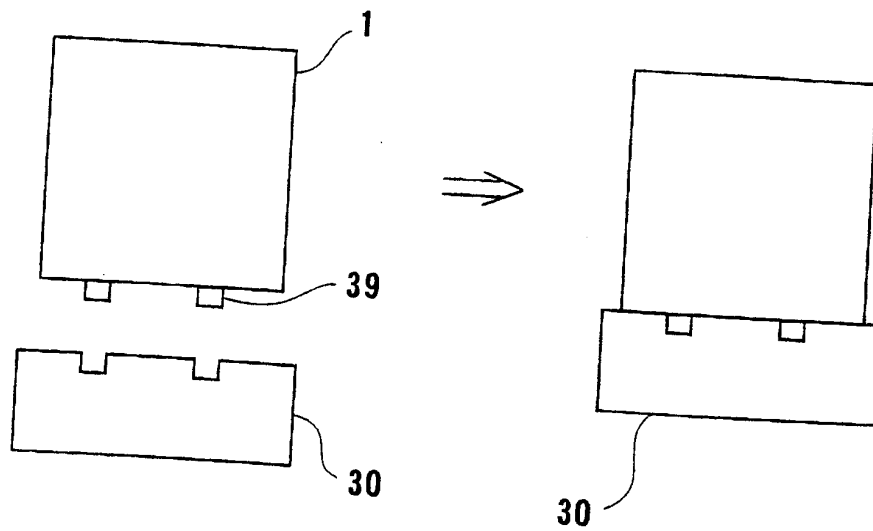
FIG. 27B



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FIG. 28



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FIG. 29A

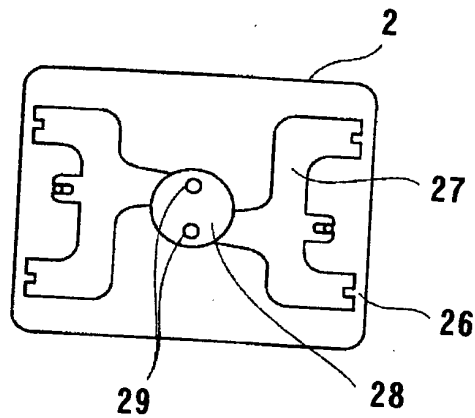


FIG. 29B

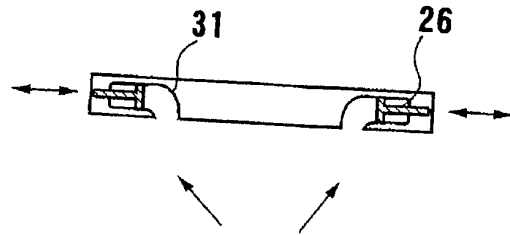


FIG. 29C

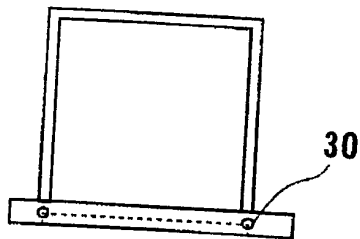


FIG. 29D

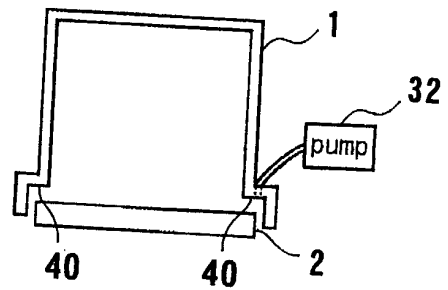


FIG. 29E

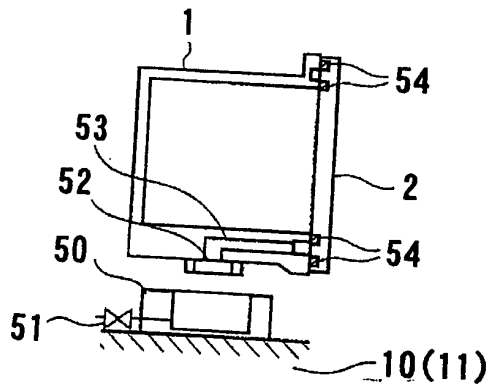
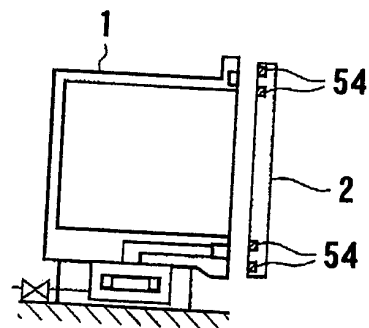


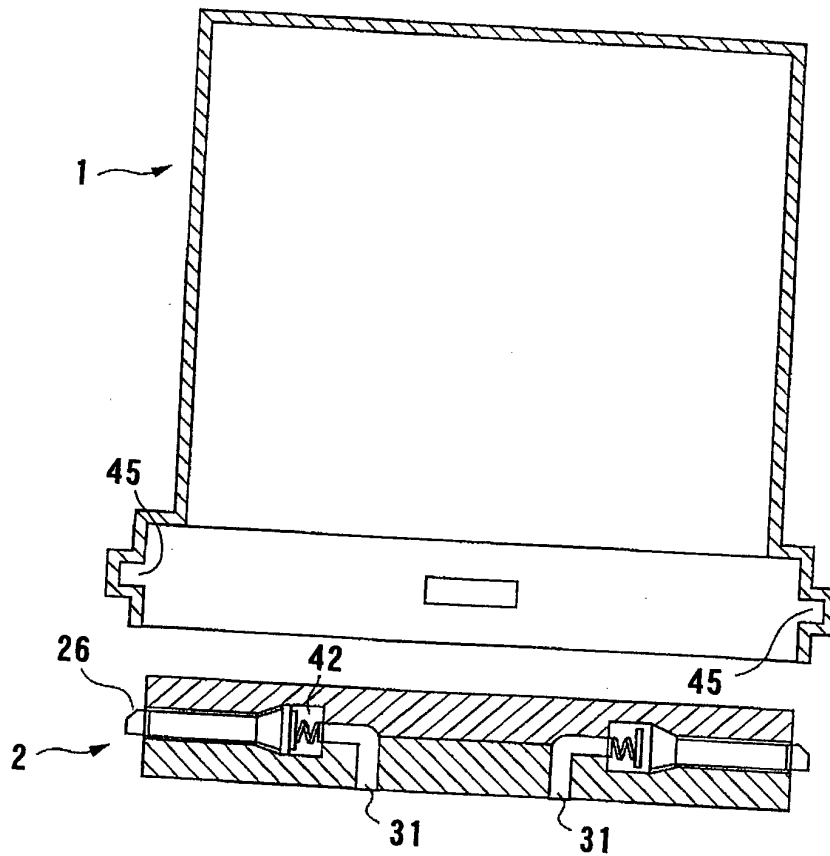
FIG. 29F



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FIG. 30



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FIG. 31A

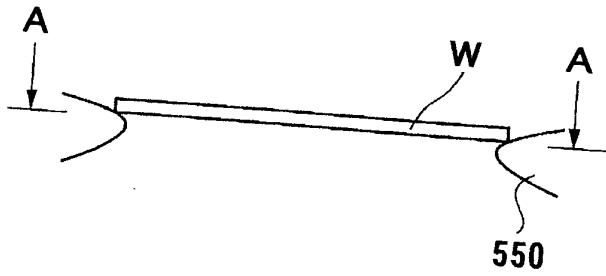
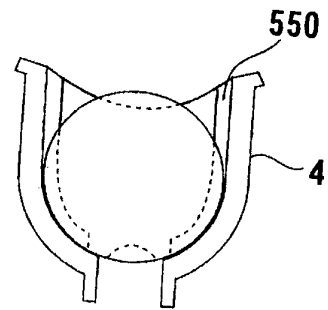


FIG. 31B



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FIG. 33A

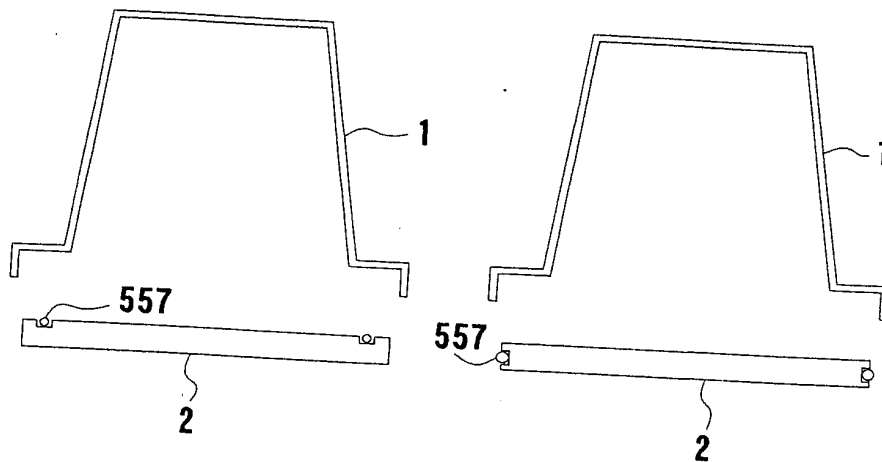


FIG. 33B

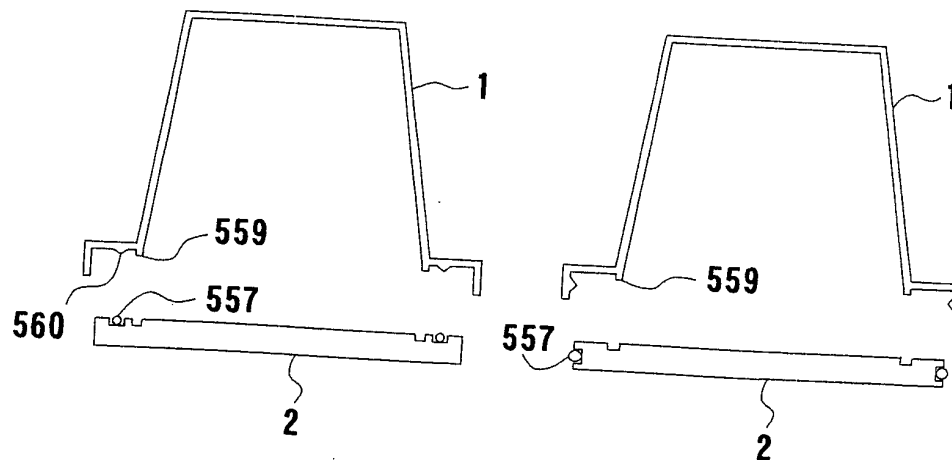


FIG. 34A

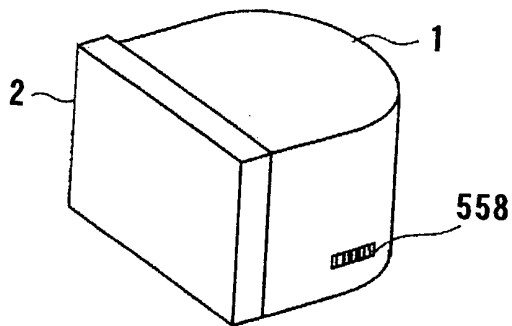
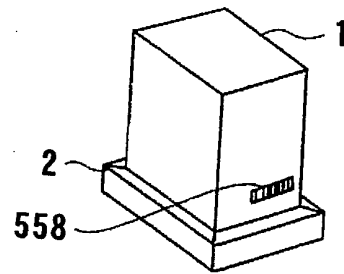


FIG. 34B



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FIG. 35A

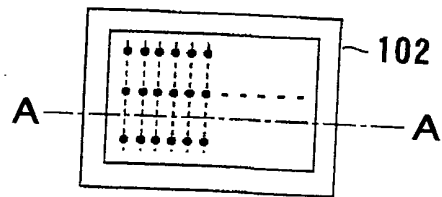


FIG. 35B

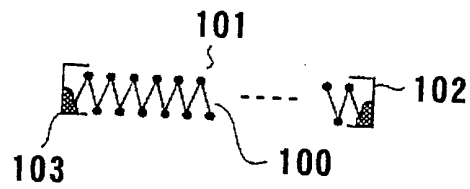
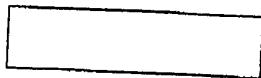


FIG. 35C



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FIG. 36A

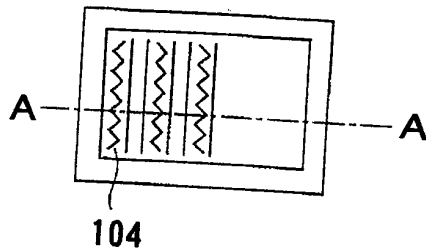


FIG. 36B

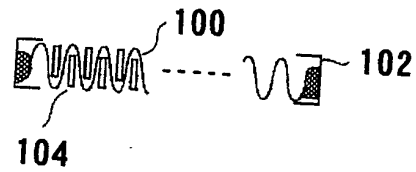
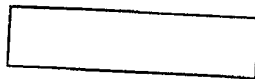


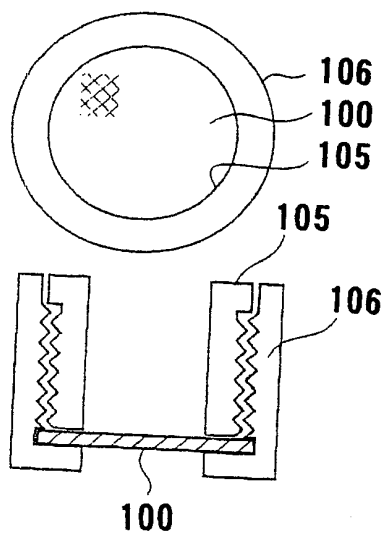
FIG. 36C



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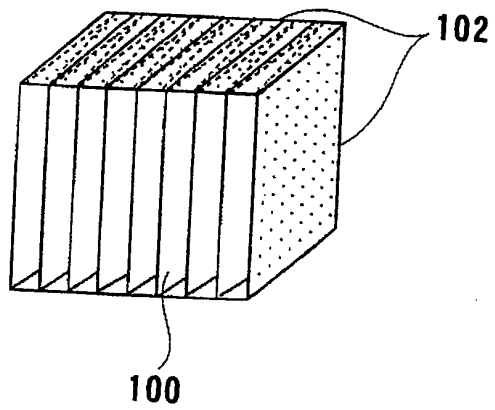
FIG. 37



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FIG. 38



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FIG. 40A

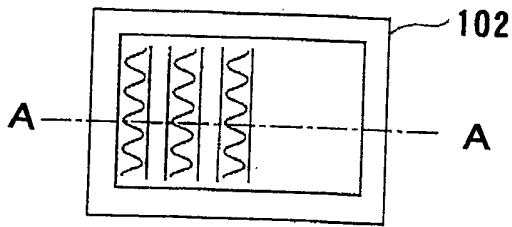


FIG. 40B

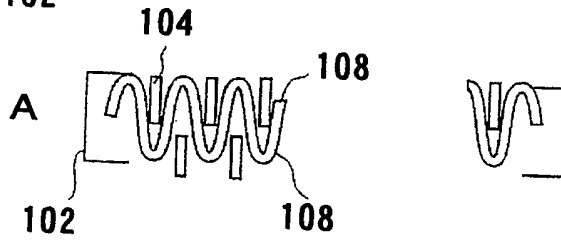


FIG. 40C



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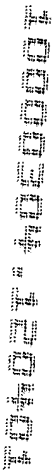


FIG. 42A

FIG. 42B

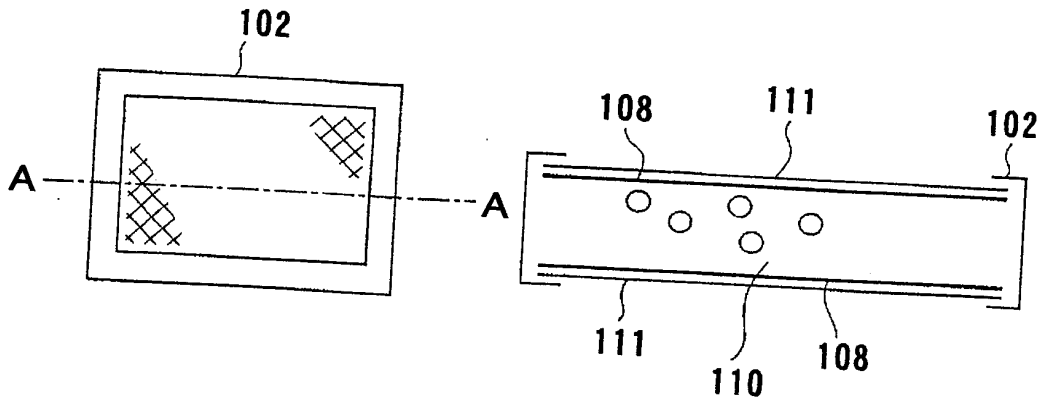
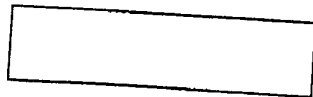


FIG. 42C



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FIG. 43A

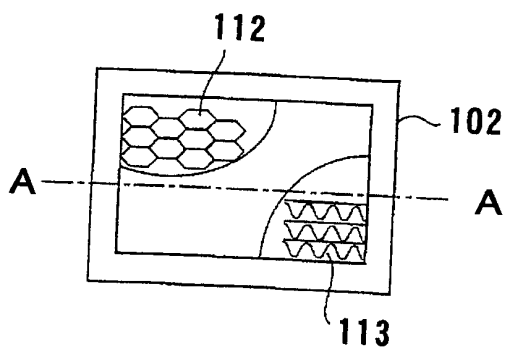


FIG. 43B

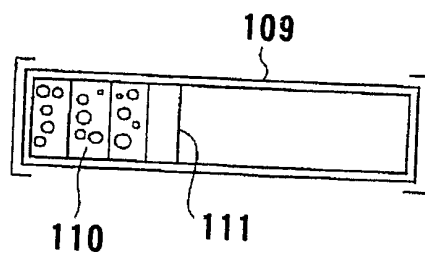
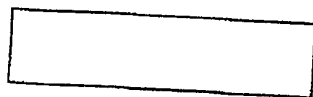


FIG. 43C



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FIG. 44A

FIG. 44B

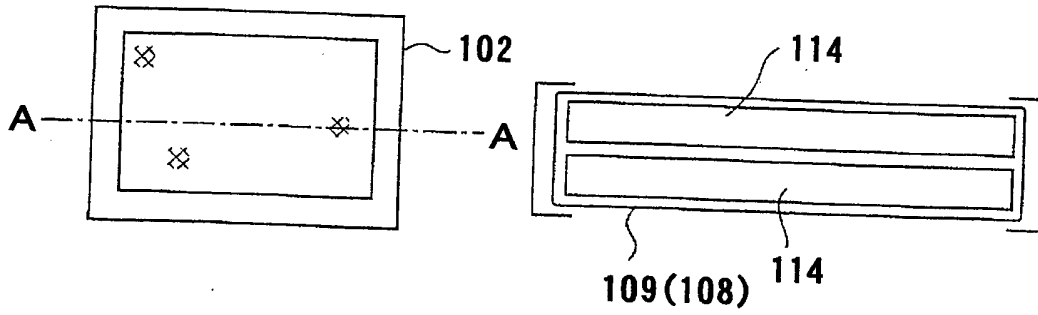


FIG. 44C



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FIG. 45A

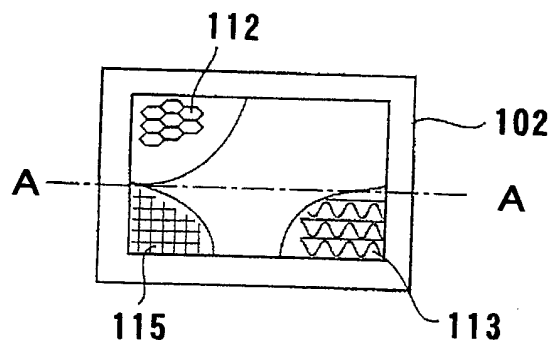
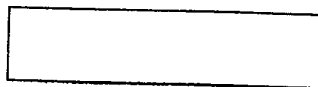


FIG. 45B



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FIG. 1 is a perspective view of a multi-layered structure 100. The structure consists of a central core 108 and two outer layers, 116a and 116b. Arrows A and B indicate the thickness of the layers 116a and 116b, respectively.

FIG. 47

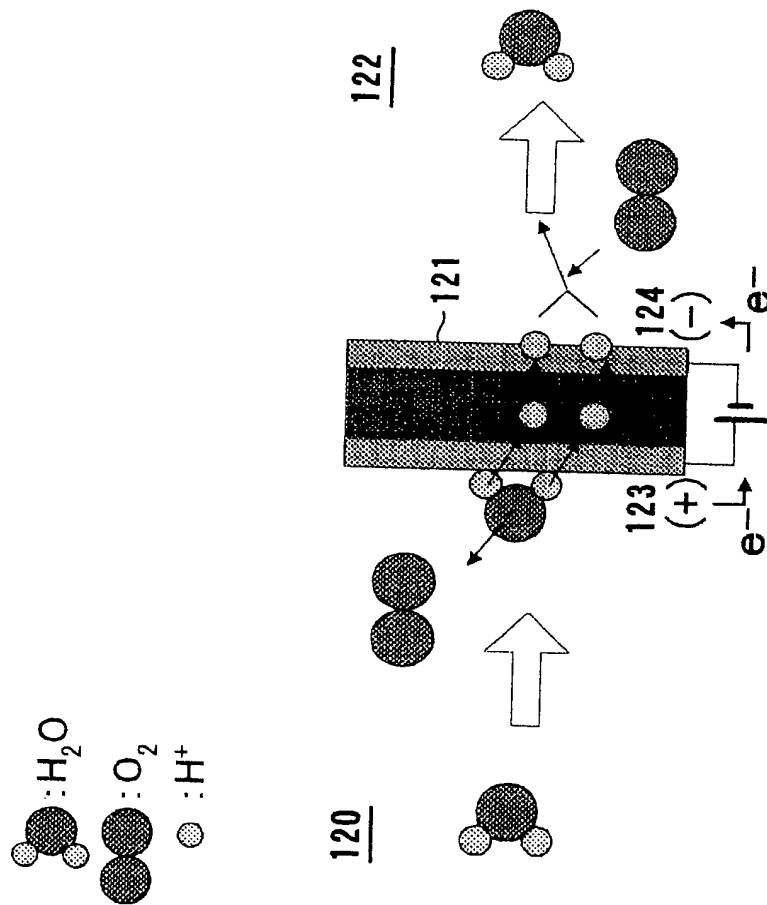
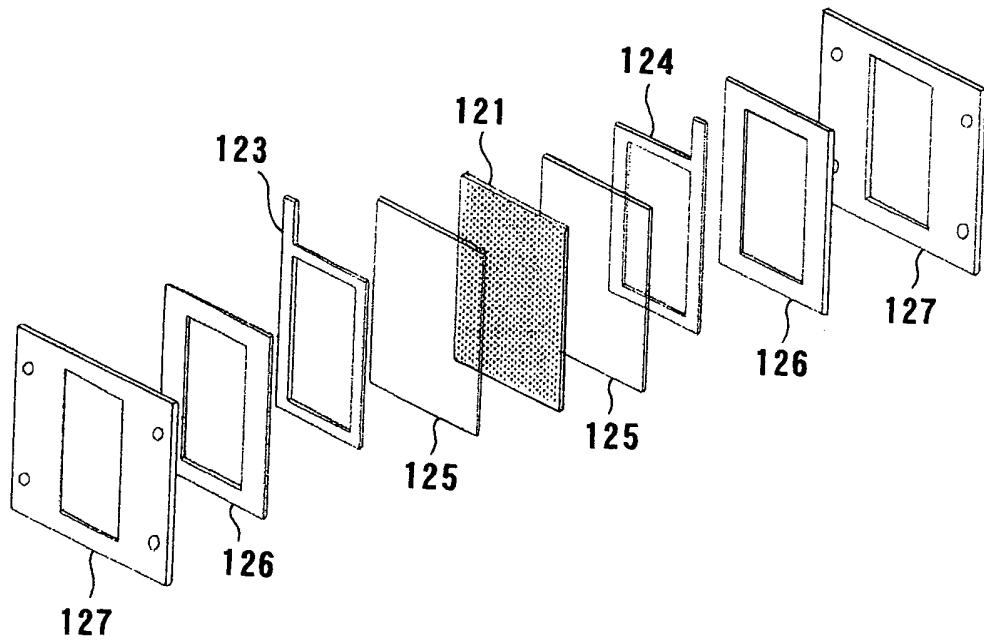


FIG. 48

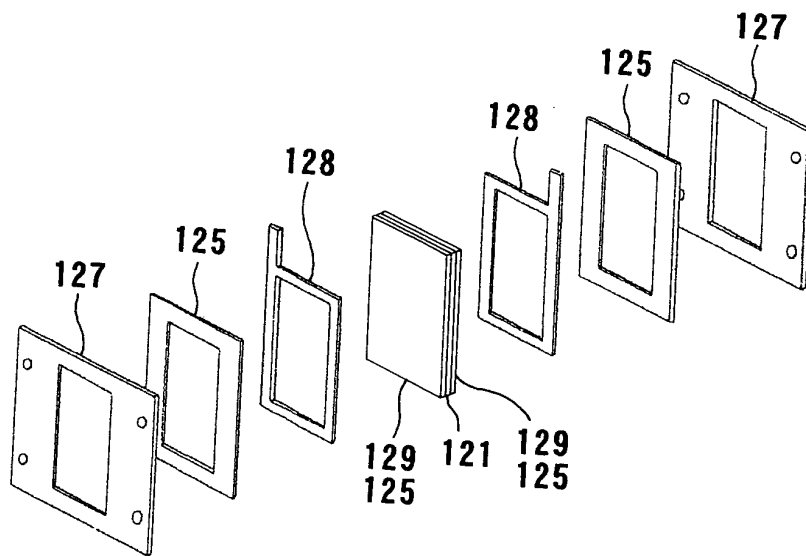


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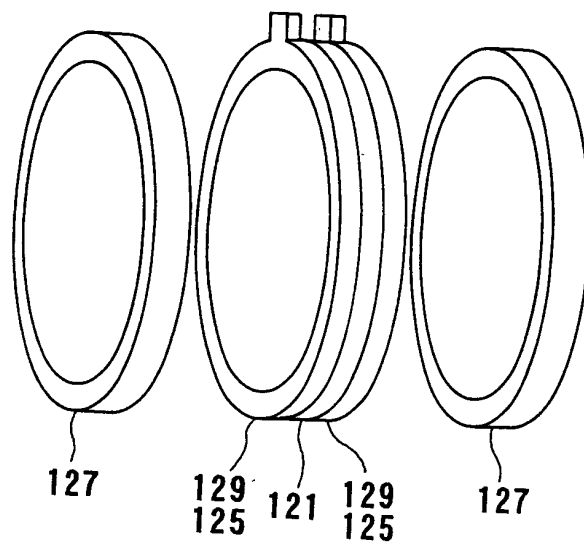
FIG. 49



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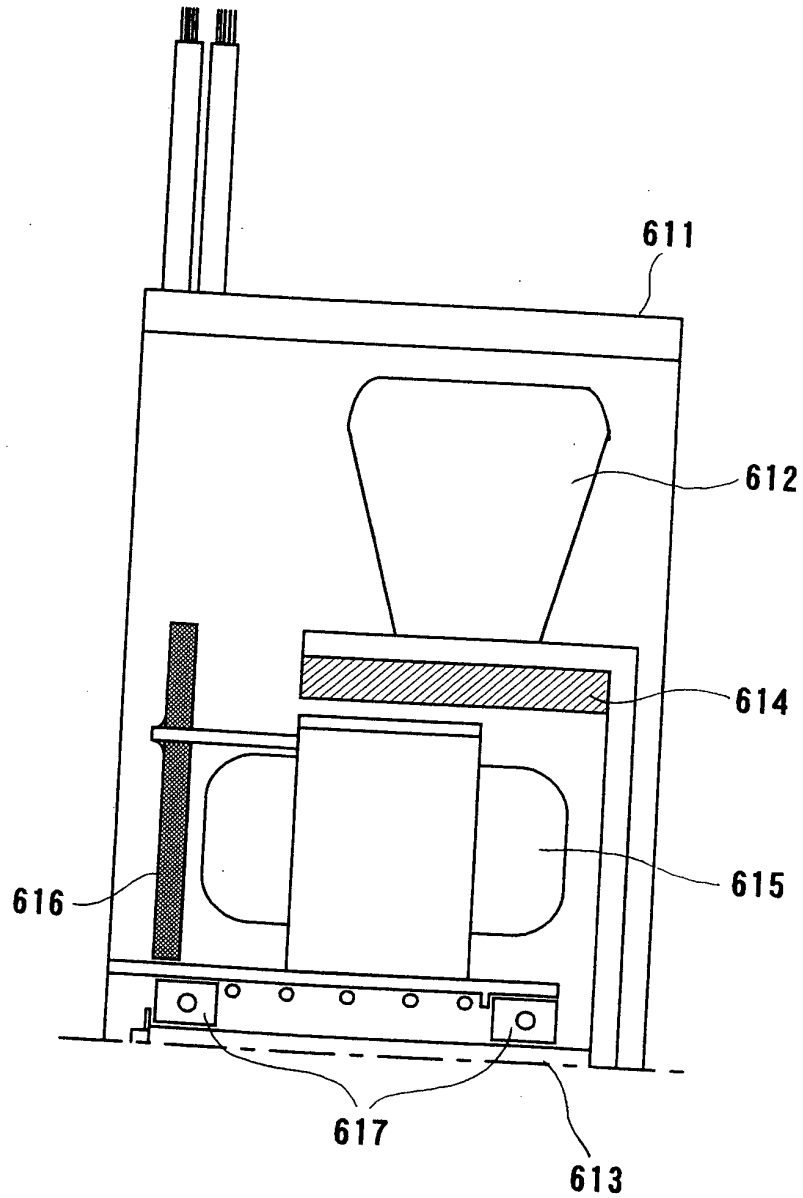
FIG. 50



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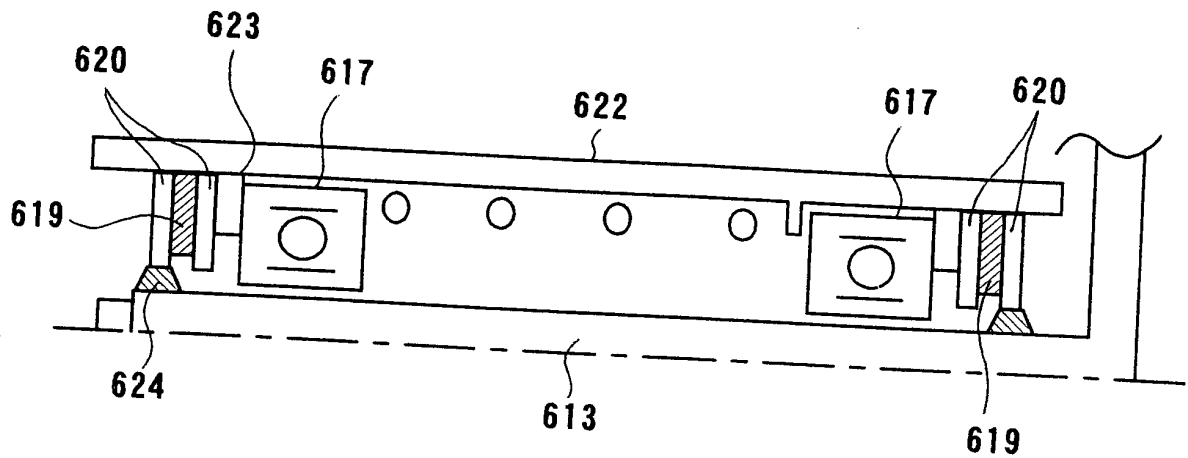
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FIG. 51



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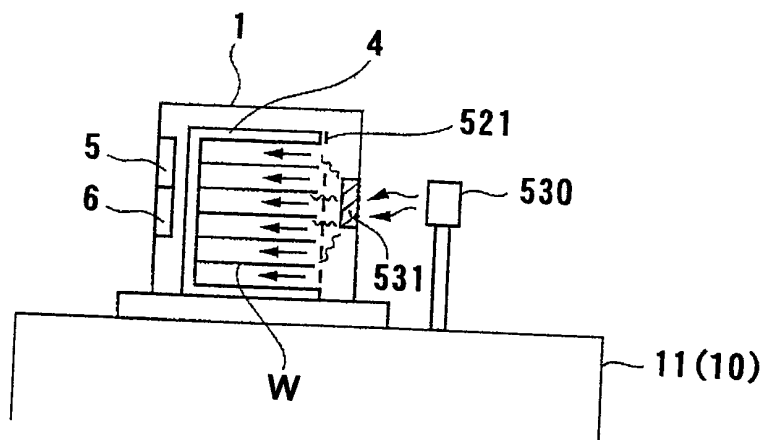
FIG. 52



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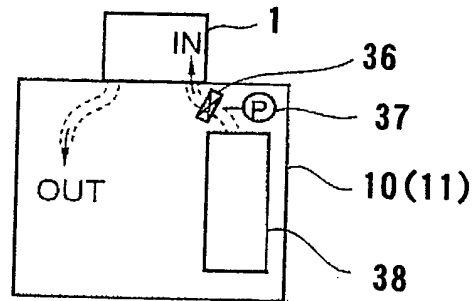
FIG. 53



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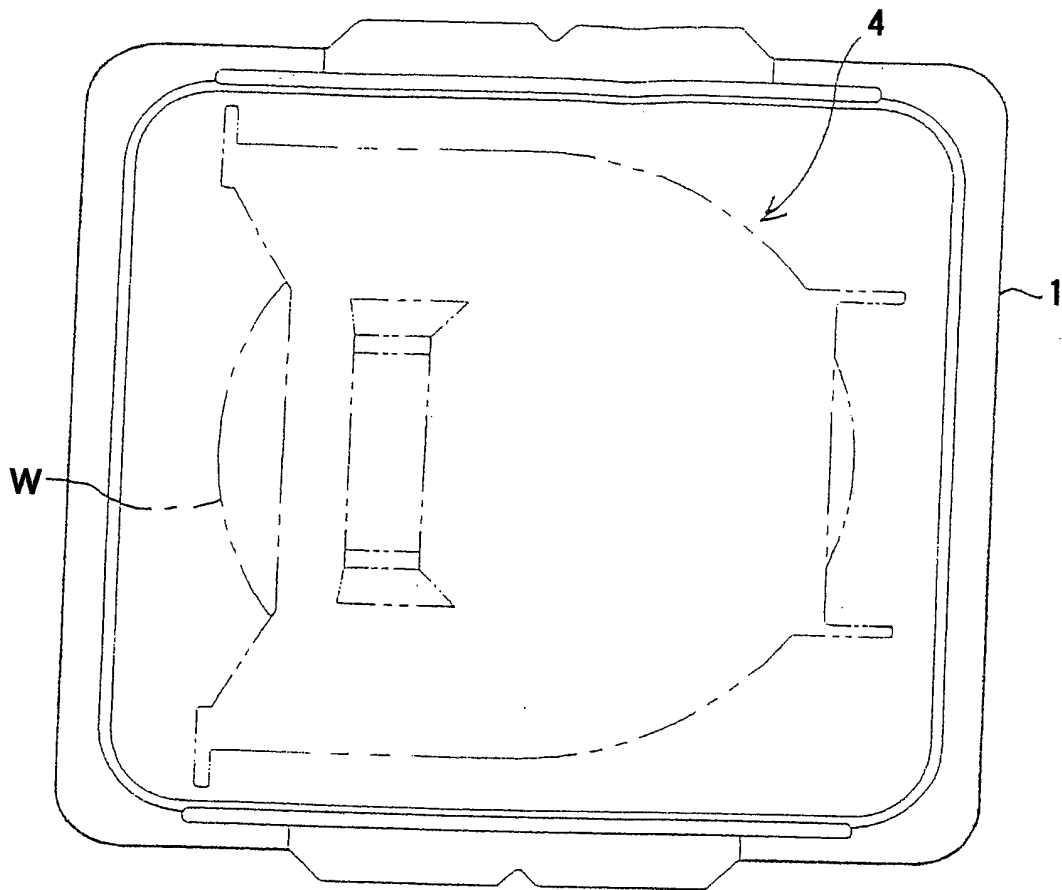
FIG. 54



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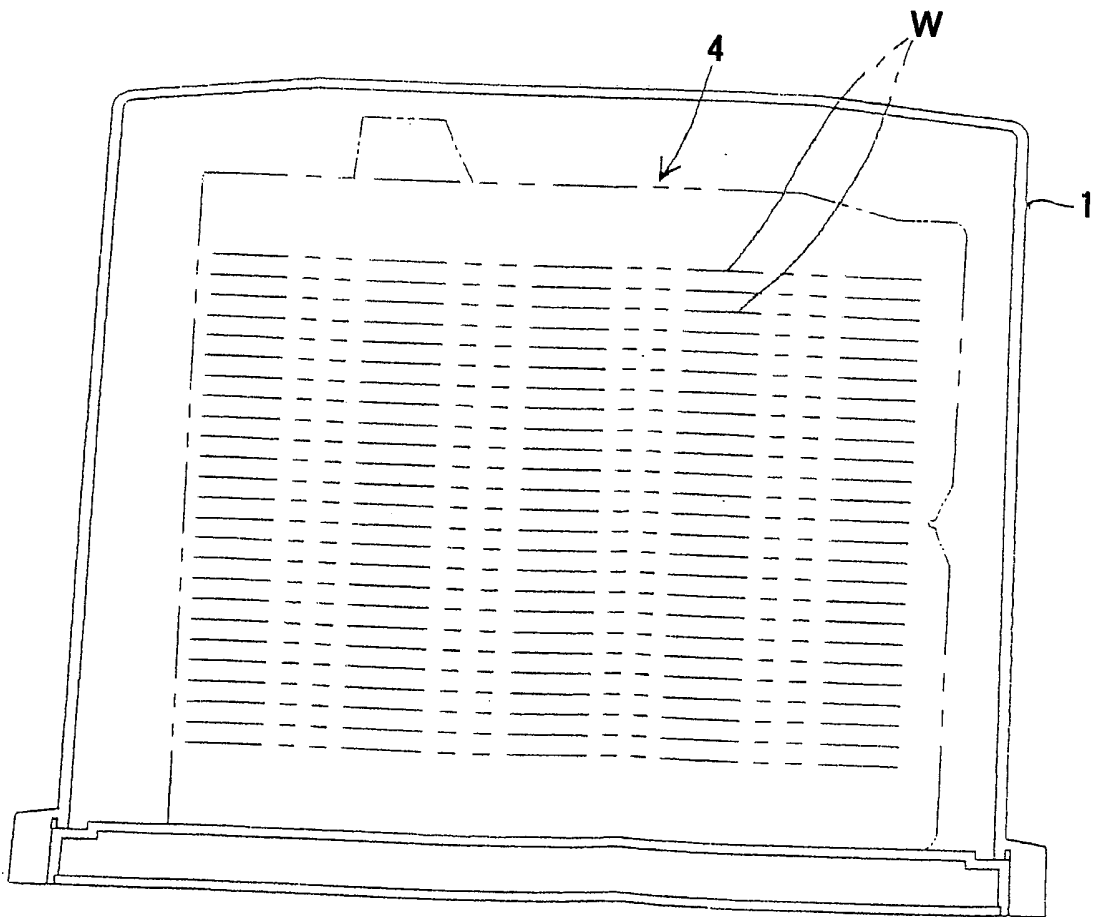
FIG. 55



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FIG. 56



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FIG. 57A

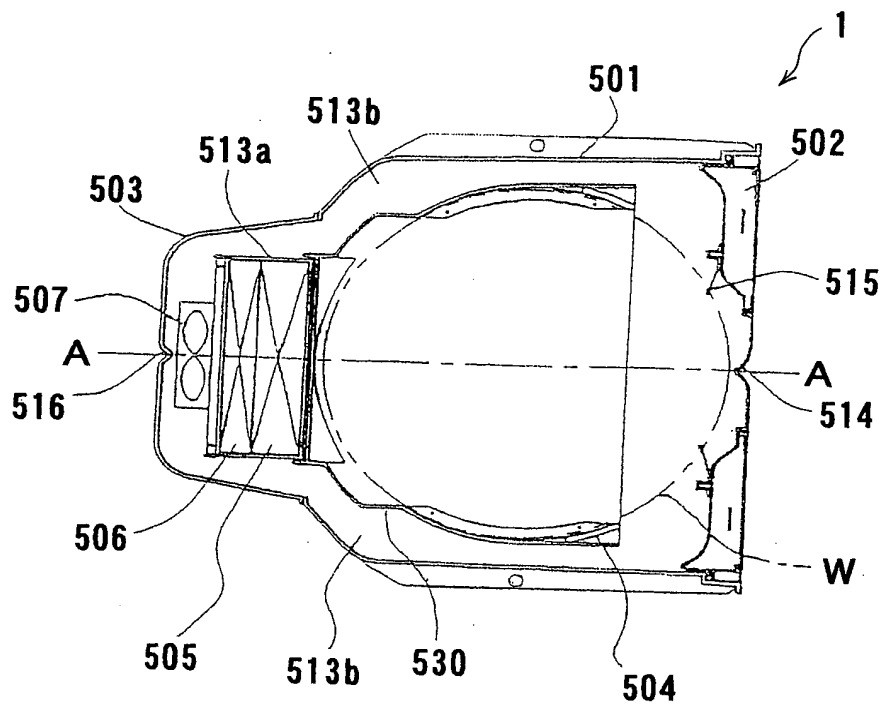
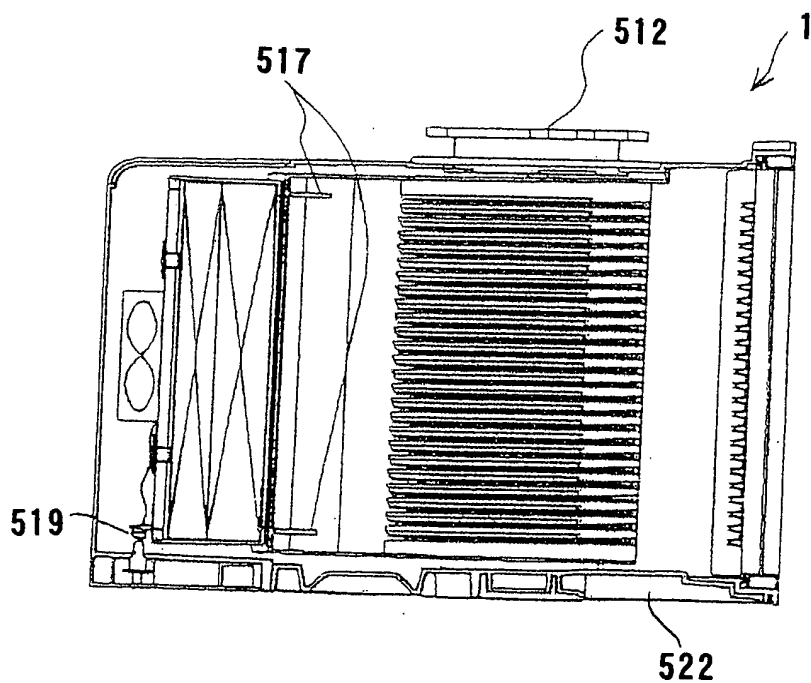


FIG. 57B



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FIG. 58A

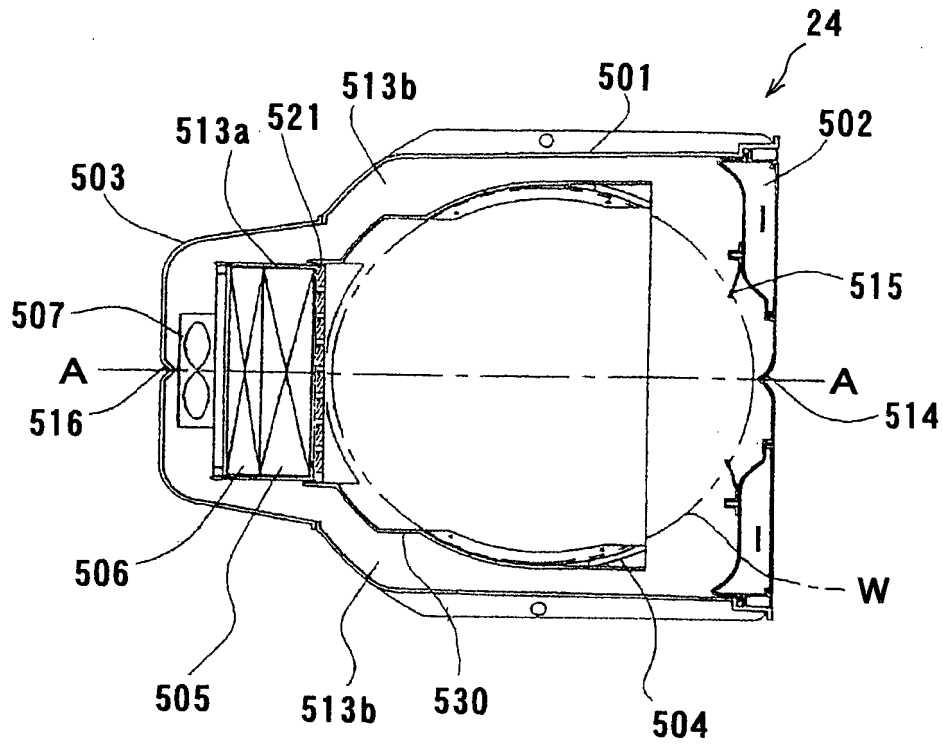
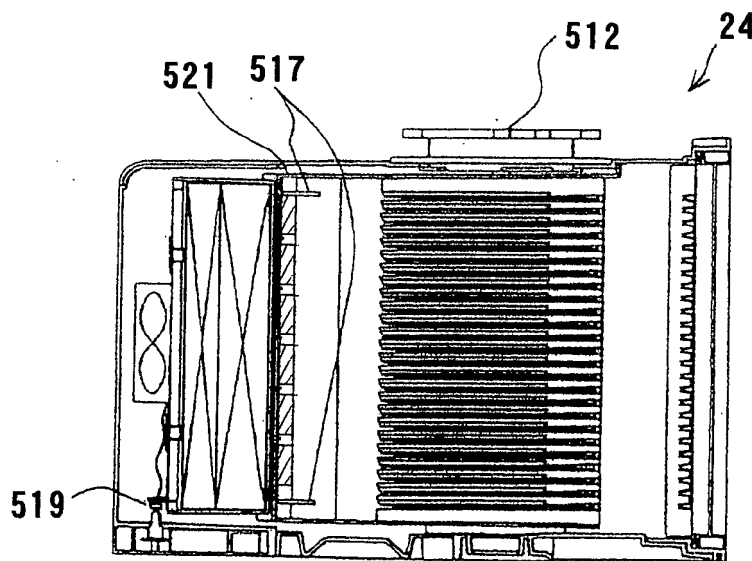


FIG. 58B



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FIG. 59A

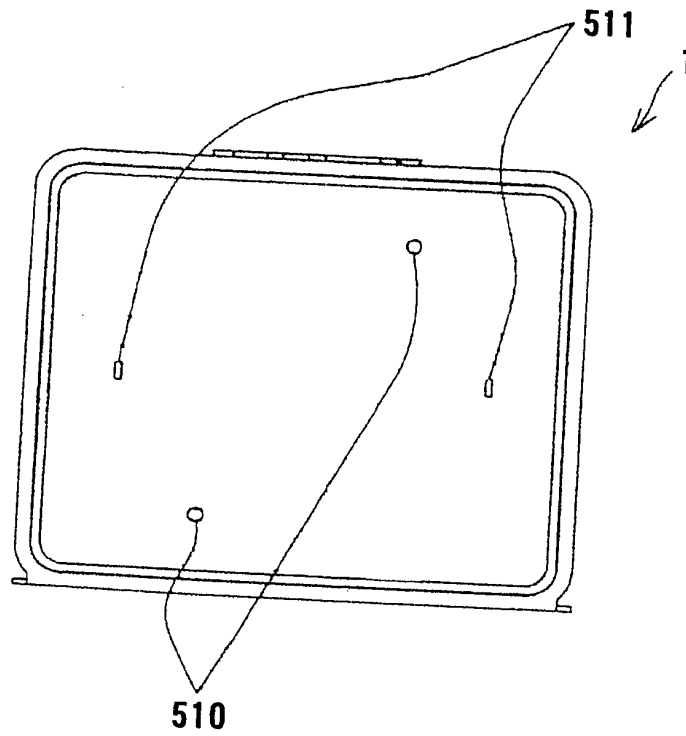
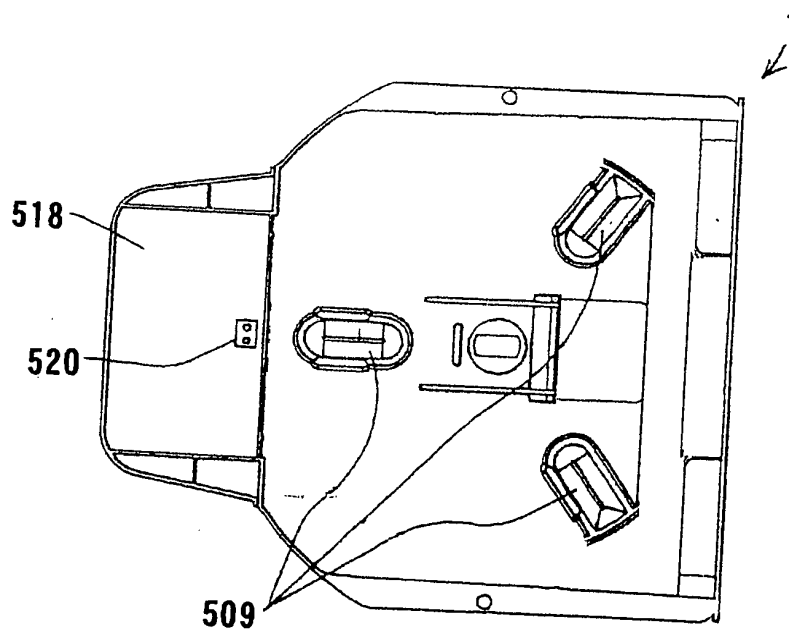


FIG. 59B



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FIG. 60A

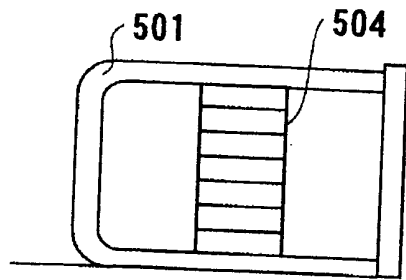


FIG. 60B

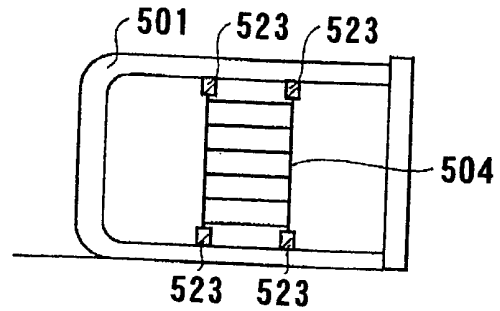


FIG. 60C

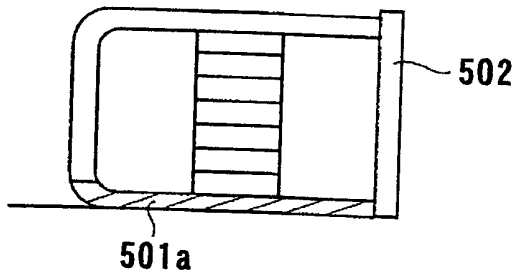


FIG. 60D

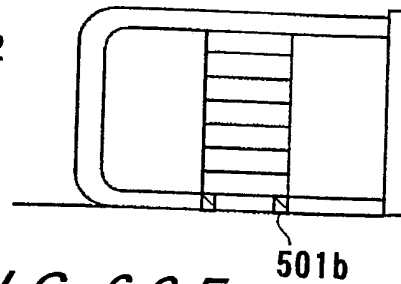


FIG. 60E

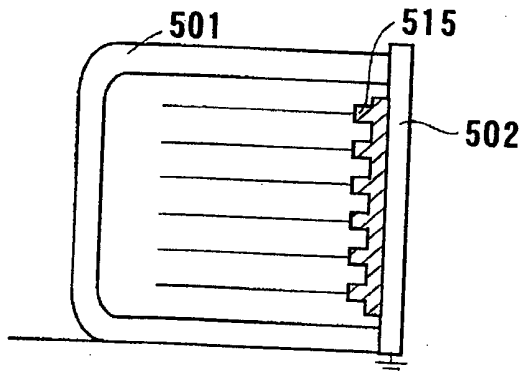


FIG. 60F

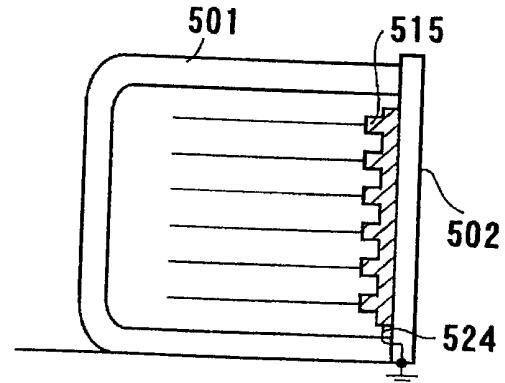


FIG. 60G

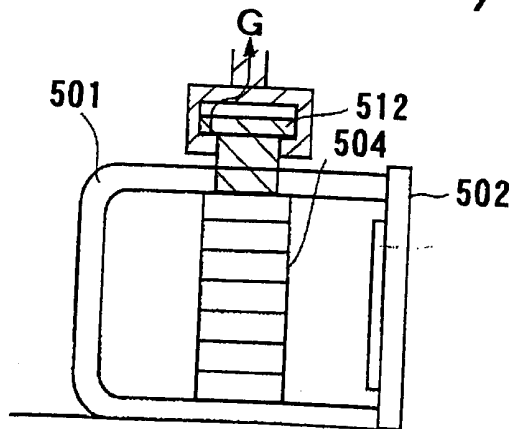


FIG. 60H

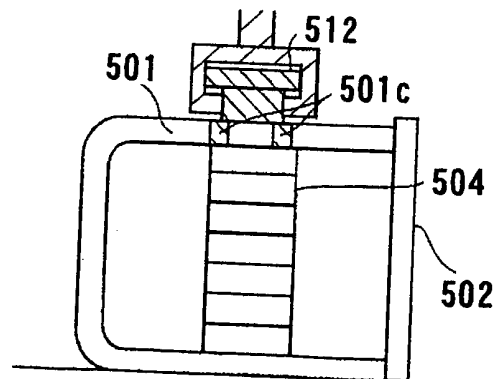
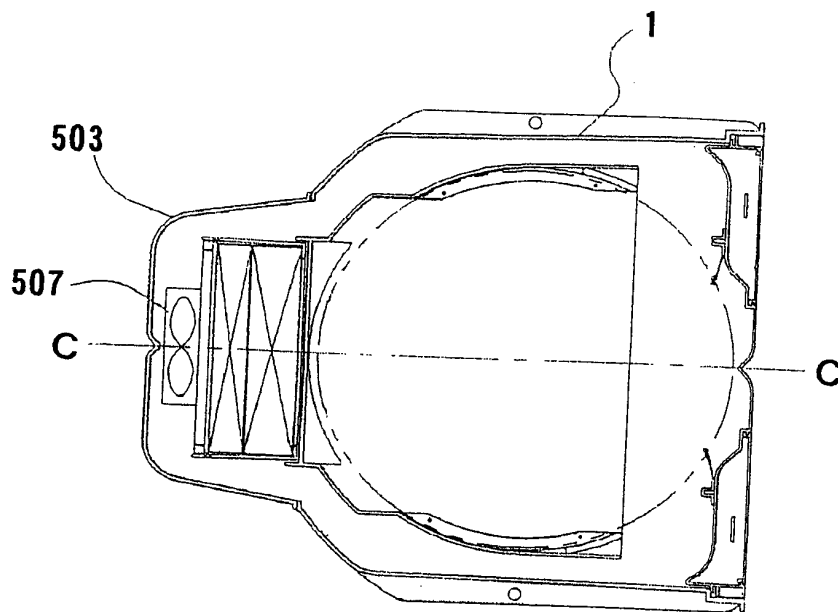


FIG. 60A

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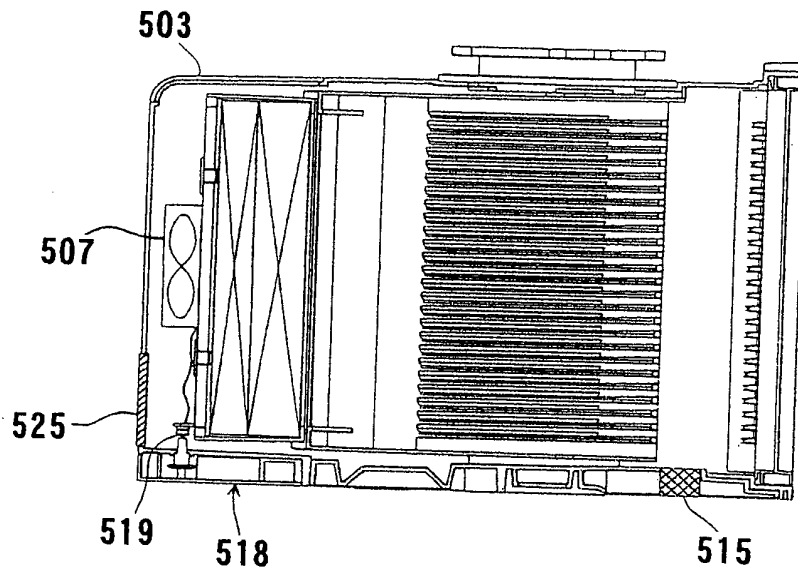
FIG. 61



1000000-1000000

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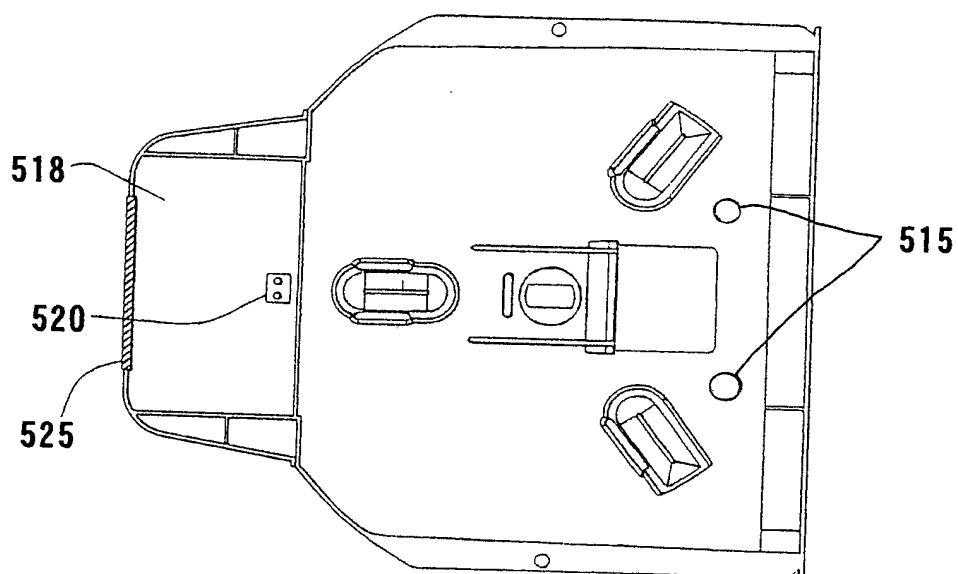
FIG. 62



104927-4060007

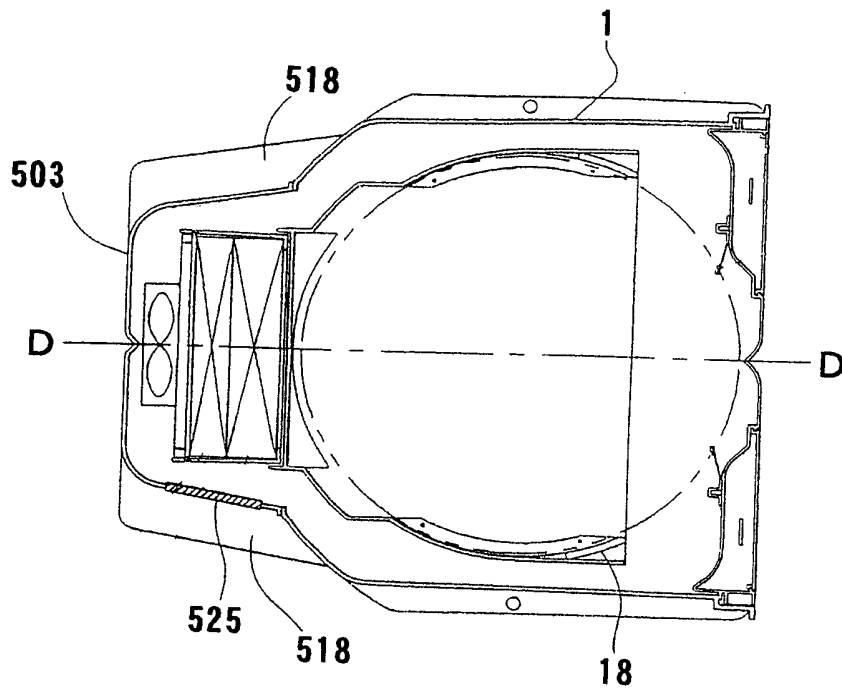
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FIG. 63



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FIG. 64

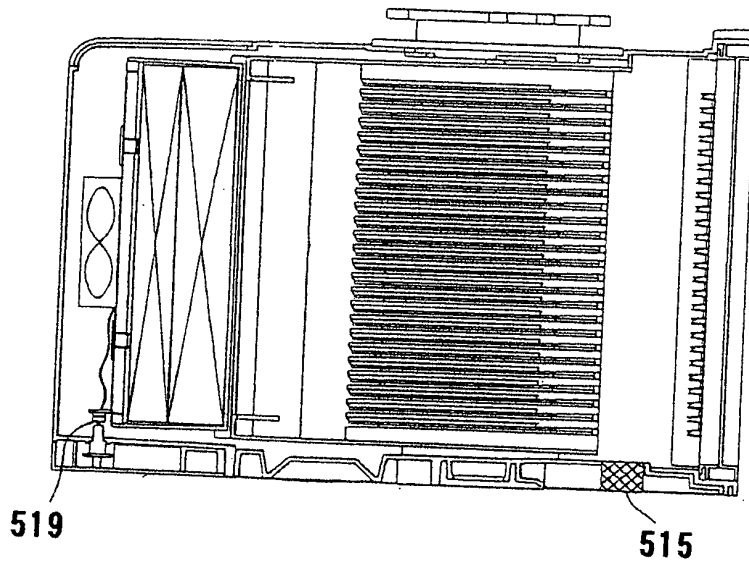


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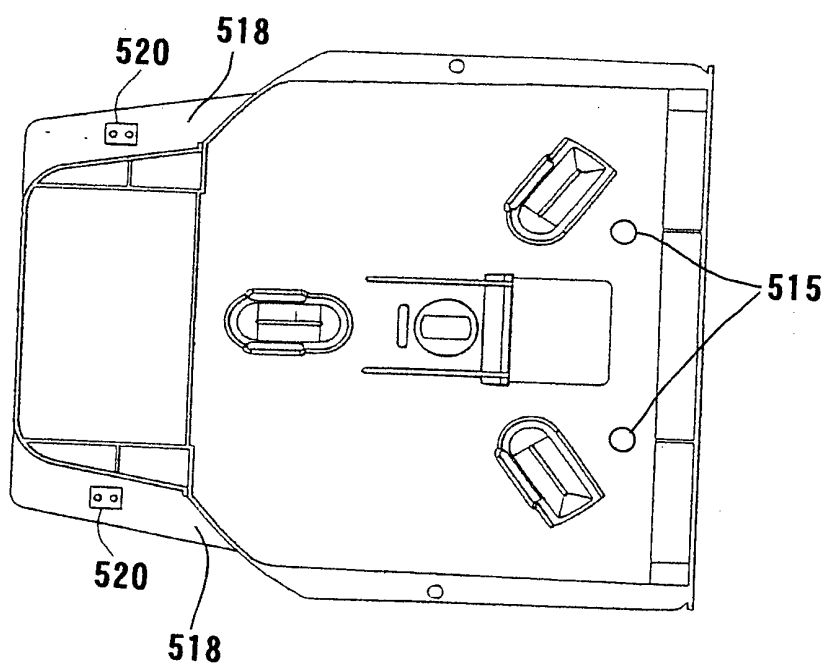
FIG. 65



10000304-4200001

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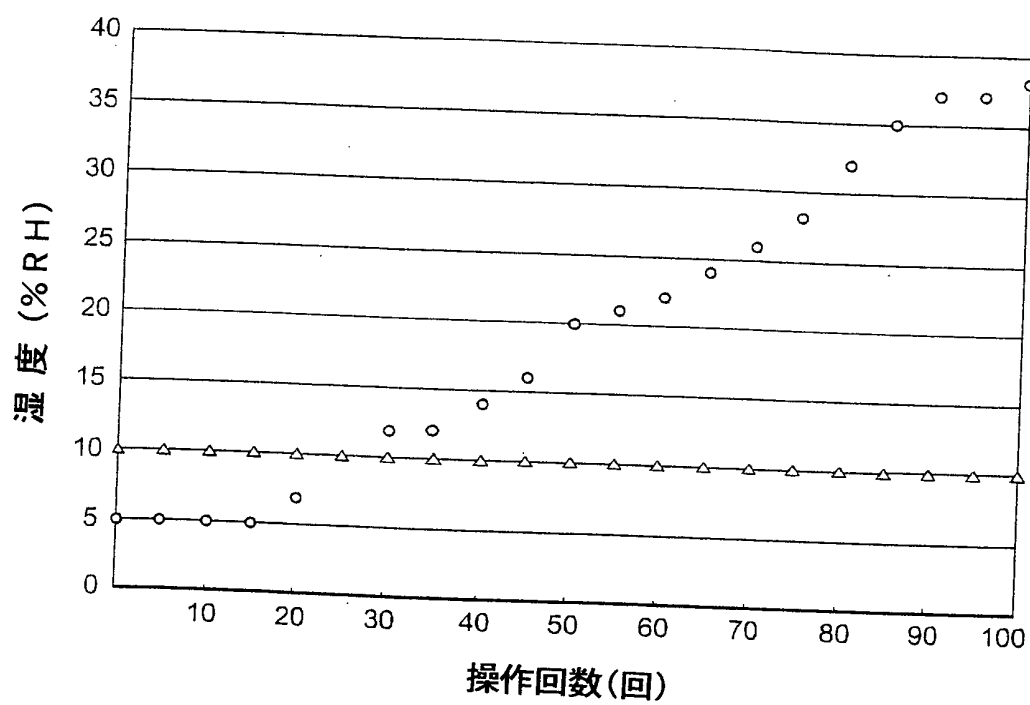
FIG. 66



1000364-120404

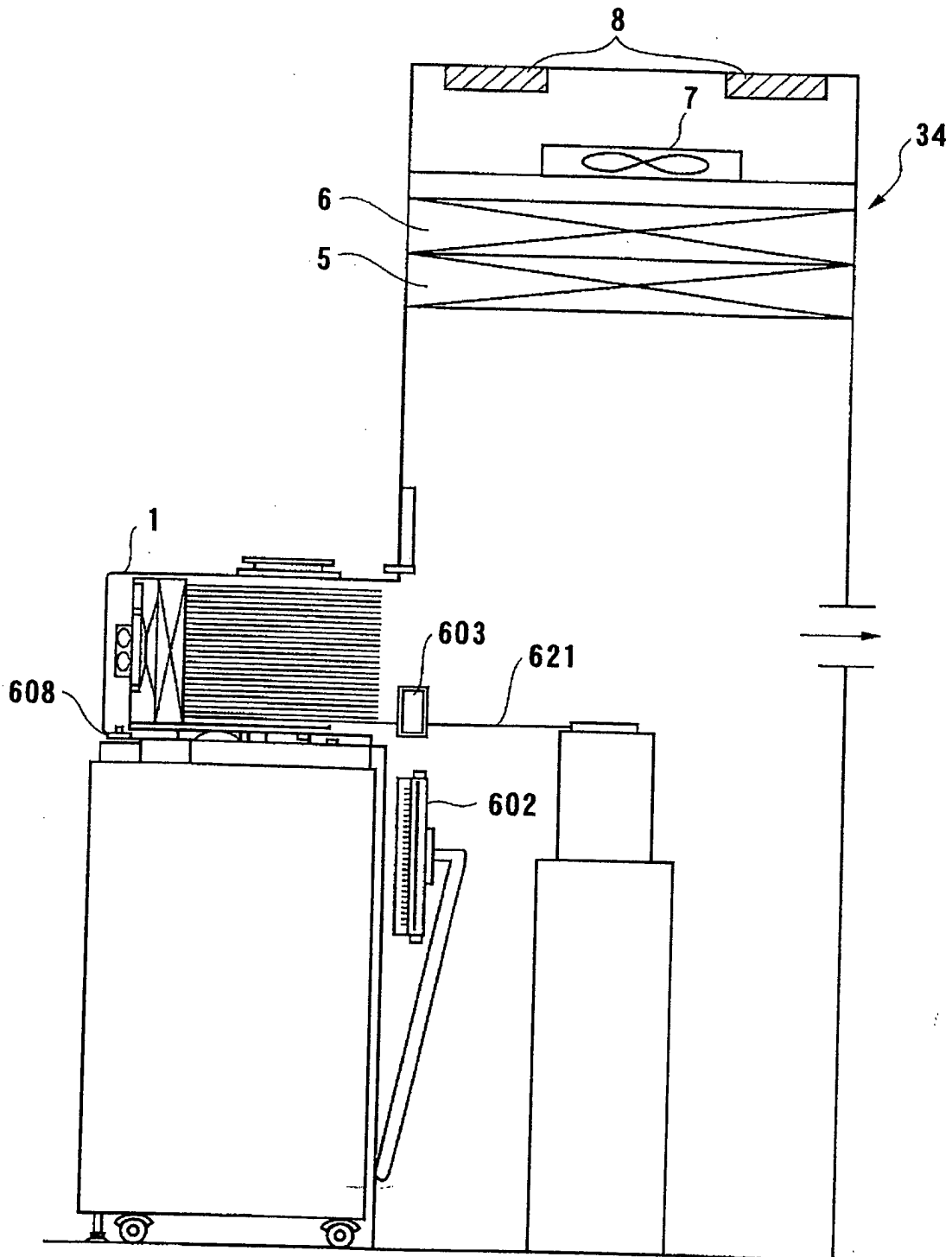
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FIG. 67



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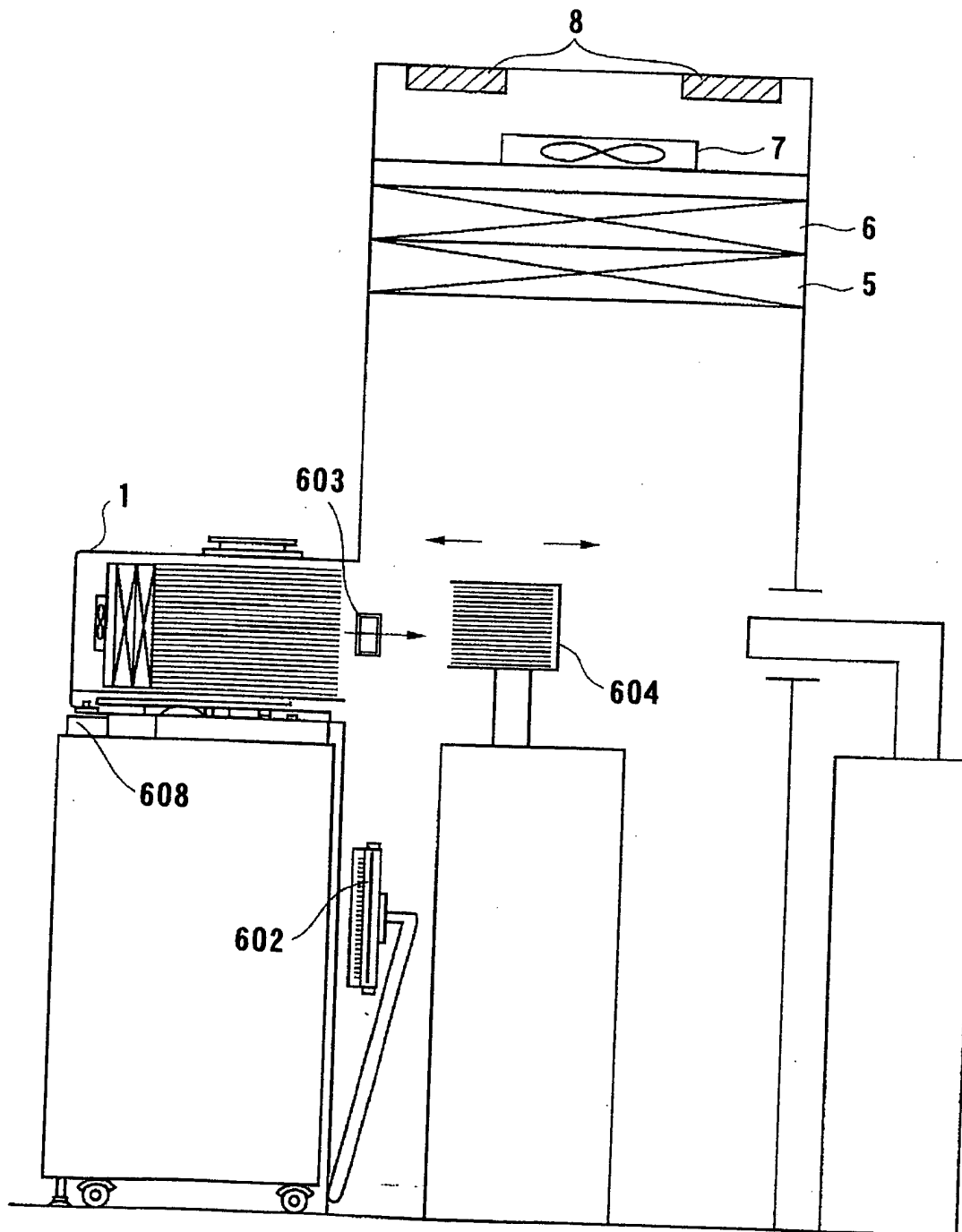
FIG. 68



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FIG. 69



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FIG. 70A

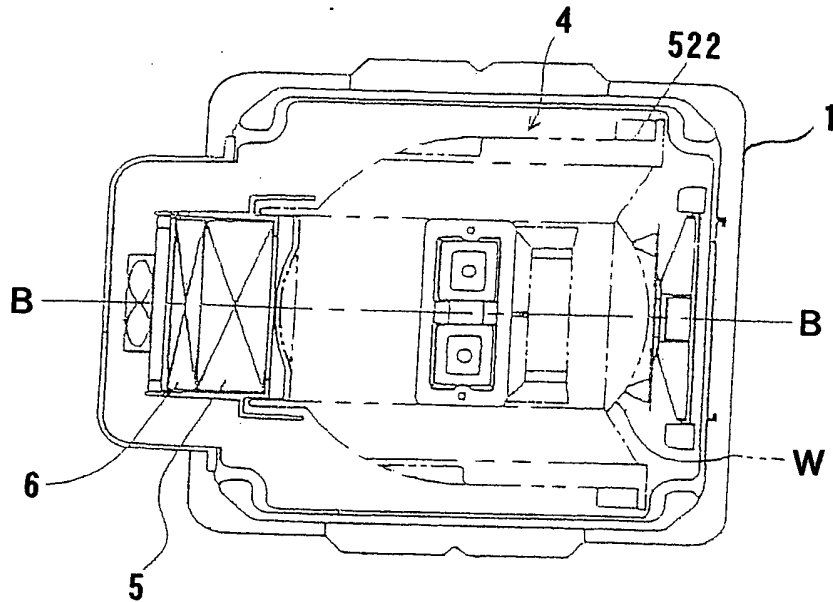
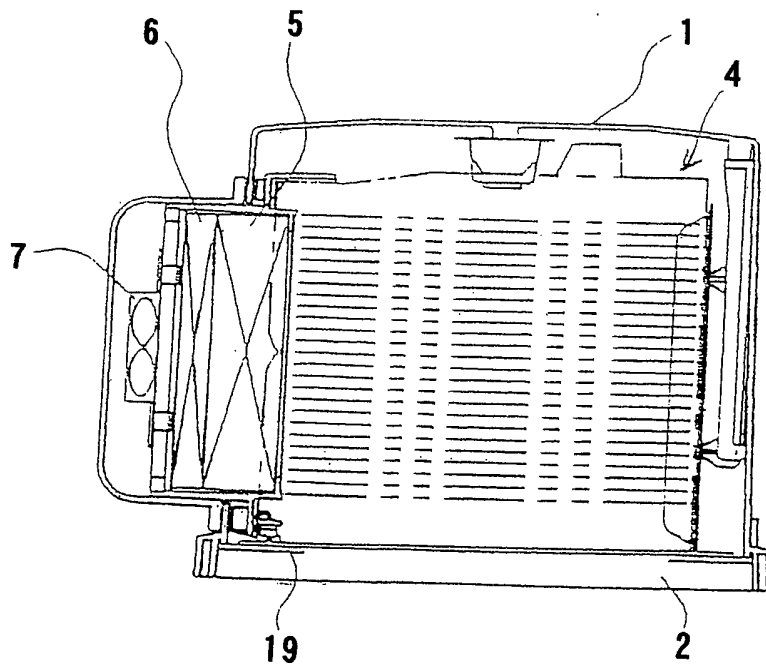


FIG. 70B



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FIG. 71A

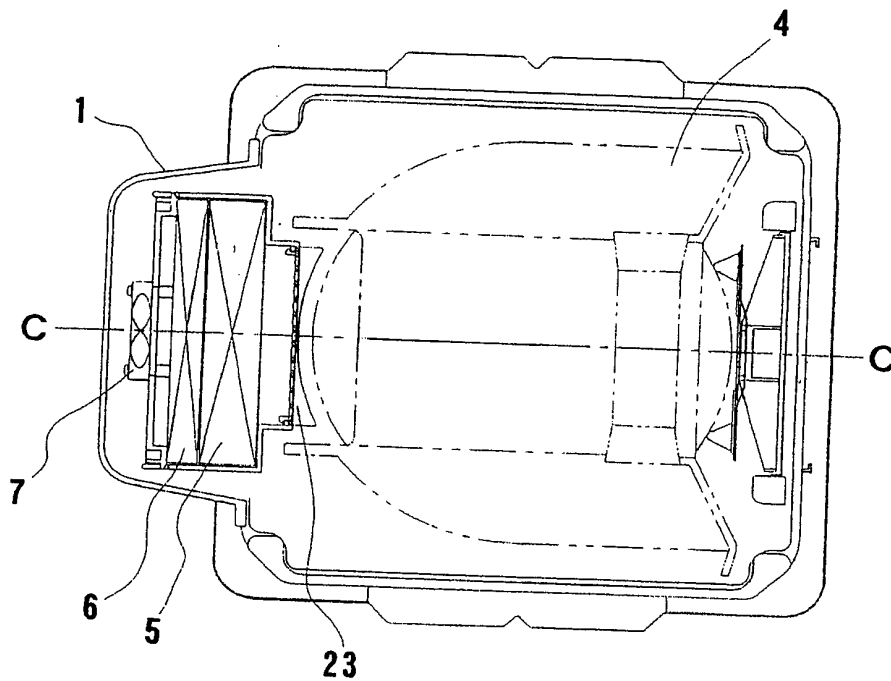
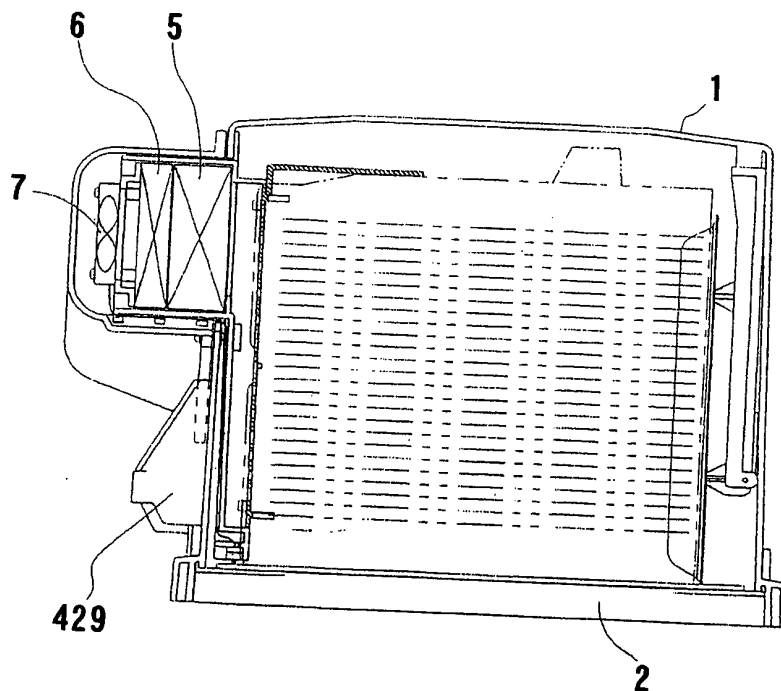
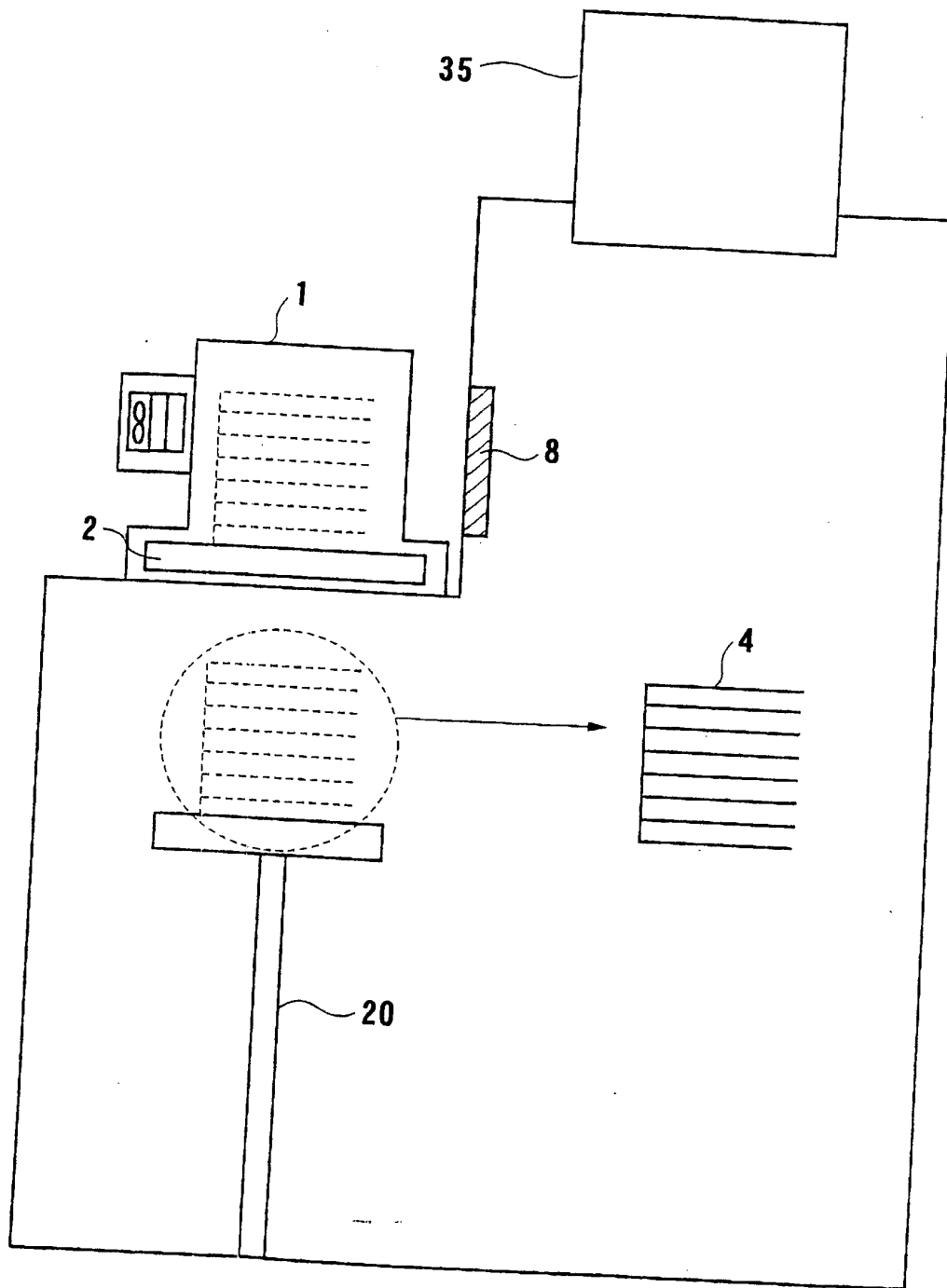


FIG. 71B



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FIG. 72

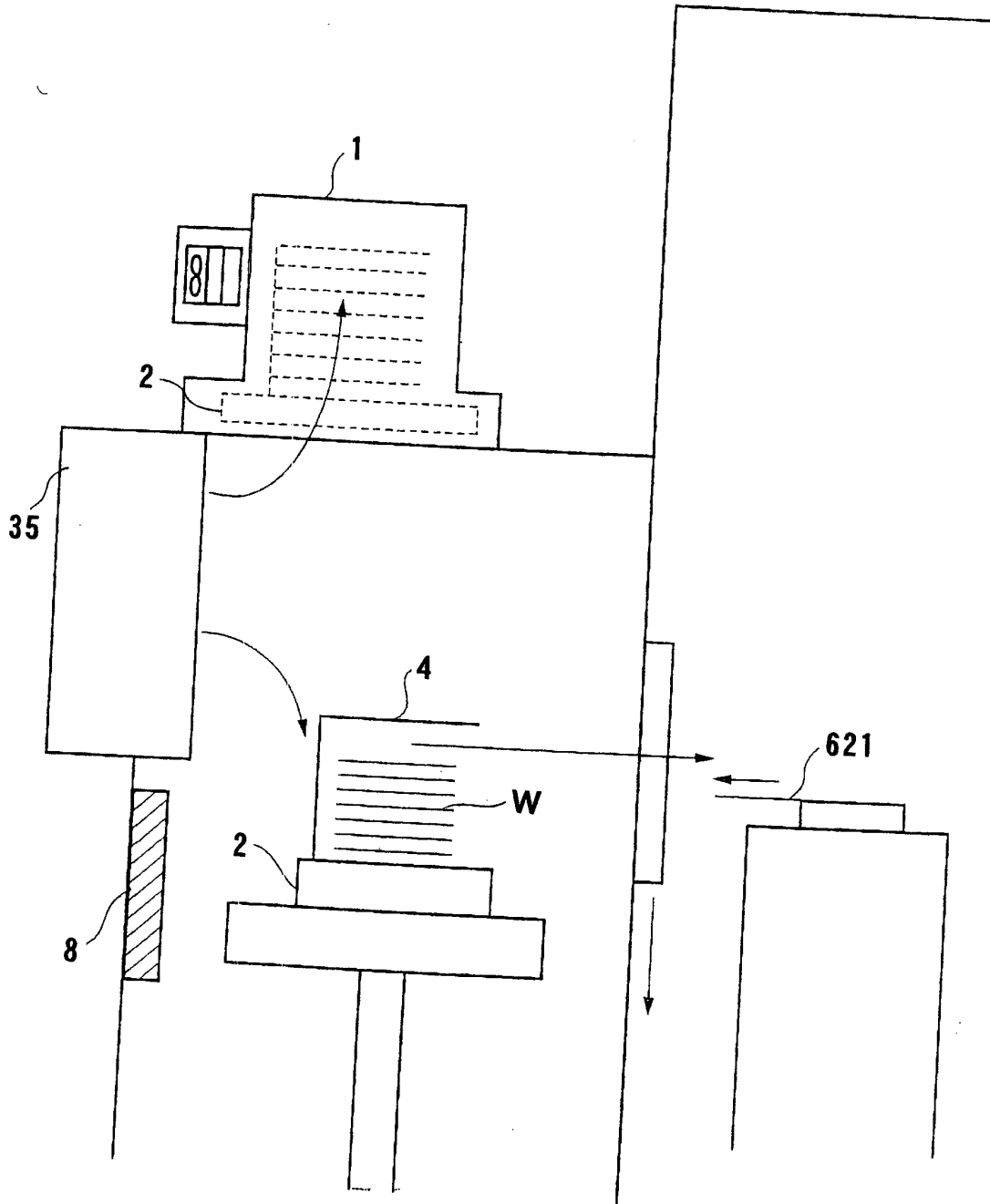


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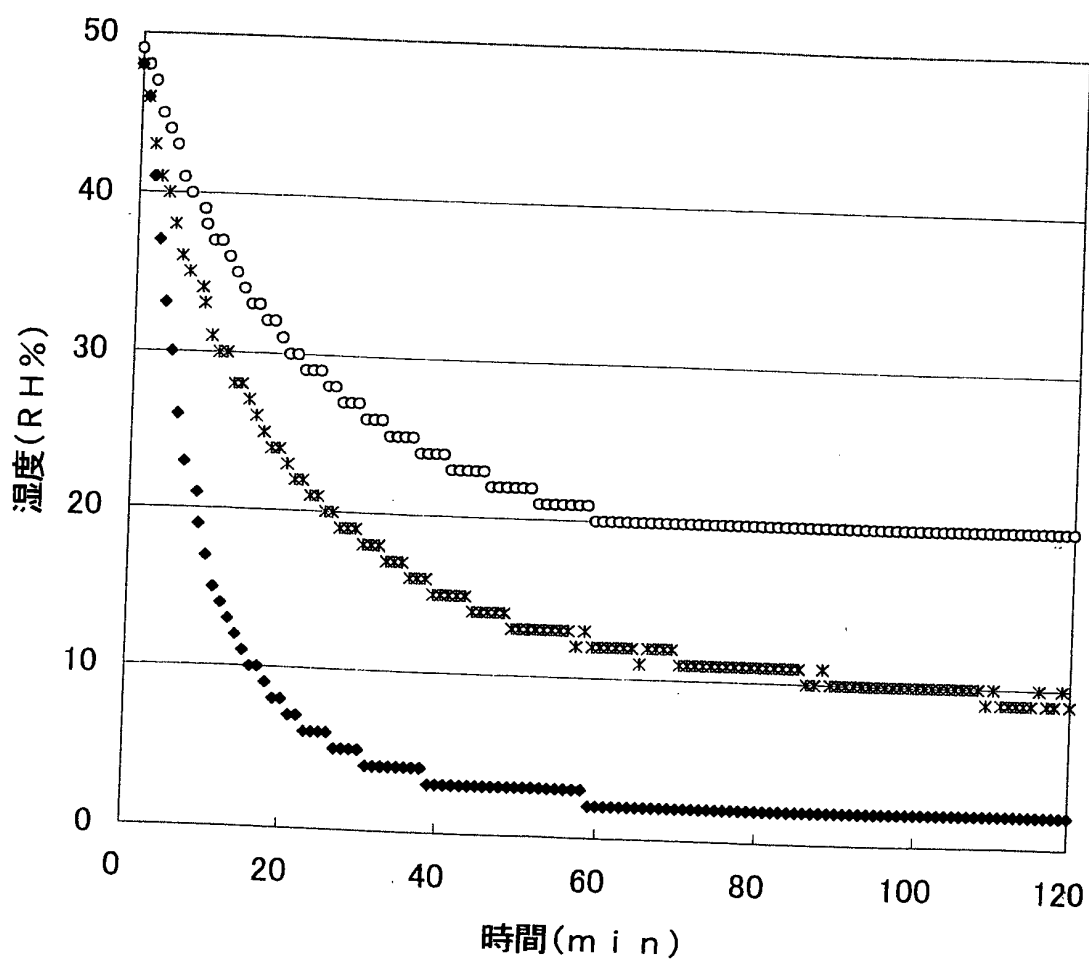
FIG. 73



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FIG. 74



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FIG. 75

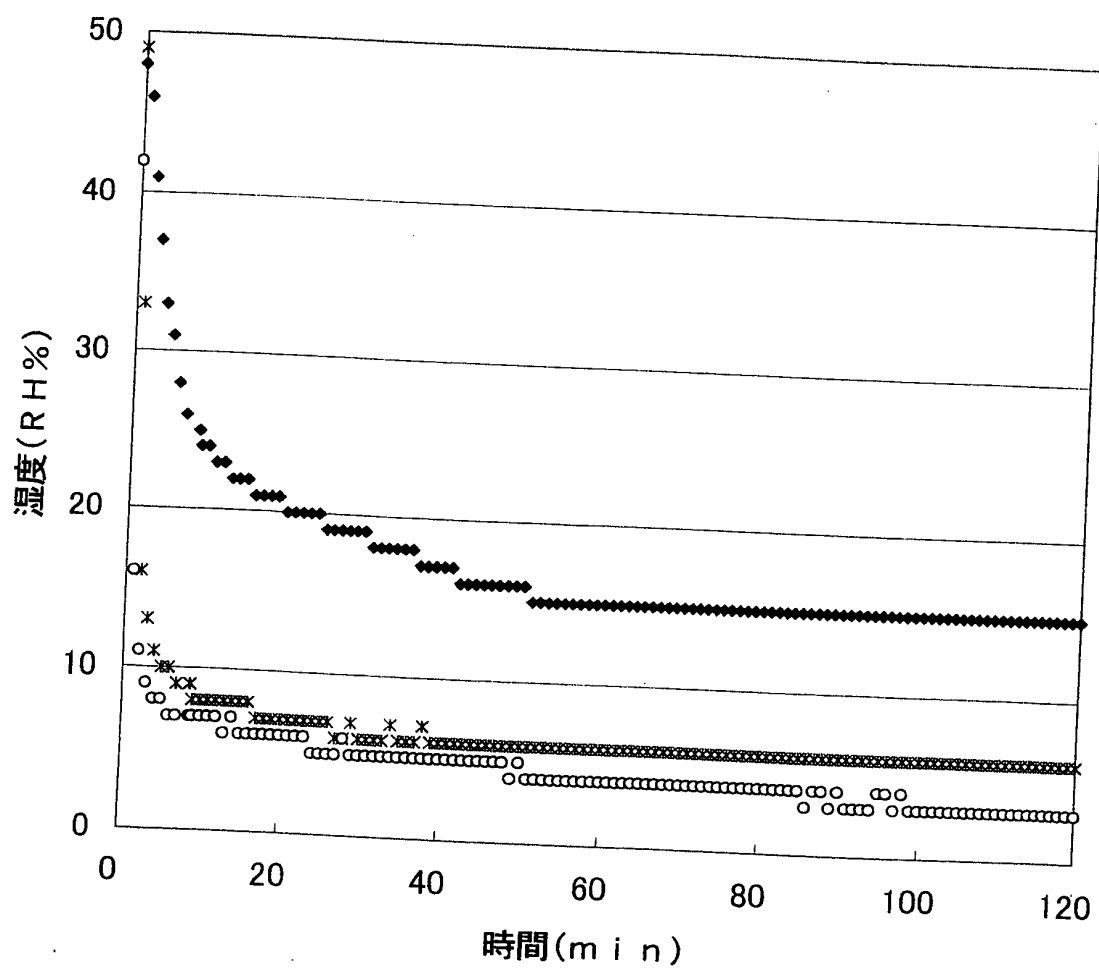
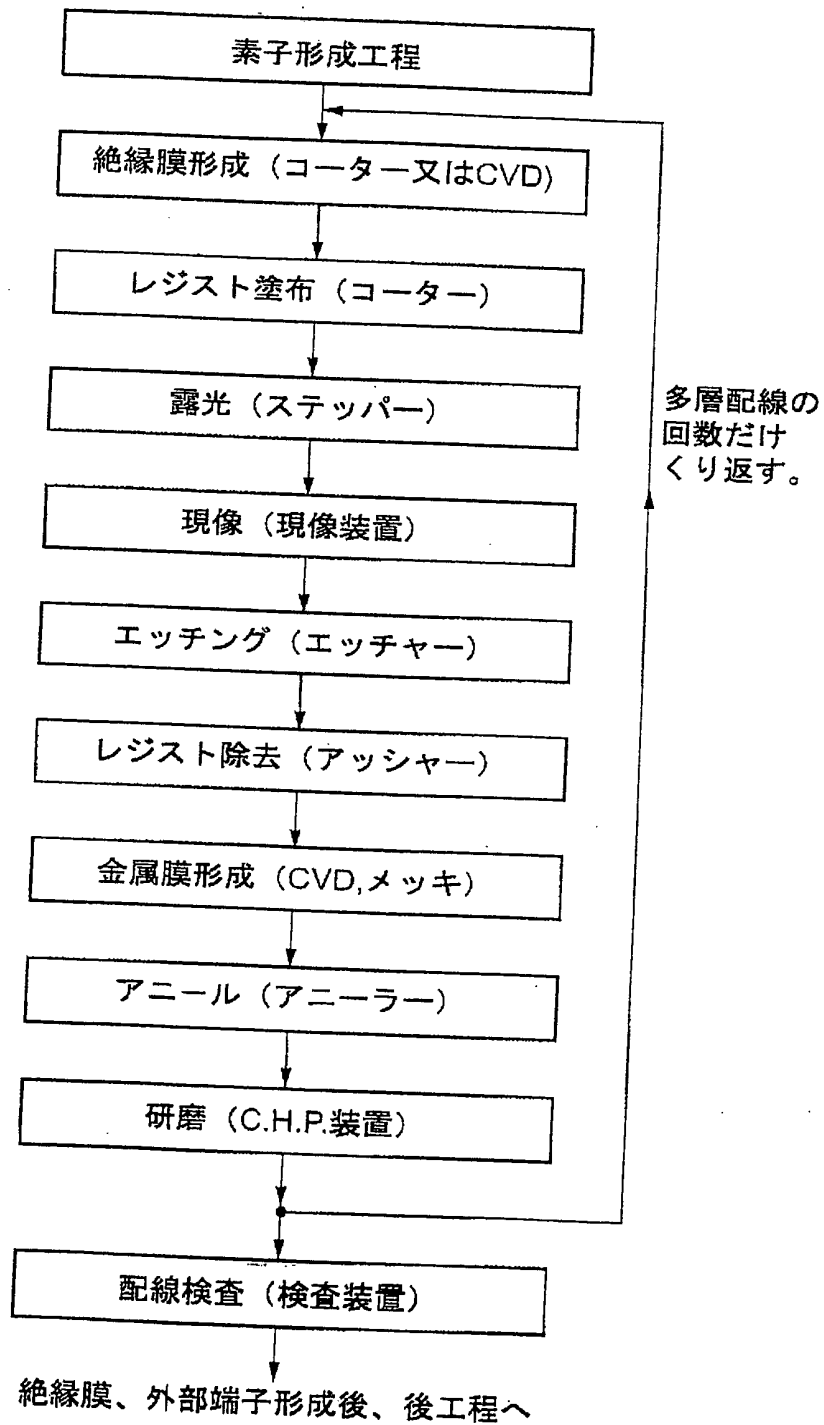


FIG. 76

## 半導体製造前工程



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FIG. 77A

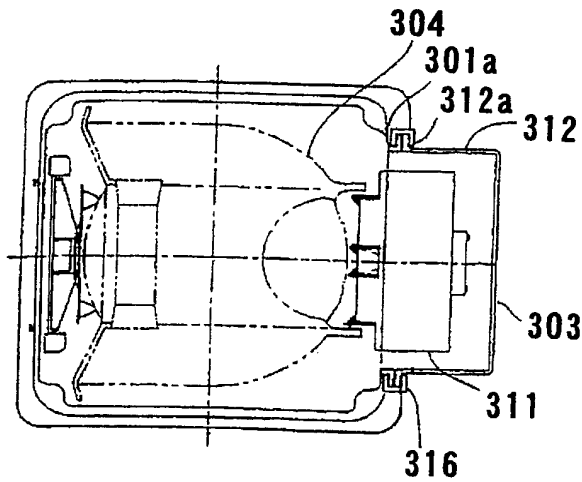


FIG. 77B

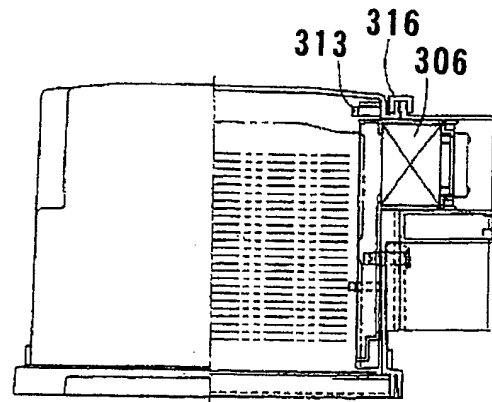


FIG. 77C

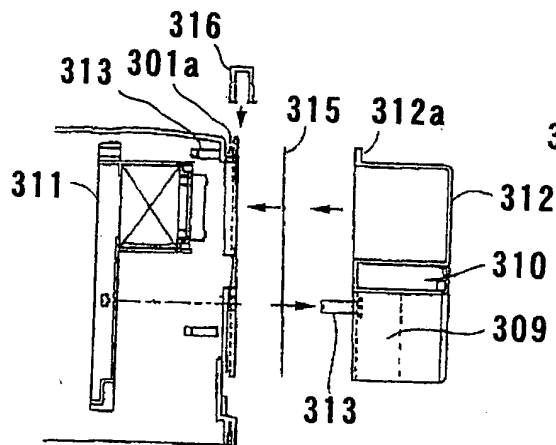
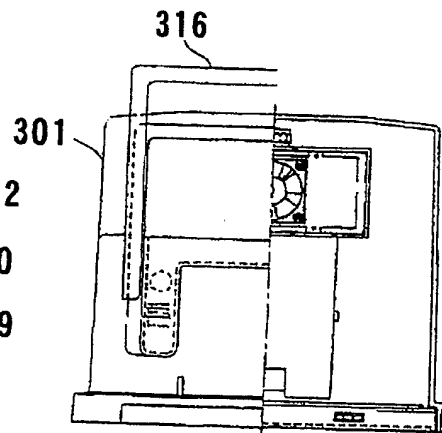


FIG. 77D



4000304-4000304

FIG. 78A

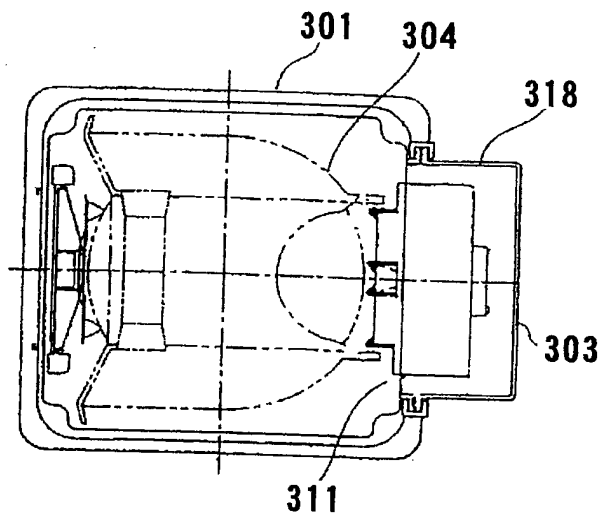


FIG. 78B

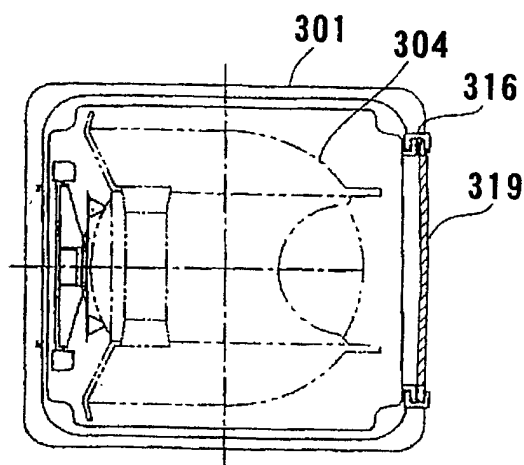


FIG. 78C

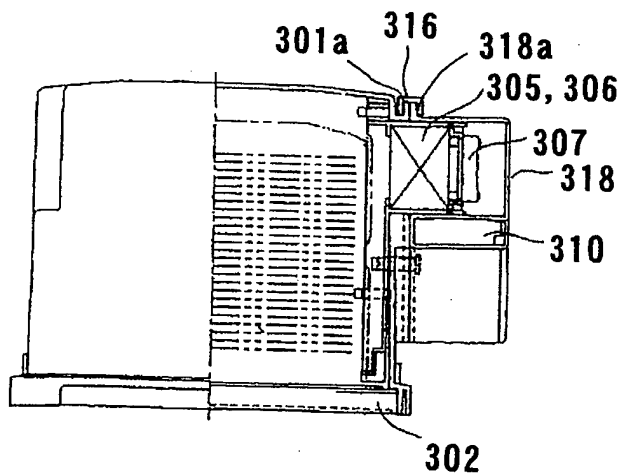
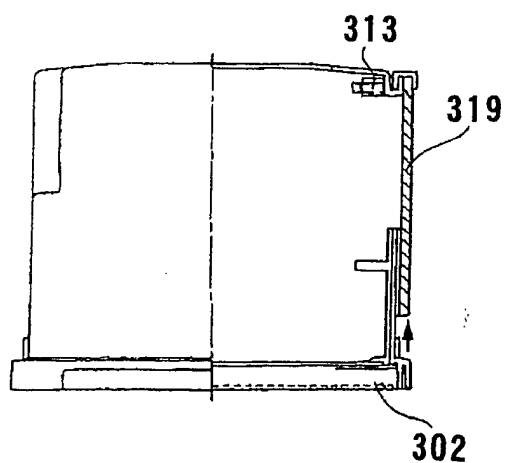
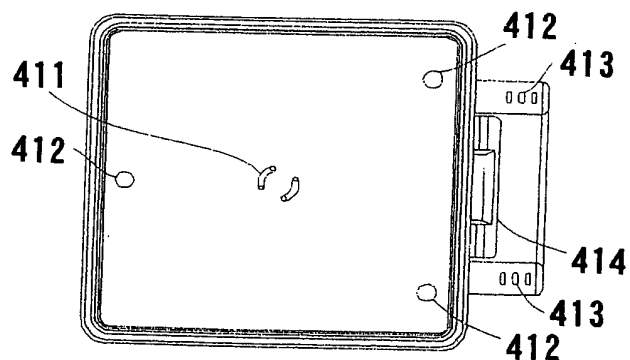


FIG. 78D

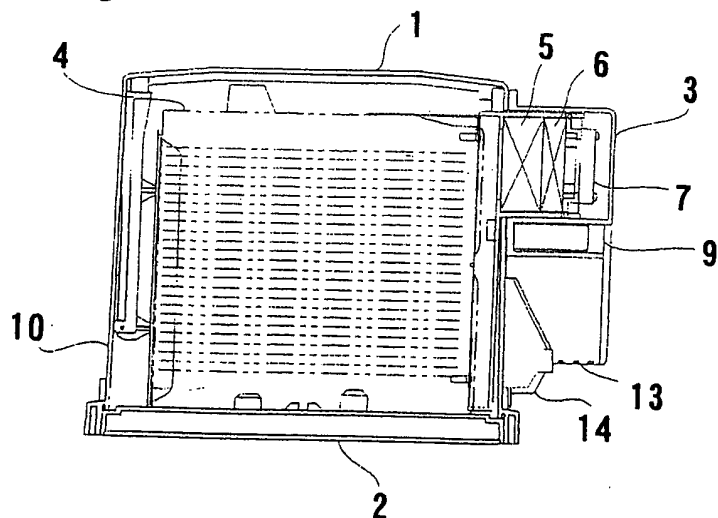


10000304 120001

**FIG. 79B**



**FIG. 79C**



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FIG. 80A

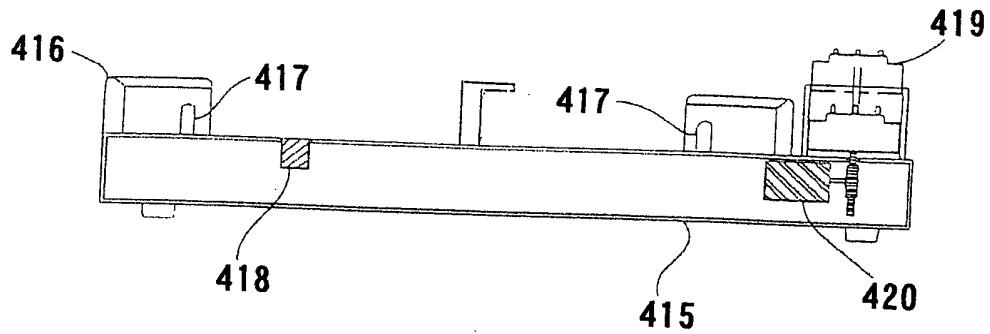
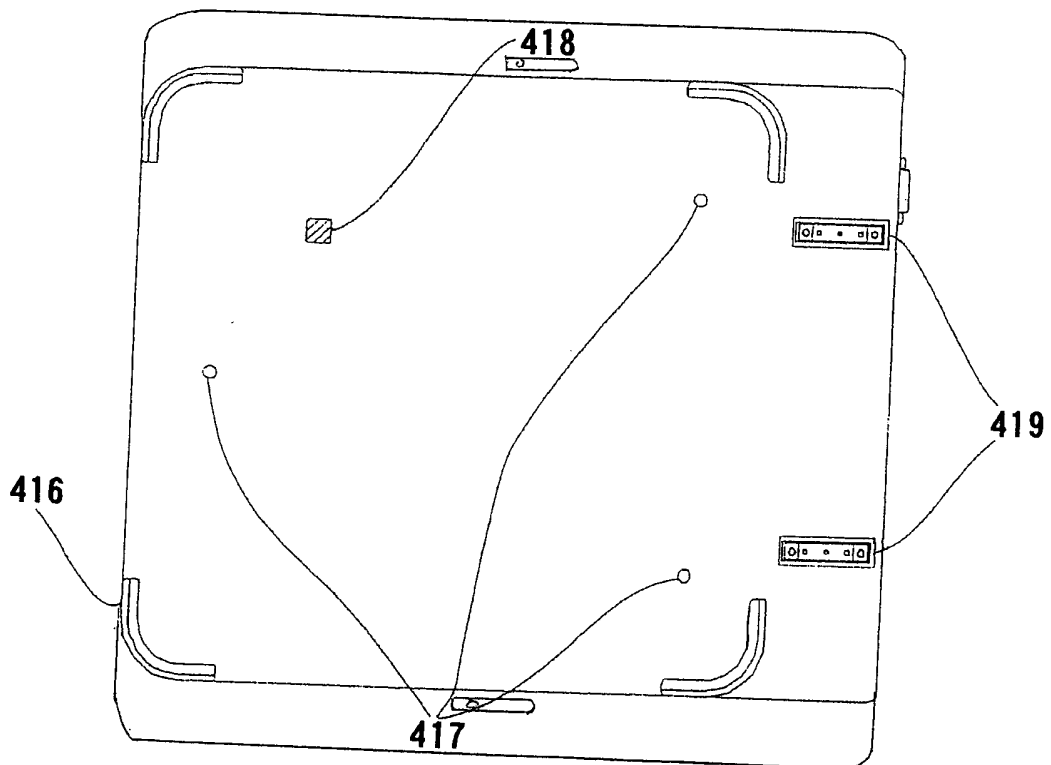


FIG. 80B





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FIG. 81A

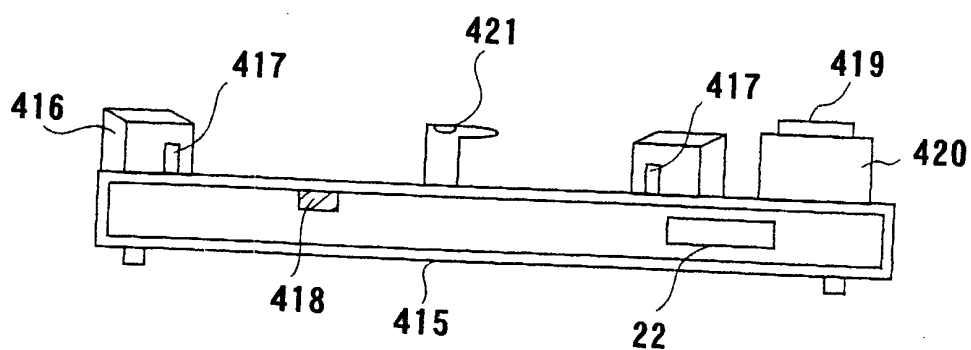
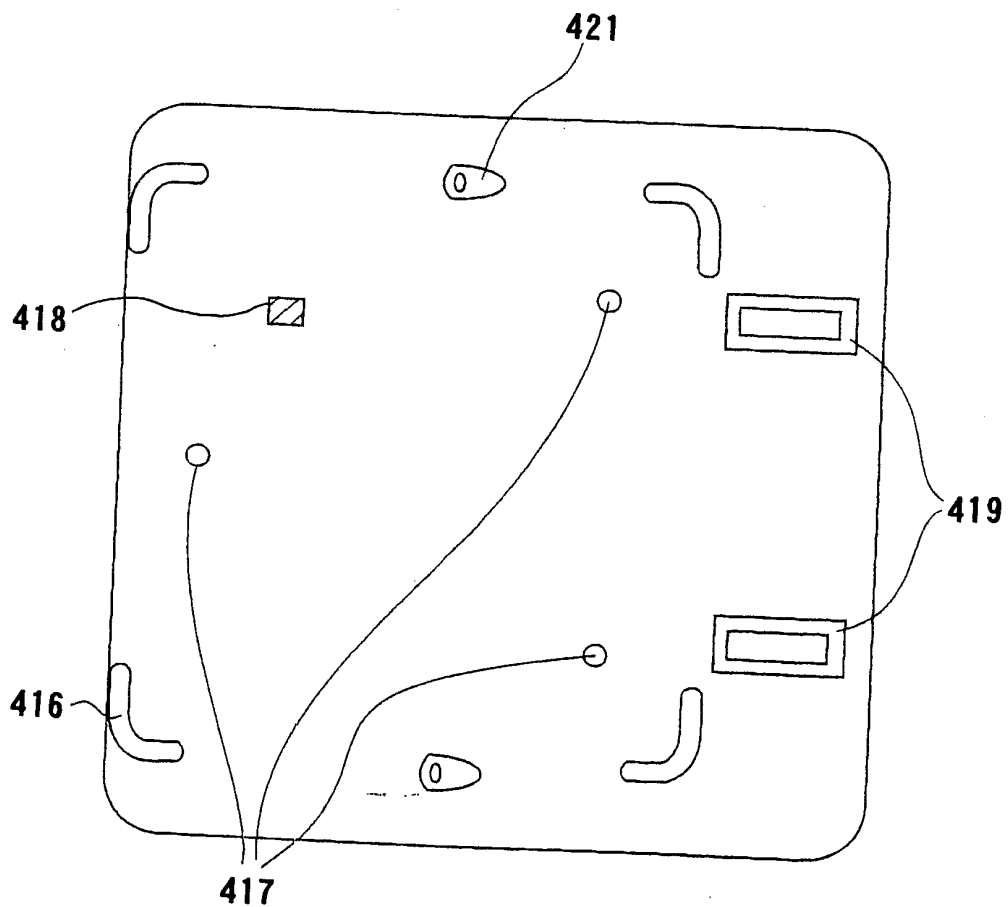


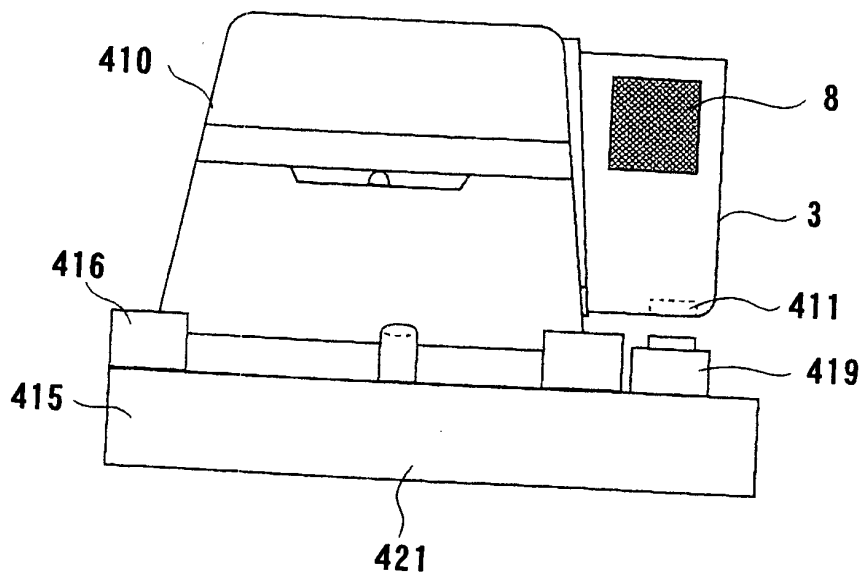
FIG. 81B





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*F / G. 83*

[illegible]

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FIG. 84

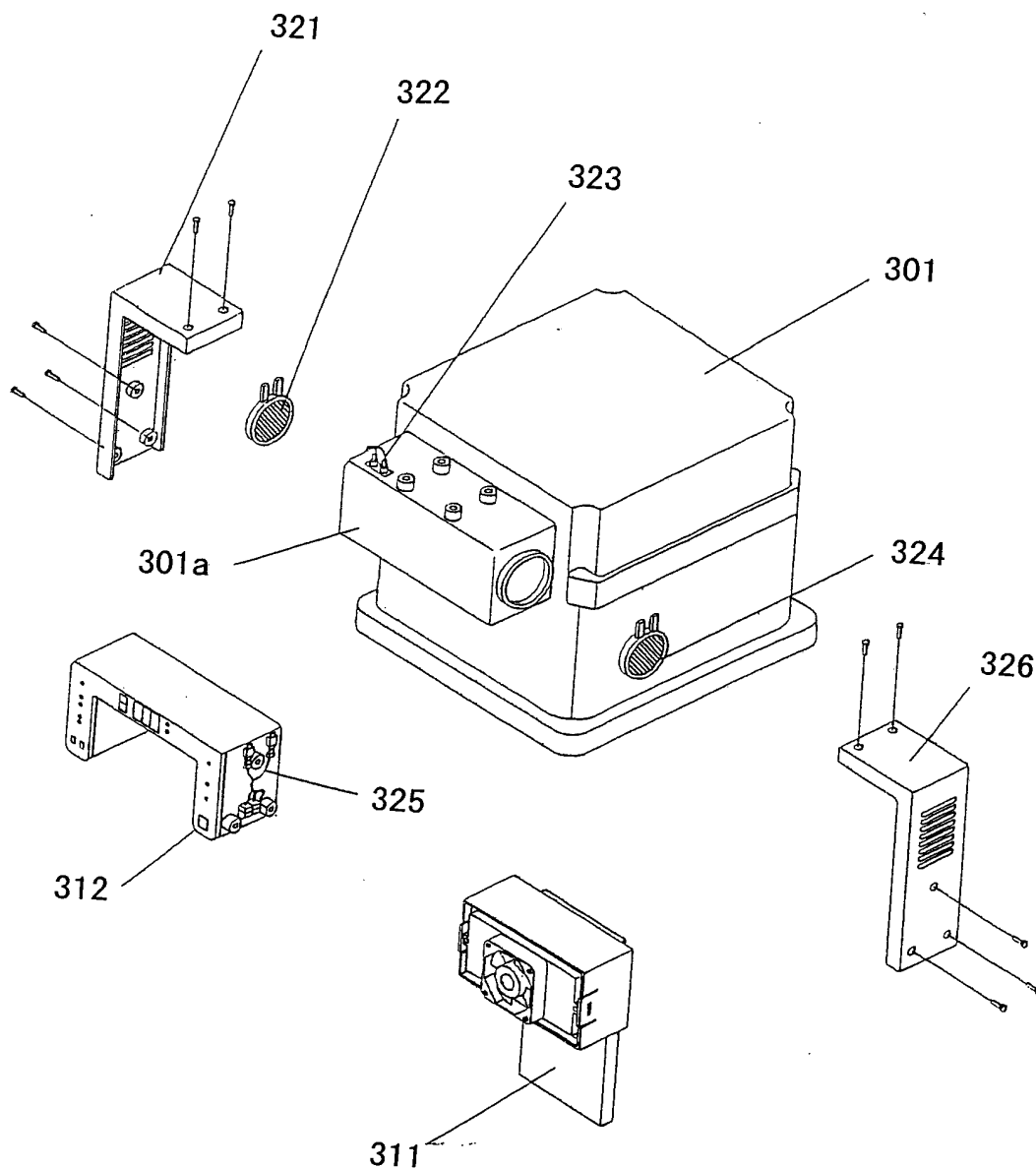
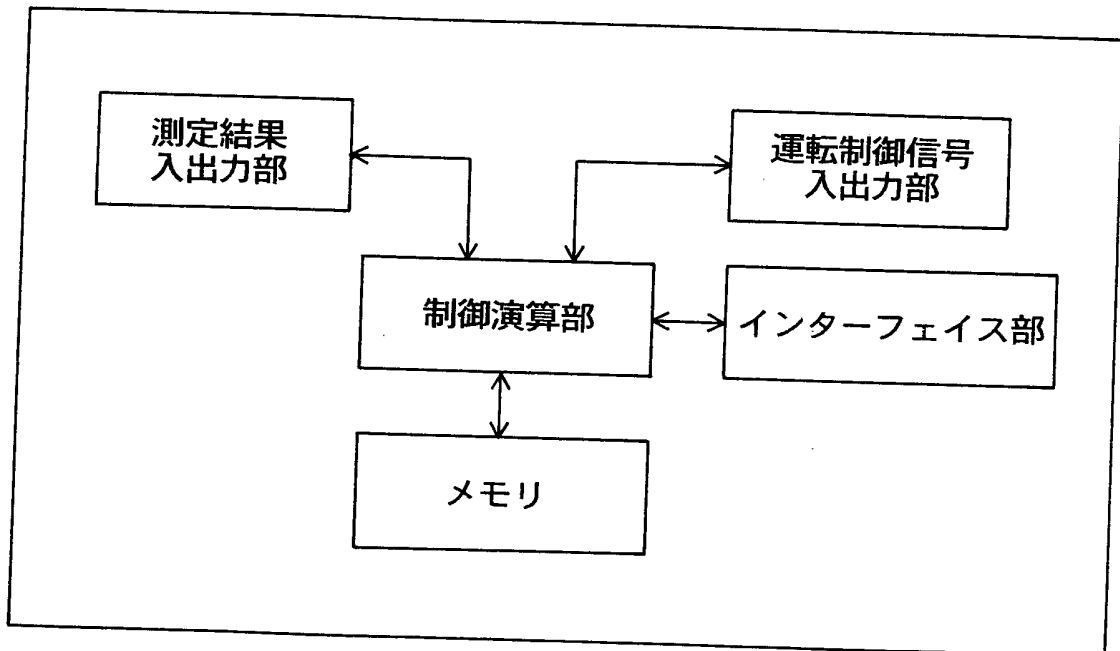
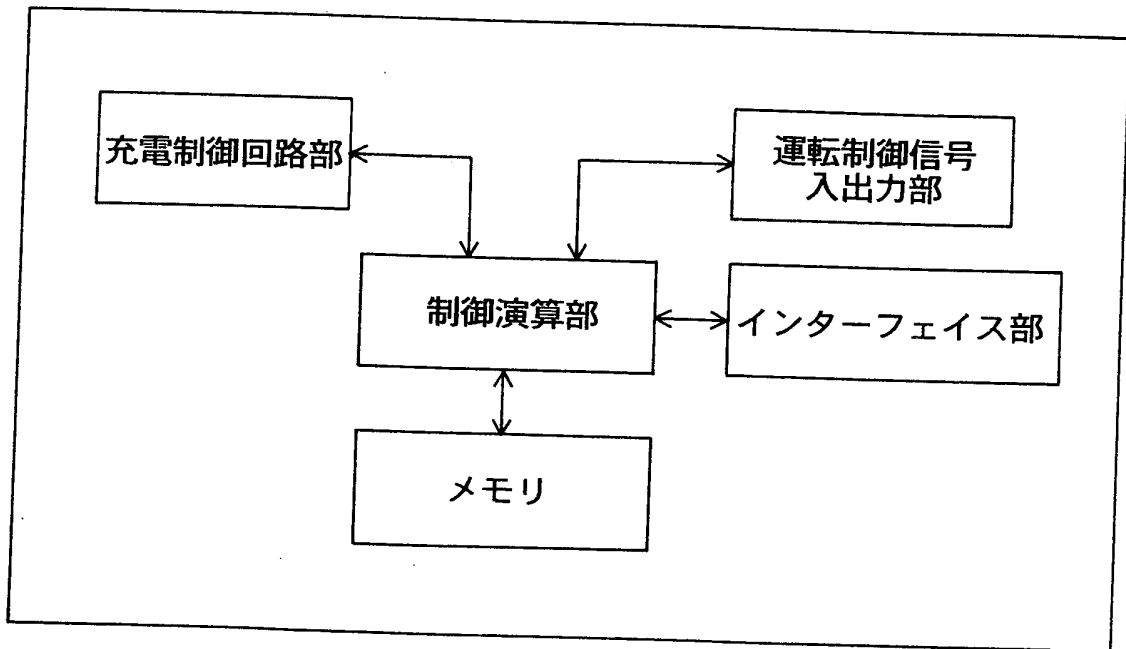


FIG. 85



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FIG. 86



10000304-120404

FIG. 87A

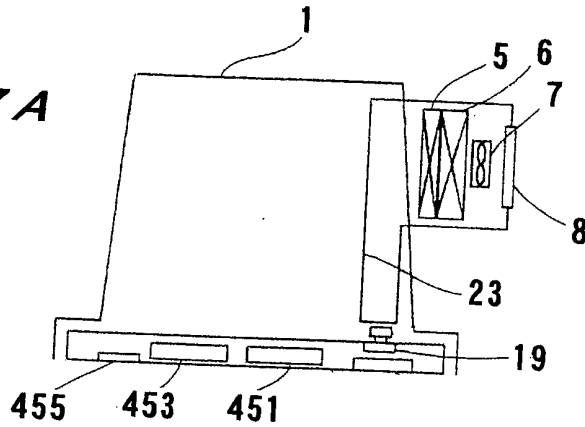


FIG. 87B

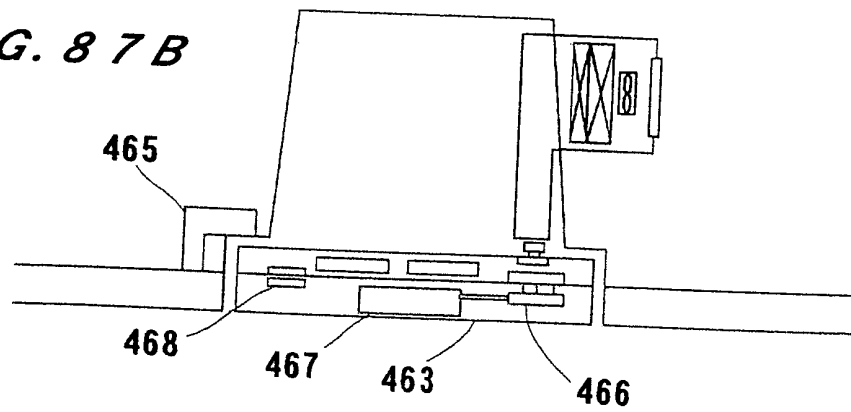
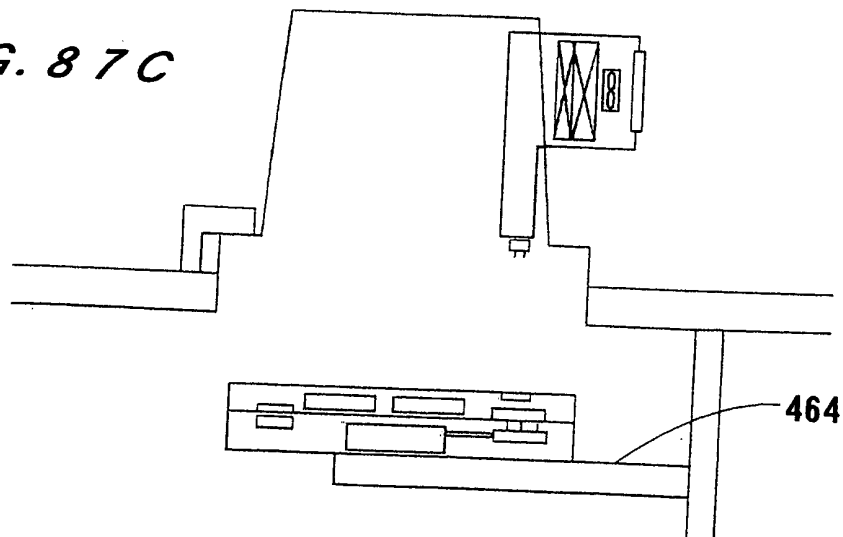
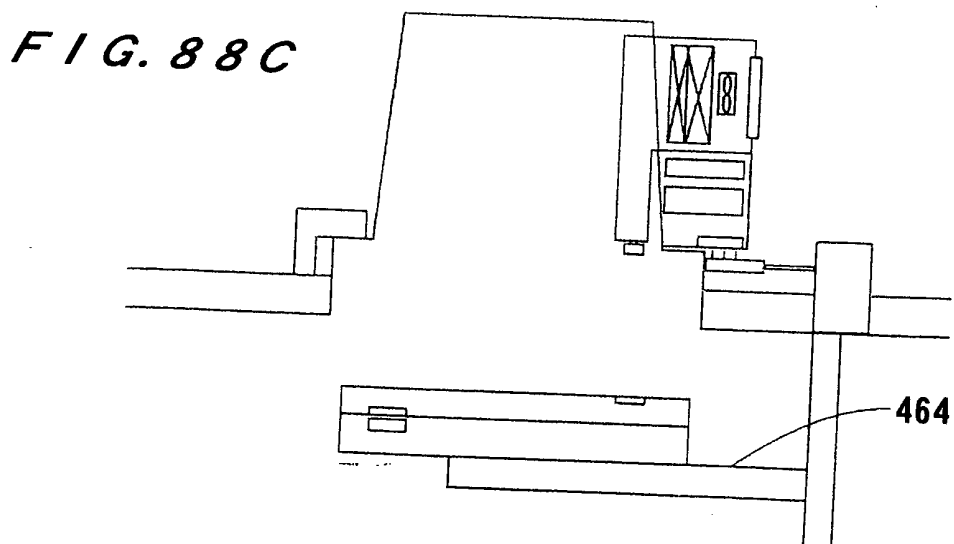
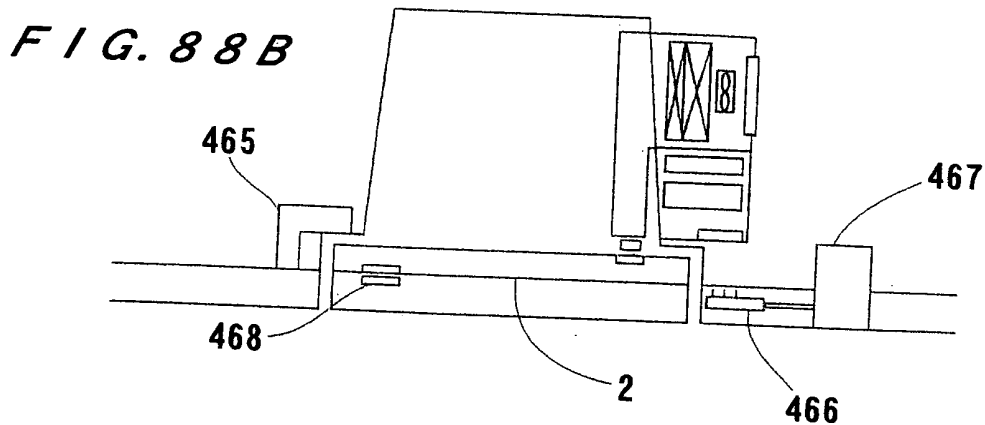
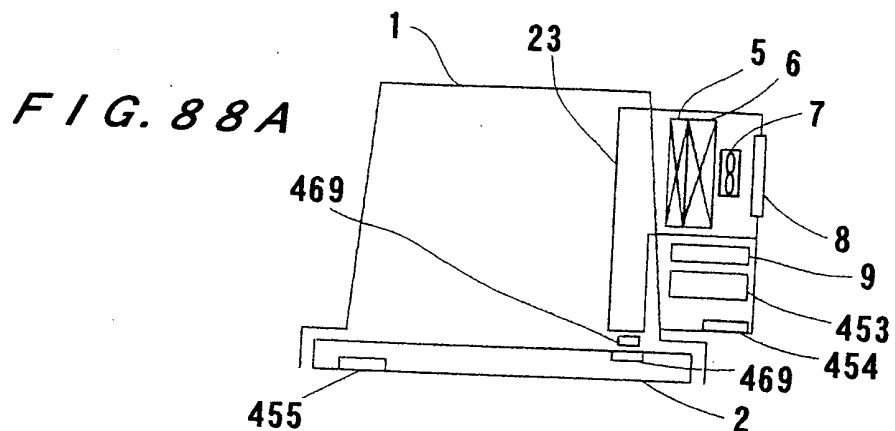


FIG. 87C



1000000-1000000



10000304-120404



FIG. 89A

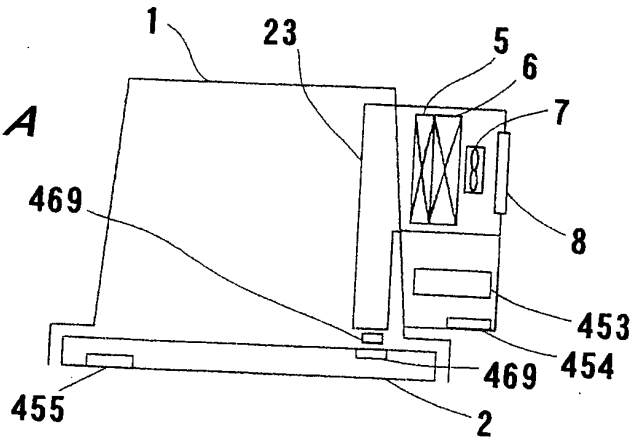


FIG. 89B

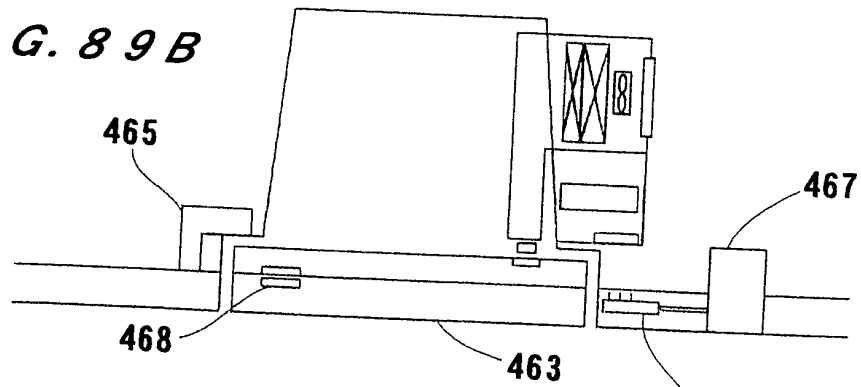
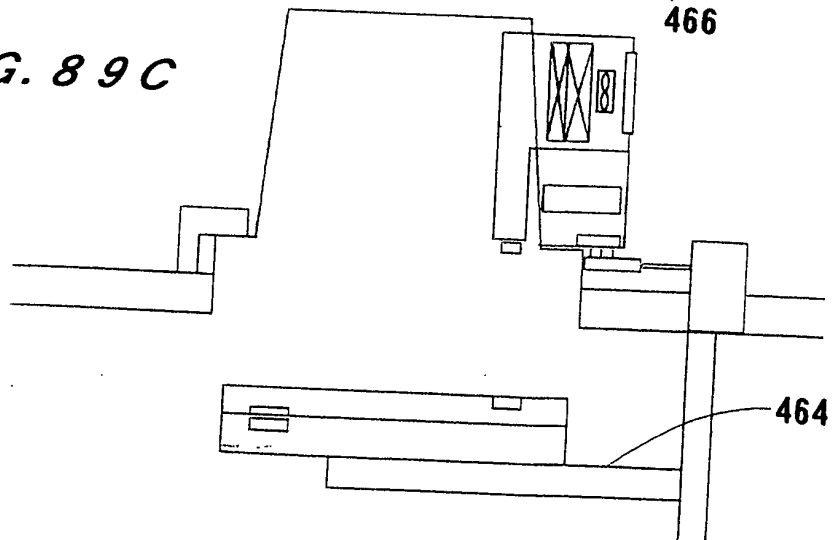


FIG. 89C



10000304-100404

FIG. 90A

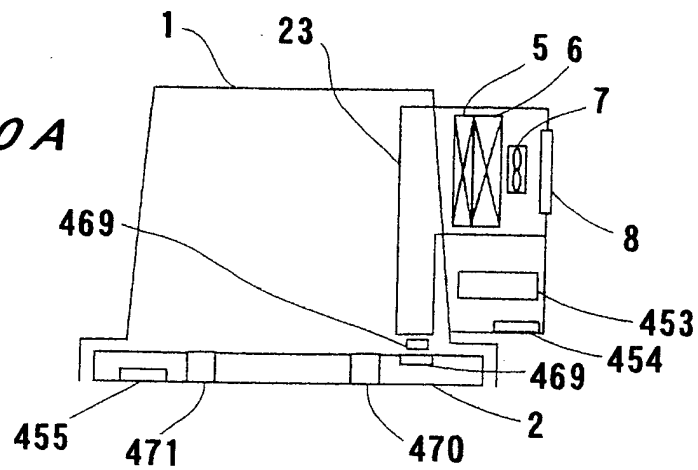


FIG. 90B

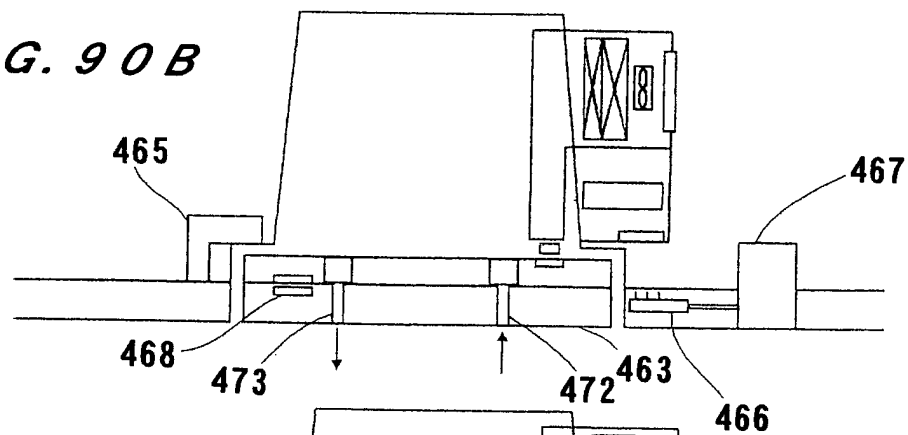
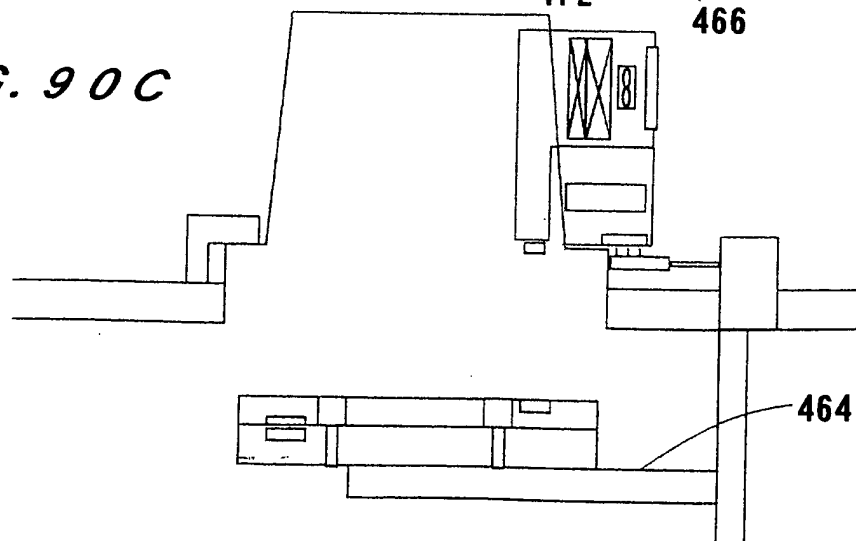
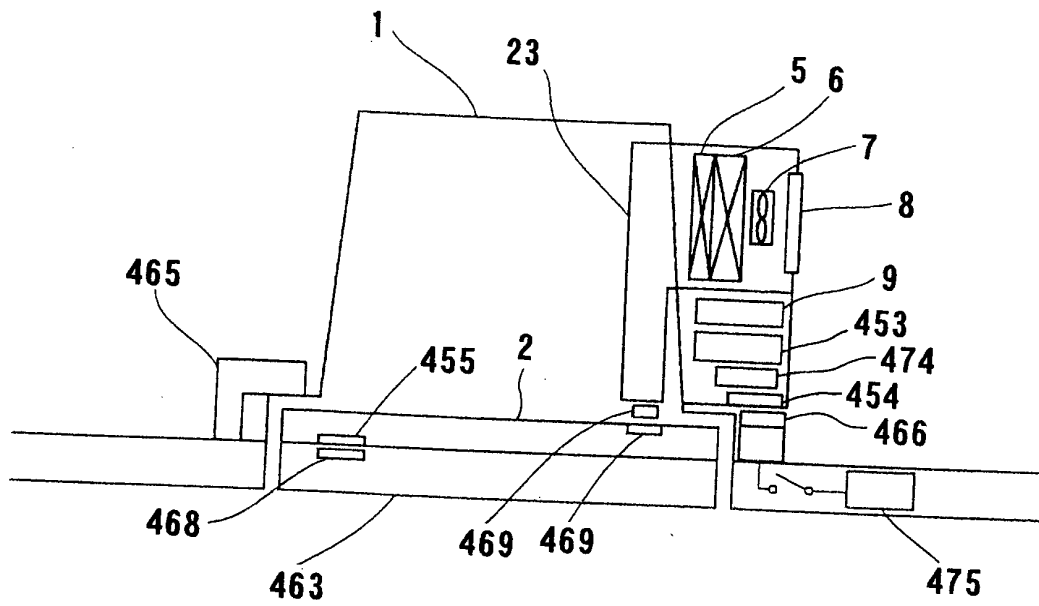


FIG. 90C



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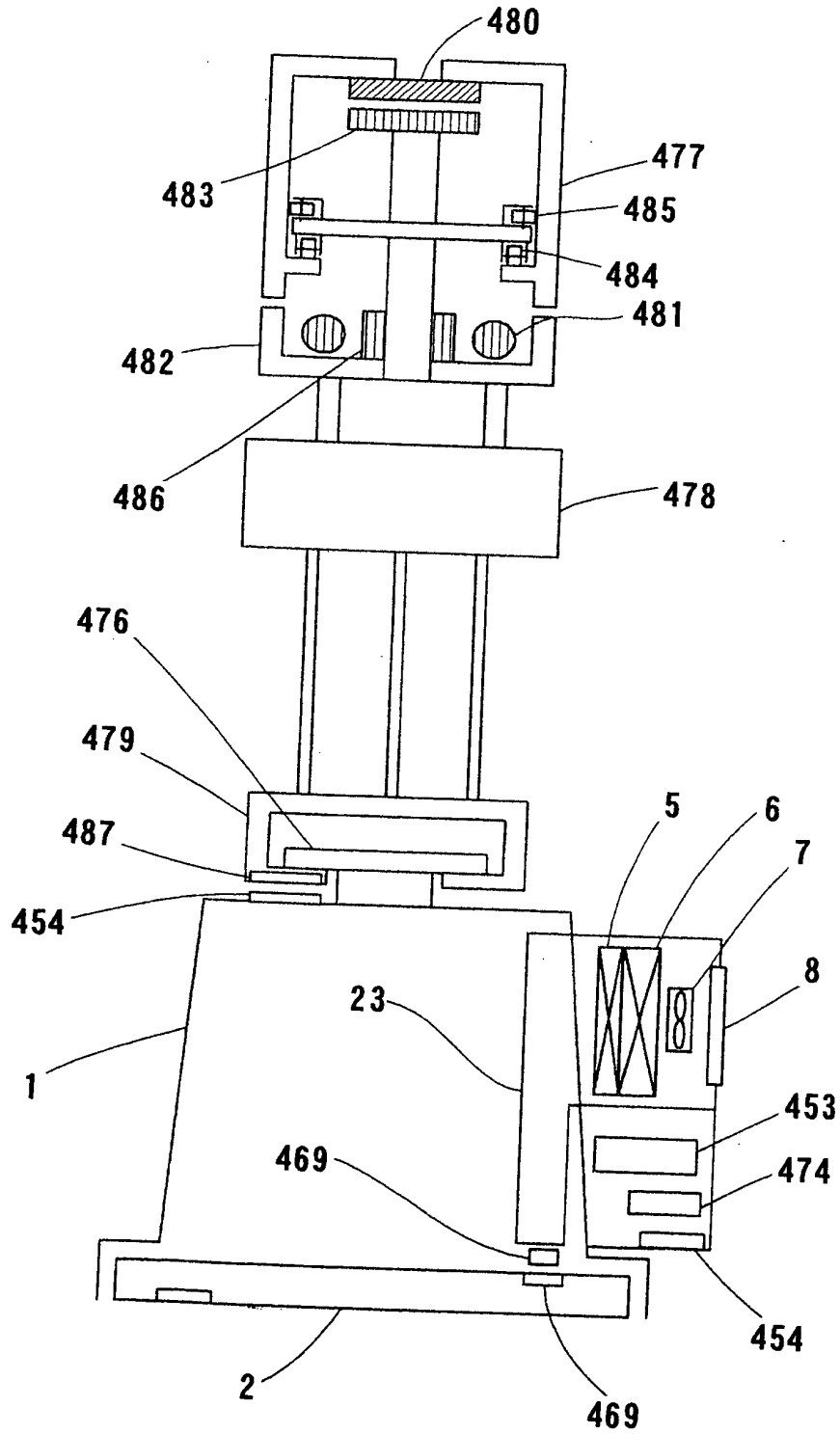
FIG. 91



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**FIG. 92**



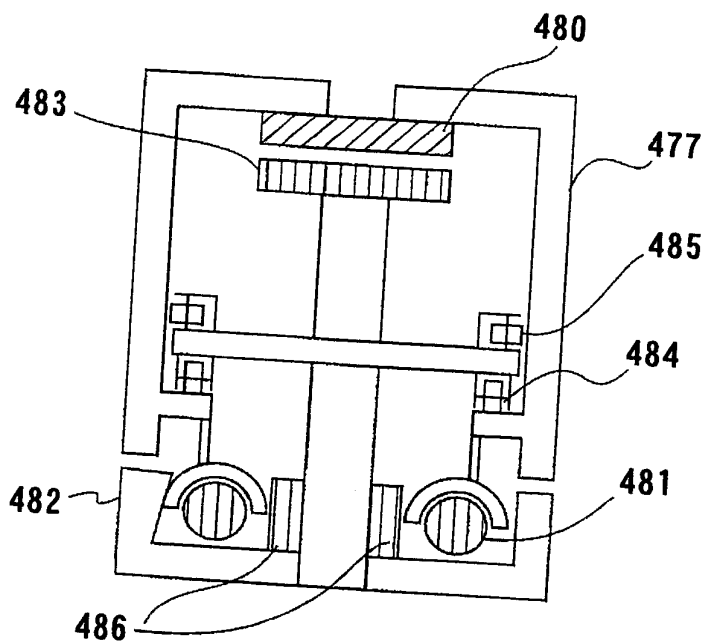
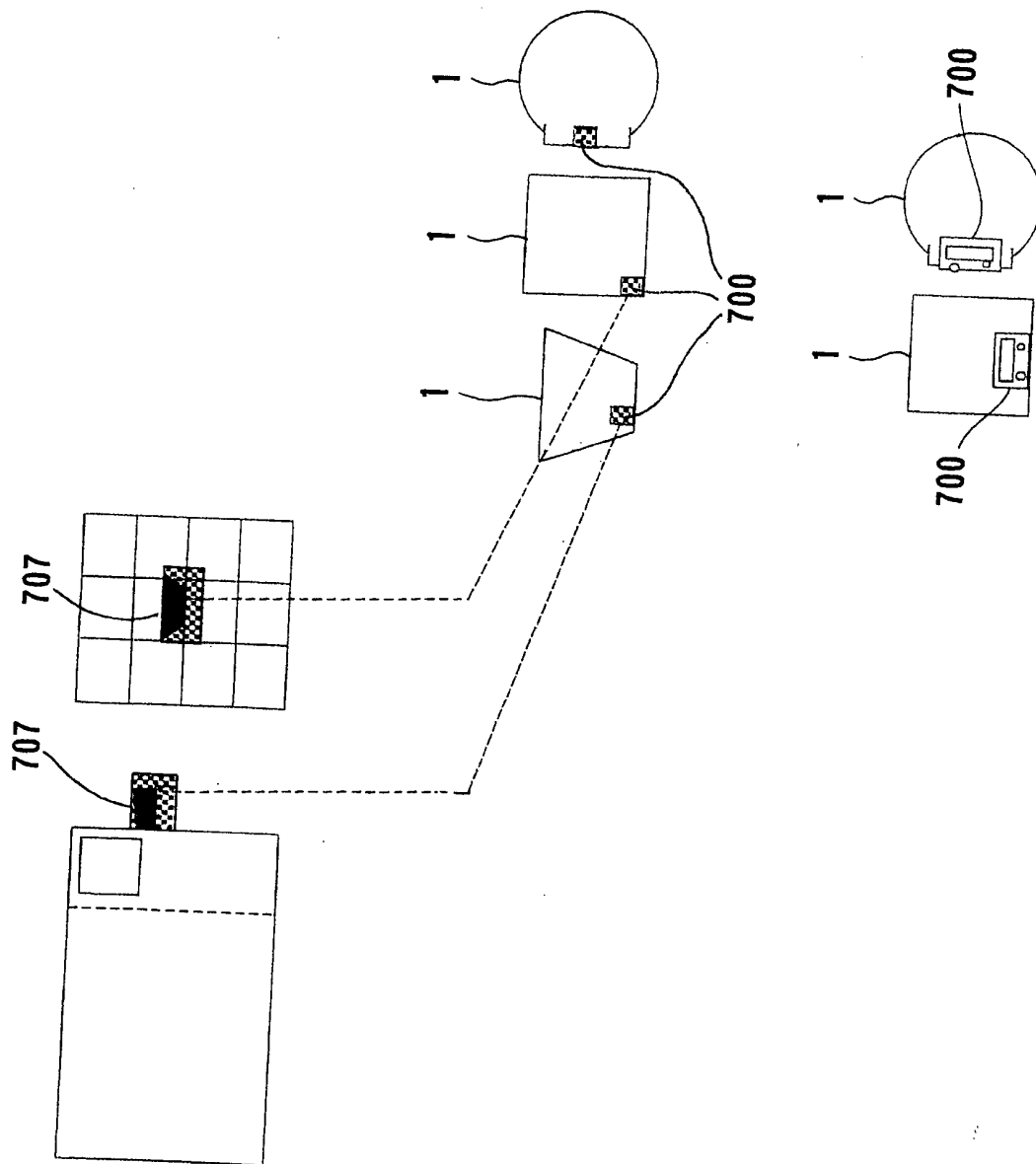




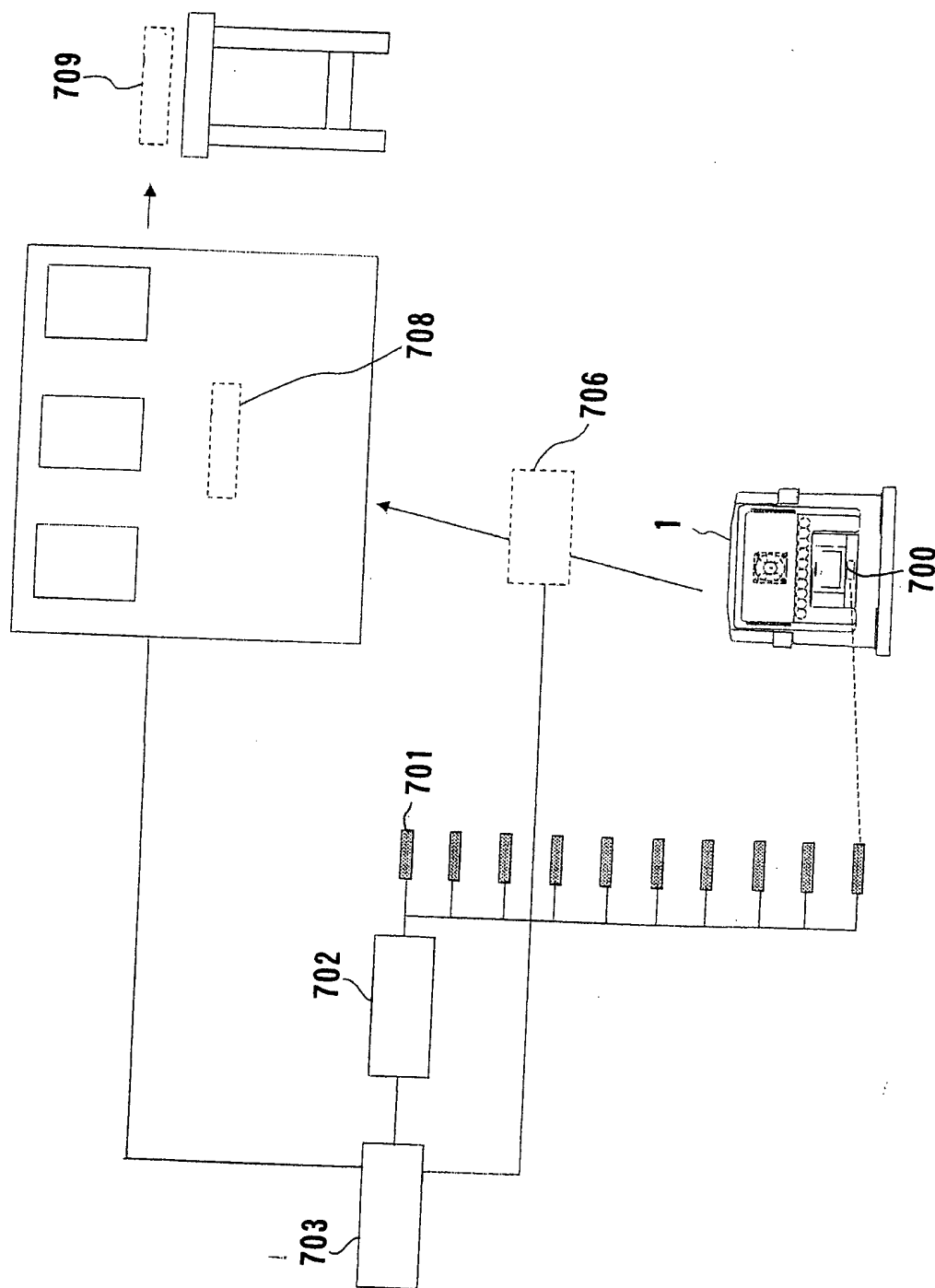
FIG. 95

FIG. 95



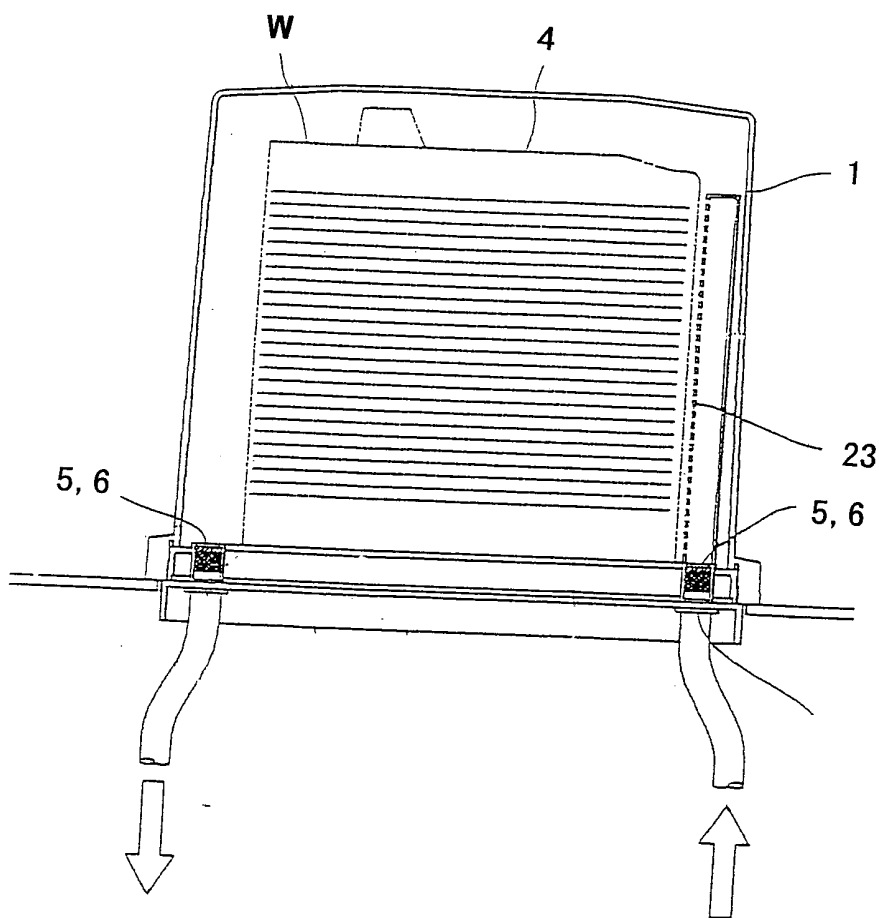
FOH027-40200007

FIG. 96



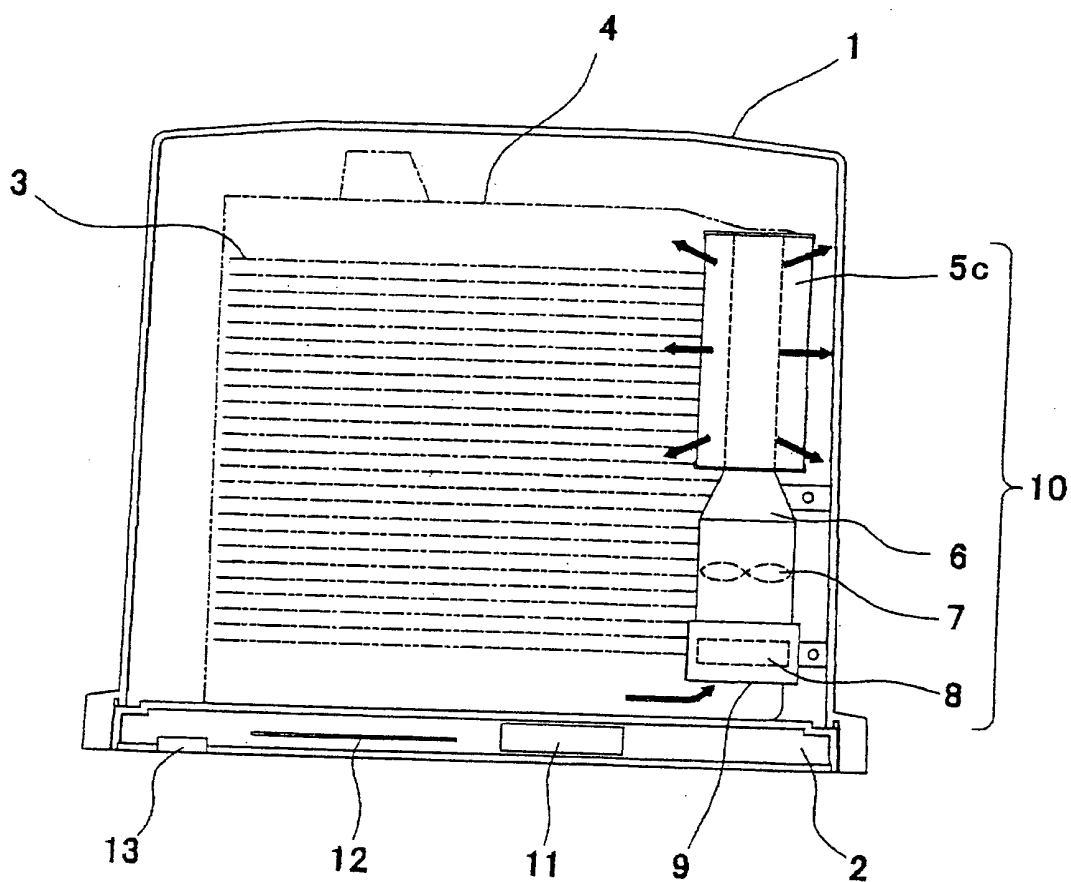


*FIG. 97*

[illegible]

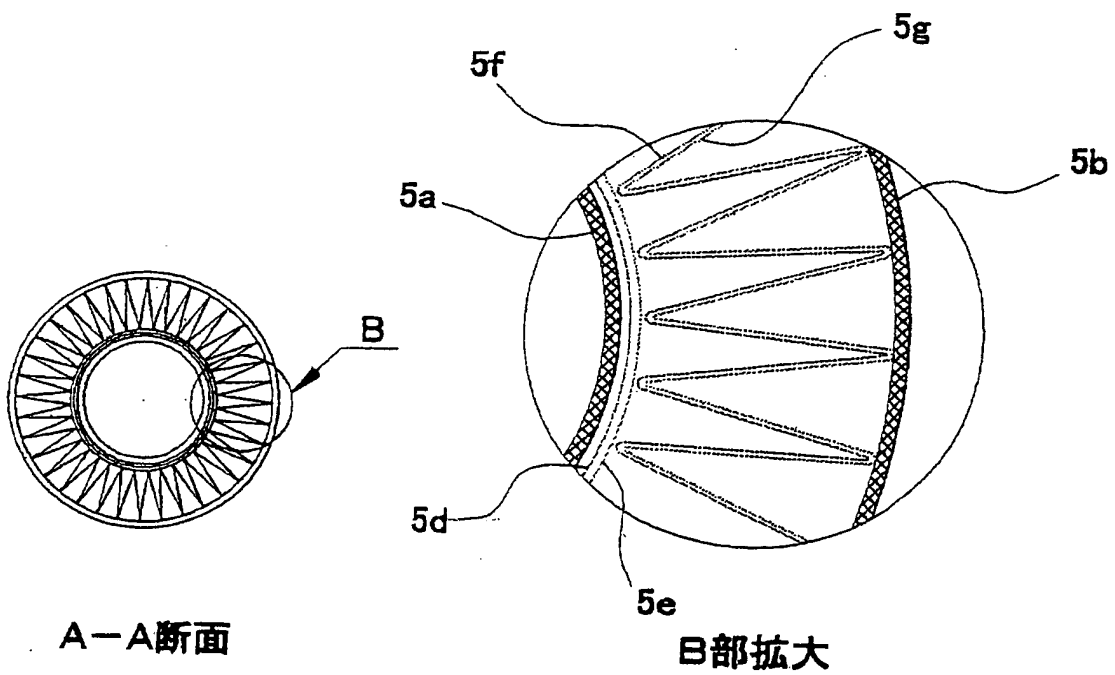
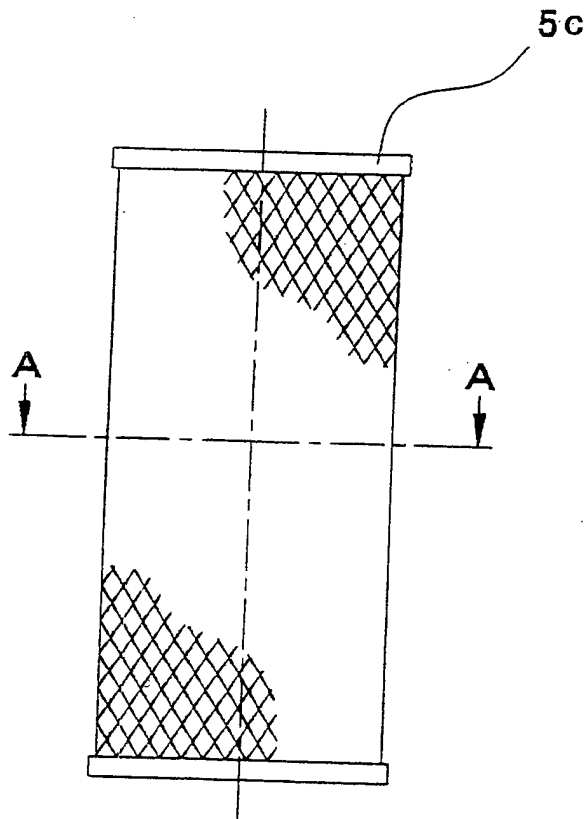
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FIG. 98



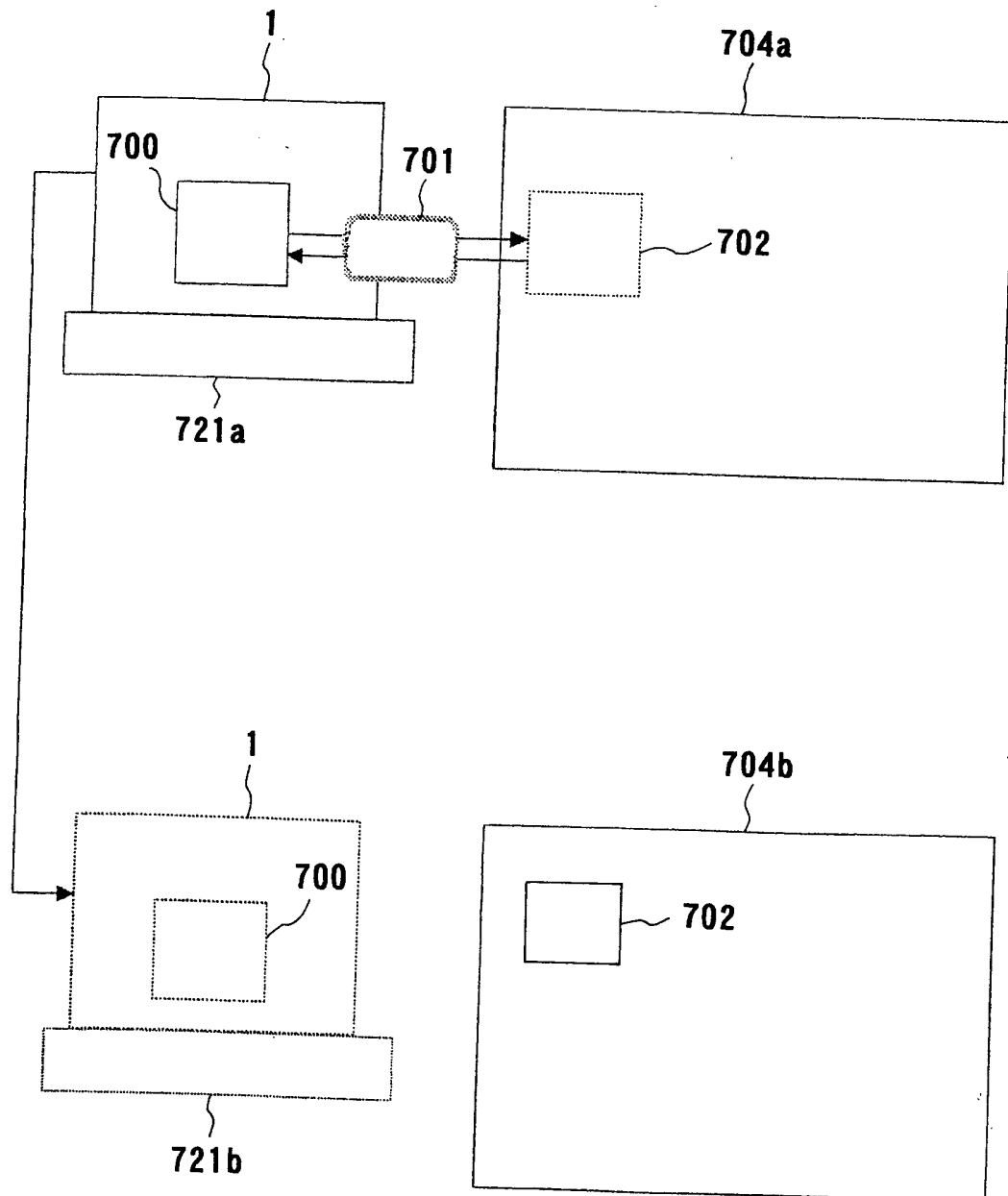
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FIG. 99



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FIG. 100



1000304-10404

FIG. 101

